ANNEXURE - I SYLLABUS FOR THE ENTRANCE EXAMINATIONS, 2016

(See Clause 9.5.1)

MATHEMATICS

UNIT I: ALGEBRA

SETS, RELATIONS AND FUNCTIONS

Sets and their Representations: Finite and Infinite sets; Empty set; Equal sets; Subsets; Power set; Universal set; Venn Diagrams; Complement of a set; Operations on Sets (Union, Intersection and Difference of Set); Applications of sets: Ordered Pairs, Cartesian Product of Two sets; Relations: Domain, Co-domain and Range: Functions: into, on to, one - one in to, one-one on to Functions; Constant Function; Identity Function; composition of Functions; Invertible Functions; Binary Operations.

Complex Numbers

Complex Numbers in the form a + ib; Real and Imaginary Parts of a complex Number; Complex Conjugate, Argand Diagram, Representation of Complex Number as a point in the plane; Modulus and Argument of a Complex Number; Algebra of Complex Numbers; Triangle Inequality; $|Z_1+Z_2| \le |Z_1|+|Z_2|$; $|Z_1.Z_2| = |Z_1||Z_2|$; Polar Representation of a Complex Number.

Quadratic Equations

Solution of a Quadratic Equation in the Complex Number System by (i) Factorization (ii) Using Formula; Relation between Roots and Coefficients; Nature of Roots; Formation of Quadratic Equations with given Roots; Equations Reducible to Quadratic Forms.

Sequences and Series

Sequence and Examples of Finite and Infinite Sequences; Arithmetic Progression (A..P): First Term, Common Difference, nth Term and sum of n terms of an A.P.; Arithmetic Mean (A.M); Insertion of Arithmetic Means between any Two given Numbers; Geometric Progression (G.P): first Term, Common Ratio and nth term, Sum to n Terms, Geometric Mean (G.M); Insertion of Geometric Means between any two given Numbers.

Permutations, Combinations, Binomial Theorem and Mathematical Induction

Fundamental Principle of Counting; The Factorial Notation; Permutation as an Arrangement; Meaning of P(n, r); Combination: Meaning of C(n,r); Applications of Permutations and Combinations. Statement of Binomial Theorem; Proof of Binomial Theorem for positive integral Exponent using Principle of Mathematical Induction and also by combinatorial Method; General and Middle Terms in Binomial Expansions; Properties of Binomial Coefficients; Binomial Theorem for any Index (without proof); Application of Binomial Theorem. The Principle of Mathematical Induction, simple Applications.

Matrices and Determinants

Concept of a Matrix; Types of Matrices; Equality of Matrices (only real entries may be considered): Operations of Addition, Scalar Multiplication and Multiplication of Matrices; Statement of Important Results on operations of Matrices and their Verifications by Numerical Problem only; Determinant of a Square Matrix; Minors and Cofactors; singular and non-singular Matrices; Applications of Determinants in (i) finding the Area of a Triangle (ii) solving a system of Linear Equations (Cramer's Rule); Transpose, Adjoint and Inverse of a Matrix; Consistency and Inconsistency of a system of Linear Equations; Solving

System of Linear Equations in Two or Three variables using Inverse of a Matrix (only up to 3X3 Determinants and Matrices should be considered).

Linear Inequations

Solutions of Linear Inequation in one variable and its Graphical Representation; solution of system of Linear Inequations in one variable; Graphical solutions of Linear inequations in two variables; solutions of system of Linear Inequations in two variables.

Mathematical Logic and Boolean Algebra

Statements; use of Venn Diagram in Logic; Negation Operation; Basic Logical Connectives and Compound Statements including their Negations.

UNIT II : TRIGONOMETRY

Trigonometric functions and Inverse Trigonometric functions

Degree measures and Radian measure of positive and negative angles; relation between degree measure and radian measure, definition of trigonometric functions with the help of a unit circle, periodic functions, concept of periodicity of trigonometric functions, value of trigonometric functions of x for x = 0, $\frac{\pi}{6}$, $\frac{\pi}{4}$, $\frac{\pi}{3}$, $\frac{\pi}{2}$, π , $\frac{3\pi}{2}$, 2π ; trigonometric functions of sum and difference of numbers.

$$Sin(x \pm y) = Sin x Cos y \pm Cos x Sin y ; Cos(x \pm y) = Cos x Cos y \mp Sin x Sin y ; Tan(x \pm y) = \frac{Tan x \pm Tan y}{1 \mp Tan x Tan y} ; Sin(2\pi \pm x) = \pm Sin x , Cos(2\pi \pm x) = Cos x ; Cos(-x) = Cos x , Sin(-x) = -Sin x ; Cos(\frac{\pi}{2} \pm x) = \pm Sin x$$
$$Sin(\frac{\pi}{2} \pm x) = Cos x ; Cos(\pi \pm x) = -Cos x , Sin(\pi \pm x) = \pm Sin x$$

