Syllabus B. Tech (Electrical Engineering) BoS - 2020

Syllabus

Core Courses

B. Tech (Electrical Engineering) BoS - 2020

| | | ELECTRI | ICAL ENG | GINEERING DEPARTMENT | | | | | | |
|-------------|---|---|---|---|----------------------------------|-----------------------------------|---------------|--|--|--|
| Course:- Ba | chelor of Te | echnology (E | lectrical E | Engineering) | | | | | | |
| Semester | Third | Subject Titl | le | Electrical Circuit Analysis | | Code | TEE 301 | | | |
| Course Com | ponents | Credits | | | L | Т | Р | | | |
| Core Course | (CC) | 04 | | Contact Hours | 03 | 01 | 00 | | | |
| Examination | n Duration | Theory | Practic al | WEIGHTAGE: EVALUATION | CW A | MSE | ESE | | | |
| (Hrs) | | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Obje | ectives | | | | | | | | | |
| CO 1 | Apply netv | work theorem | s for the a | nalysis of electrical circuits. | | | | | | |
| CO2 | Explain the transient and steady-state response of electrical circuits. | | | | | | | | | |
| CO3 | Analyze ci | Analyze circuits in the sinusoidal steady-state (single-phase and three-phase). | | | | | | | | |
| CO4 | Familiarit | Camiliarity with the solution of first and second order networks. | | | | | | | | |
| CO5 | Applicatio | n of Laplace | transform | for circuit analysis | | | | | | |
| CO6 | Design of a | different kind | s of two p | ort networks | | | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Superposition theorem, Thevenin's theorem, Norton theorem, Maximum power transfer theorem. Analysis with dependent current and voltage sources. Node and Mesh Analysis. Graph Theory, Network Topology, formation of incidence matrix, Tie set and cutest matrix, equilibrium equations, solution of electric circuits. Concept of duality and dual networks | | | | | | | | | |
| Unit -2 | Sinusoidal Representa and admitt complex p coupled cin | I steady state ation of sine ances, AC cir ower. Three- rcuits, Ideal T | e analysis function a rcuit analy phase circ fransforme | as rotating phasor, phasor diag ysis, effective or RMS values, a puits. Mutual coupled circuits, I er. | rams, im verage p Oot Conv | pedance ower and rention in | s 1 7 1 | | | |
| Unit -3 | Electrical Circuit Analysis Using Laplace Transforms Review of Laplace Transform, Analysis of electrical circuits using Laplace Transform for standard inputs, convolution integral, inverse Laplace transform, transformed network with initial conditions. Transfer function representation. Poles and Zeros. Frequency response (magnitude and phase plots), series and parallel | | | | | | | | | |
| Unit -4 | Fourier Circuit analysis : Trignometric form of Fourier series. Concept of Symmetry. Circuit response to periodic forcing functions. Circuit analysis in the S-domain. Z(s) & Y(s) functions, Modelling of inductor, Capacitor. Nodal & Mesh analysis in the S-domain. Transfer functions. | | | | | | | | | |
| Unit -5 | Two Port Two Port I parameters interconne | Network Networks, ter s, admittance ctions of two | rminal pai parameter port netw | rs, relationship of two port var s, transmission parameters and h orks. | ables, ir lybrid pa | npedance | 7 | | | |
| | Total Hou | irs | | | | | 42 | | | |

- 1. M. E. Van Valkenburg, "Network Analysis", Prentice Hall, 2006.
- 2. D. Roy Choudhury, "Networks and Systems", New Age International Publications, 1998.
- 3. W. H. Hayt and J. E. Kemmerly, "Engineering Circuit Analysis", McGraw Hill Education, 2013.
- 4. C. K. Alexander and M. N. O. Sadiku, "Electric Circuits", McGraw Hill Education, 2004.
- 5. K. V. V. Murthy and M. S. Kamath, "Basic Circuit Analysis", Jaico Publishers, 1999