Trigonometric functions of multiple and submultiples of numbers.

$$Sin 2 x = 2 Sin x Cos x;$$

$$Sin_3x = 3Sin_x - 4Sin_x^3$$
; $Cos_2x = Cos_x^2 - Sin_x^2 = 1 - 2Sin_x^2 = 2Cos_x^2 - 1$; $Cos_3x = 4Cos_x^3 - 3Cos_x$

$$Tan 3x = \frac{3\operatorname{Tan} x - \operatorname{Tan}^3 x}{1 - 3Tan^2 x}; Sin x + \operatorname{Sin} y = 2\operatorname{Sin}\left(\frac{x + y}{2}\right)\operatorname{Cos}\left(\frac{x - y}{2}\right); Cos x + \operatorname{Cos} y = 2\operatorname{Cos}\left(\frac{x + y}{2}\right)\operatorname{Cos}\left(\frac{x - y}{2}\right)$$
$$Sin x - \operatorname{Sin} y = 2\operatorname{Cos}\left(\frac{x + y}{2}\right)\operatorname{Sin}\left(\frac{x - y}{2}\right); Cos x - \operatorname{Cos} y = -2\operatorname{Sin}\left(\frac{x + y}{2}\right)\operatorname{Sin}\left(\frac{x - y}{2}\right)$$

Conditional identities for the angles of a triangle, solution of trigonometric equations of the type Sin x = Sin a; Cos x = Cos a; Tan x = Tan a and equations reducible to these forms. Inverse Trigonometric functions:

(i) $\sin^{-1}(\sin x) = x$ and other similar formula (ii) $\sin^{-1}(\frac{1}{x}) = Co \sec^{-1} x$ and other similar formula.

$$Sin^{-1}(-x) = -Sin^{-1}x , Tan^{-1}(-x) = -Tan^{-1}x ; Co \sec^{-1}(-x) = -Co \sec^{-1}x , Cos^{-1}(-x) = \pi - Cos^{-1}(x) ;$$

Sec^{-1}(-x) = \pi - Sec^{-1}(x) , Cot^{-1}(-x) = \pi - Cot^{-1}(x)

$$Sin^{-1}x + Cos^{-1}x = \frac{\pi}{2}, Tan^{-1}x + Cot^{-1}x = \frac{\pi}{2}; Cosec^{-1}(x) + Sec^{-1}(x) = \frac{\pi}{2}; Tan^{-1}x - Tan^{-1}y = Tan^{-1}\left(\frac{x-y}{1+xy}\right), xy > -1$$
$$Tan^{-1}x + Tan^{-1}y = Tan^{-1}\left(\frac{x+y}{1-xy}\right); xy < 1; 2Tan^{-1}x = Sin^{-1}\left(\frac{2x}{1+x^2}\right) = Cos^{-1}\left(\frac{1-x^2}{1+x^2}\right) = Tan^{-1}\left(\frac{2x}{1-x^2}\right), |x| < 1$$

Simple problems

Graph of the following trigonometric functions;

y = Sin x; y = Cos x; y = Tan x; y = a Sin x; y = a Cos x, y = a Sin bx; y = a Cos bx;

UNIT III: GEOMETRY

Cartesian System of Rectangular Co ordinates

Cartesian system of co ordinates in a plane, Distance formula, Centroid and incentre, Area of a triangle, condition for the collinearity of three points in a plane, Slope of line, parallel and perpendicular lines, intercepts of a line on the co ordinate axes, Locus and its equation.

Lines and Family of lines

Various forms of equations of a line parallel to axes, slope-intercept form, The Slope point form, Intercept form, Normal form, General form, Intersection of lines. Equation of bisectors of angle between two lines, Angles between two lines, condition for concurrency of three lines, Distance of a point from a line, Equations of family of lines through the intersection of two lines.

Circles and Family of circles

Standard form of the equation of a circle General form of the equation of a circle, its radius and center, Equation of the circle in the parametric form.

Conic sections

Sections of a cone. Equations of conic sections [Parabola, Ellipse and Hyperbola] in standard form.

Vectors

Vectors and scalars, Magnitude and Direction of a vector, Types of vectors (Equal vectors, unit vector, Zero vector). Position vector of a point, Localized and free vectors, parallel and collinear vectors, Negative of a vector, components of a vector, Addition of vectors, multiplication of a vector by a scalar, position vector of point dividing a line segment in a given ratio, Application of vectors in geometry. Scalar product of two vectors, projection of a vector on a line, vector product of two vectors.

Three Dimensional Geometry

Coordinate axes and coordinate planes in three dimensional space, coordinate of a point in space, distance between two points, section formula, direction cosines, and direction ratios of a line joining two points, projection of the join of two points on a given line, Angle between two lines whose direction ratios are given, Cartesian and vector equation of a line through (i) a point and parallel to a given vector (ii) through two points, Collinearity of three points, coplanar and skew lines, Shortest distance between two lines, Condition for the intersection of two lines, Carterian and vector equation of a plane (i) When the normal vector and the distance of the plane from the origin is given (ii) passing though a point and perpendicular to a given vector (iii) Passing through a point and parallel to two given lines through the intersection of two other planes (iv) containing two lines (v) passing through three points, Angle between (i) two lines (ii) two planes (iii) a line and a plane, Condition of coplanarity of two lines in vector and Cartesian form, length of perpendicular of a point from a plane by both vector and Cartesian methods.

UNIT IV: STATISTICS

Statistics and probability

Mean deviation for ungrouped data, variance for grouped an ungrouped data, standard deviation. Random experiments and sample space, Events as subset of a sample space, occurrence of an event, sure and impossible events, Exhaustive events, Algebra of events, Meaning of equality likely outcomes, mutually exclusive events. Probability of an event; Theorems on probability; Addition rule, Multiplication rule, Independent experiments and events. Finding P (A or B), P (A and B), random variables, Probability distribution of a random variable.

UNIT V : CALCULUS

Functions, Limits and continuity

Concept of a real function; its domain and range; Modulus Function, Greatest integer function: Signum functions; Trigonometric functions and inverse trigonometric functions and their graphs; composite functions, Inverse of a function.

Limit of a function; meaning and related notations; Left and right hand limits; Fundamental theorems

on limits without proof
$$\lim_{x \to a} \frac{x^n - a^n}{x - a} = na^{n-1}, a > 0; \lim_{x \to 0} \frac{Sin x}{x} = 1; \lim_{x \to 0} \frac{e^x - 1}{x} = 1$$
 (without proof);

 $\lim_{x\to 0} \frac{\log(1+x)}{x} = 1$ Limits at Infinity and infinity limits; continuity of a function at a point, over an open/ closed interval; Sum, Product and quotient of continuous functions; Continuity of special functions- Polynomial, Trigonometric, exponential, Logarithmic and Inverse trigonometric functions.

Differentiation

Derivative of a function; its geometrical and physical significance; Relationship between continuity and differentiability; Derivatives of polynomial, basic trigonometric, exponential, logarithmic and inverse trigonometric functions from first principles; derivatives of sum, difference, product and quotient of functions; derivatives of polynomial, trigonometric, exponential, logarithmic, inverse trigonometric and implicit functions; Logarithmic differentiation; derivatives of functions expressed in parametric form; chain rule and differentiation by substitution; Derivatives of Second order.

Application of Derivatives

Rate of change of quantities; Tangents and Normals; increasing and decreasing functions and sign of the derivatives; maxima and minima; Greatest and least values; Rolle's theorem and Mean value theorem; Approximation by differentials.

Indefinite Integrals

Integration as inverse of differentiation; properties of integrals; Integrals involving algebraic, trigonometric, exponential and logarithmic functions; Integration by substitution; Integration by parts; Integrals of the type:

$$\int \frac{dx}{x^2 \pm a^2}, \int \frac{dx}{a^2 - x^2}, \int \frac{dx}{\sqrt{x^2 \pm a^2}}, \int \frac{dx}{\sqrt{a^2 - x^2}}, \int \frac{dx}{ax^2 + bx + c},$$
$$\int \frac{px + q}{ax^2 + bx + c} dx, \int \frac{dx}{\sqrt{ax^2 + bx + c}}, \int \frac{px + q}{\sqrt{ax^2 + bx + c}} dx.$$

Integration of rational functions; Partial fractions and their use in integration; Integrals of the type

$$\int \sqrt{x^2 \pm a^2} \, dx, \int \sqrt{a^2 - x^2} \, dx, \int \sqrt{ax^2 + bx + c} \, dx, \int (px + q) \sqrt{ax^2 + bx + c} \, dx,$$
$$\int \frac{dx}{a + b \cos x}, \int \frac{dx}{a - b \sin x}, \int \sin^{-1} x \, dx, \int \log x \, dx.$$

Definite Integrals

Definite integral as limit of a sum; Fundamental theorems of integral calculus without proof); Evaluation of definite integrals by substitution and by using the following properties.