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|--|---|---|--|--|--|---------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | Third | Subject | Title | Analog Electronics | | Code | TEE 305 | | | |
| Course Com | ponents | Credits | | | L | Τ | P | | | |
| Core Course | (CC) | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examination | ı | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration (H | rs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Obje | ctives | | | | | | • | | | |
| CO 1 | Demonstrate the characteristics of diode and BJT. | | | | | | | | | |
| CO2 | Understand the characteristics of MOSFET. | | | | | | | | | |
| CO3 | Design the various types of rectifier and amplifier circuits. | | | | | | | | | |
| CO4 | Design of | sinusoida | l and non-si | nusoidal oscillators. | | | | | | |
| CO5 | Understa | nd the fur | ctioning of | OP-AMP and design OP-AMP bas | sed circu | iits. | | | | |
| CO6 | Familiari | ze with lin | near and nor | nlinear applications of OP-AMP. | | | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Junction of rectifiers, BJT circu Structure a signal mod amplifiers | liode, I-V Zener dio nits and I-V ch del, biasin ; Small si | characteris des, clampin aracteristics g circuits, c gnal equival | stics of a diode; review of half-wing and clipping circuits, Varactor of s of a BJT; BJT as a switch. BJT as common-emitter, common-base and ent circuits, high-frequency equiva | vave an liode. an ampl d comm alent circ | d full-wave lifier: small- on-collector cuits | 12 | | | |
| Unit -2 | MOSFET MOSFET amplifier: common-d impedance | circuits structure small-sigr lrain amp es, trans-co | and I-V ch al model an lifiers; smal onductance, l | aracteristics. MOSFET as a switc ad biasing circuits, common-source 1 signal equivalent circuits - gain nigh frequency equivalent circuit. | ch. MOS e, comm 1, input | SFET as an non-gate and and output | 8 | | | |
| Unit -3 | Introduct Basics of c characteris | ion to op op-amp, Ic stics of op | erational an leal Op-amp -amp, AC c | nplifier b, Internal circuit of op-amp, Differ haracteristics of op-amp. | ential ar | nplifier; DC | 6 | | | |
| Unit -4 | Linear applications of op-ampInverting and non-inverting amplifier, differential amplifier, Adder, Subtractor,instrumentation amplifier, integrator, differentiator,Op-amp based active filter, oscillators (Wein bridge and phase shift). | | | | | | | | | |
| Unit -5 | Nonlinear applications of op-amp Hysteretic Comparator, Zero Crossing Detector, Square-wave and triangular-wave generators. Precision rectifier, peak detector. | | | | | | | | | |
| | Total Hou | urs | | | | | 36 | | | |

- 1. A. S. Sedra and K. C. Smith, "Microelectronic Circuits", New York, Oxford University Press, 1998.
- 2. J. V. Wait, L. P. Huelsman and G. A. Korn, "Introduction to Operational Amplifier theory and applications", McGraw Hill U. S., 1992.
- 3. J. Millman and A. Grabel, "Microelectronics", McGraw Hill Education, 1988.
- 4. P.R. Gray, R.G. Meyer and S. Lewis, "Analysis and Design of Analog Integrated Circuits", John Wiley & Sons, 2001.
- 5. Milliman, J. and Halkias, C.C., Intergrated Electronics, Tata McGraw Hill (2007).