$$\int_{a}^{b} f(x) dx = -\int_{b}^{a} f(x) dx; \int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$$

$$\int_{a}^{b} f(x) dx = \int_{a}^{b} f(a + b - x) dx; \int_{0}^{a} f(x) dx = \int_{0}^{a} f(a - x) dx$$

$$\int_{a}^{b} f(x) dx = \int_{a}^{b} f(a + b - x) dx; \int_{0}^{a} f(x) dx = \int_{0}^{a} f(a - x) dx$$

$$\int_{a}^{b} f(x) dx = \int_{a}^{b} f(a + b - x) dx; \int_{0}^{a} f(x) dx = \int_{0}^{a} f(a - x) dx$$

$$\int_{0}^{2a} f(x) dx = \int_{0}^{a} f(x) dx + \int_{0}^{a} f(2a - x) dx; = \int_{0}^{2a} f(x) dx = 2 \int_{0}^{a} f(x) dx, \text{ if } f(2a - x) = f(x)$$

$$\int_{0}^{2a} f(x) dx = 0, \text{ if } f(2a - x) = -f(x)$$

$$\int_{-a}^{a} f(x) dx = \begin{cases} 2 \int_{0}^{a} f(x) dx, \text{ if } f(x) \text{ is even} \\ 0 & \text{ if } f(x) \text{ is odd} \end{cases}$$

Application of definite integrals in finding areas bounded by a curve, circle, parabola and ellipse in standard form between two ordinates and x-axis; Area between two curves, line and circle; line and parabola: line and ellipse.

Differential Equations

Definition; order and degree; general and particular solutions of a differential equation; formation of differential equations whose general solution is given; solution of differential equations by method of Separation of variables; Homogeneous differential equations of first order and their solutions; Solution

of linear differential equations of the type $\frac{dy}{dx} + P(x) y = Q(x)$ where P (x), Q (x) are functions of x.

PHYSICS

UNIT 1: INTRODUCTION AND MEASUREMENT

Physics - Scope and excitement; Physics in relation to science, society and technology - inventions, names of scientists and their fields, nobel prize winners and topics, current developments in physical sciences and related technology. Units for measurement - systems of units, S . I units, conversion from other systems to S.I units. Fundamental and derived units. Measurement of length, mass and time, least count in measuring instruments (eg. vernier calipers, screw gauge etc), Dimensional analysis and applications, order of magnitude, accuracy and errors in measurement, random and instrumental errors, significant figures and rounding off principles.

UNIT 2 : DESCRIPTION OF MOTION IN ONE DIMENSION

Objects in motion in one dimension - Motion in a straight line, uniform motion - its graphical representation and formulae; speed and velocity - instantaneous velocity; ideas of relative velocity with expressions and graphical representations; Uniformly accelerated motion, position - time graph, velocity - time graph and formulae. Elementary ideas of calculus - differentiation and integration - applications to motion.

UNIT 3 : DESCRIPTION OF MOTION IN TWO AND THREE DIMENSIONS

Vectors and scalars, vectors in two and three dimensions, unit vector, addition and multiplication, resolution of vector in a plane, rectangular components, scalar and vector products. Motion in two dimensions - projectile motion, ideas of uniform circular motion, linear and angular velocity, relation between centripetal acceleration and angular speed.

UNIT 4 : LAWS OF MOTION

Force and inertia, first law of motion, momentum, second law of motion, forces in nature, impulse, third law of motion, conservation of linear momentum, examples of variable mass situation, rocket propulsion, equilibrium of concurrent forces.

Static and kinetic friction, laws of friction, rolling friction, lubrication. Inertial and non-inertial frames (elementary ideas); Dynamics of uniform circular motion – centripetal and centrifugal forces, examples : banking of curves and centrifuge.

UNIT 5 : WORK, ENERGY AND POWER

Work done by a constant force and by a variable force, units of work - Energy - kinetic and potential forms, power, work-energy theorem. Elastic and inelastic collisions in one and two dimensions. Gravitational potential energy and its conversion to kinetic energy, spring constant, potential energy of a spring, Different forms of energy, mass - energy equivalence (elementary ideas), conservation of energy, conservative and non-conservative forces.

UNIT 6: MOTION OF SYSTEM OF PARTICLES AND RIGID BODY ROTATION

Centre of mass of a two particle system, generalisation to N particles, momentum conservation and center of mass motion, applications to some familiar systems, center of mass of rigid body. Moment of a force, torque, angular momentum, physical meaning of angular momentum, conservation of angular momentum with some examples, eg. planetary motion. Equilibrium of rigid bodies, rigid body rotation and equation of rotational motion, comparison of linear and rotational motions, moment of inertia and its physical significance, radius of gyration, parallel and perpendicular axes theorems (statements only), moment of inertia of circular ring and disc, cylinder rolling without slipping.

UNIT 7 : GRAVITATION

Universal law of gravitation, gravitational constant (G) and acceleration due to gravity (g), weight and gravitation, variation of g with altitude, latitude, depth and rotation of earth. Mass of earth, gravitational potential energy near the surface of the earth, gravitational potential, escape velocity, orbital velocity of satellite, weightlessness, motion of geostationary and polar satellites, statement of