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|------------------------------|----------------|---------------------------------------|------------|----------|-----|--|--|--|--|
| Course:- E | Bachelor of | Technolo | gy (Electric | al Engineering) | | | | | | | |
| Semester | 3 RD Subject Title Electrical Machines - I Code | | | | | | | | | | |
| Course Co | mponents | Credits | | | L | T | Р | | | | |
| Core Cour | se (CC) | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (| (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Ob | jectives | | | | | | | | | | |
| CO 1 | Understar | nd the con | cepts of ma | gnetic circuits. | | | | | | | |
| CO2 | Applicatio | on of mag | netic field in | n production of force and torque | | | | | | | |
| CO3 | Analysis o | the vertice | nine configu | irations and characteristics | | | | | | | |
| C04 | Examine | the variou | of operation | on of various types of transformers | | | | | | | |
| 0.05 | Acquire the concept of operation of various types of transformers. Assessment of various performance parameters of single phase and three phase | | | | | | | | | | |
| CO6 | Assessment of various performance parameters of single phase and three phase circuits. | | | | | | | | | | |
| Unit No. | vo. Content | | | | | | | | | | |
| | Content Magnetic fields and magnetic circuits | | | | | | | | | | |
| | Magnetic fields and magnetic circuits Review of magnetic circuits - MMF, flux, reluctance, inductance; review of | | | | | | | | | | |
| Unit -1 | Ampere La | aw and Bi | ot Savart L | aw; Visualization of magnetic field | ls produ | ced by | 8 | | | | |
| | a bar magi | net and a c | current carry | ying coil - through air and through | a comb | ination | | | | | |
| | of iron and | l air; influe | ence of high | ly permeable materials on the magn | netic flux | x lines. | | | | | |
| | Electrom | agnetic f | orce and t | orque | | | | | | | |
| | B-H curve of magnetic materials; flux-linkage vs current characteristic of | | | | | | | | | | |
| Unit -2 | magnetic of | circuits; li | near and n | onlinear magnetic circuits; energy | stored | in the | 6 | | | | |
| | magnetic of | circuit; - | Force and | forque Calculation from Energy a | ind Co- | energy | | | | | |
| | Transfor | nong | chanical Sys | stems | | | | | | | |
| | Principle | constructi | on and one | eration of single-phase transform | ere eau | ivələnt | | | | | |
| | circuit nh | asor diagr | am voltage | regulation losses and efficiency | Testing | - open | | | | | |
| | circuit and | d short c | ircuit tests. | polarity test, back-to-back test. | separat | ion of | | | | | |
| | hysteresis | and eddy | current loss | ses Three-phase transformer - cons | struction | , types | | | | | |
| Unit 3 | of connect | tion and th | neir compar | ative features, Parallel operation of | of single | -phase | Q | | | | |
| 01111 - 5 | and three | -phase ti | ansformers | , Autotransformers - constructi | on, pri | nciple, | 0 | | | | |
| | applicatior | ns and con | nparison wit | th two winding transformer, Magne | etizing c | urrent, | | | | | |
| | effect of | nonlinear | B-H cur | ve of magnetic core material, | harmon | ics in | | | | | |
| | magnetizat | tion curre | nt, Phase co | onversion - Scott connection, three | e-phase | to s1x- | | | | | |
| | phase conv | version, 18 | ap-changing | transformers - No-load and on-loa | a tap-ch | anging | | | | | |
| | DC mach | incis, Till | ce-winding | transformers. Cooling of transform | CIS. | | | | | | |
| | Basic cons | struction (| of a DC ma | chine magnetic structure - induc | ed FMF | 'in an | | | | | |
| | armature c | oil Armat | ure winding | and commutation - Elementary arr | nature ce | oil and | | | | | |
| Unit -4 | commutate | or. lap a | nd wave v | windings. construction of comm | nutator. | linear | 6 | | | | |
| | commutation armature MMF wave, derivation of torque equation, armature | | | | | | | | | | |
| | reaction, a | ir gap flux | density dis | tribution with armature reaction. | | | | | | | |
| | DC mach | ine - mo | toring and | generation | | | | | | | |
| | DC motor | principl | e of operation | on – back emf – classification – tor | que equ | ation – | | | | | |
| . | losses and | efficiency | – power flo | w diagram – performance character | ristics of | shunt, | ~ | | | | |
| Unit-5 | series and | compoun | d motors – | starting of dc motors – necessity | y and ty | pes of | 8 | | | | |
| | starters – s | speed cont | rol – metho | as of speed control – testing – Swi | nburne' | s test – | | | | | |
| | motors | is test – | separation | of losses – retardation test – app | ncations | of dc | | | | | |
| | Total Hou | irs | | | | | 36 | | | | |
| | 101011100 | 13 | | | | | 50 | | | | |

Text / References

- 1. A. E. Fitzgerald and C. Kingsley, "Electric Machinery", New York, McGraw Hill Education, 2013.
- 2. A. E. Clayton and N. N. Hancock, "Performance and design of DC machines", CBS Publishers, 2004.
- 3. M. G. Say, "Performance and design of AC machines", CBS Publishers, 2002.
- 4. P. S. Bimbhra, "Electrical Machinery", Khanna Publishers, 2011.
- 5. I. J. Nagrath and D. P. Kothari, "Electric Machines", McGraw Hill Education, 2010.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--|-------------|--------------|---|------------|---------|---------|--|--|--|
| Course:-Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | Third | Subject 2 | Title | Electrical and Electronics Measuring Instr | uments | Code | TEE 303 | | | |
| Course Compone | ents | Credits | | Contact Hours | L | Τ | Р | | | |
| Core Co | urse (CC) | 03 | | | 03 | 00 | 00 | | | |
| Examina | tion | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration | (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course (| Objectives | | | | | | | | | |
| CO 1 | Understa | nd the con | cept of mea | surement and different measuring instrume | nts. | | | | | |
| CO2 | Realize th | e working | of various | analog instruments to measure electrical qua | antities | | | | | |
| CO3 | Estimation of electrical quantities through measuring instruments. | | | | | | | | | |
| CO4 | Application of instrument transformer. | | | | | | | | | |
| CO5 | Developing the concept of digital measurement of electrical quantities. | | | | | | | | | |
| CO6 | Analyze various electrical signals through cathode ray oscilloscope and power analyzer | | | | | | | | | |
| | | | | | | | | | | |
| Unit | Content | | | | | | | | | |
| <i>NO</i> . | Introduction to Magnuments Matheda of Magnument Classification of instrument | | | | | | | | | |
| IInit_1 | Introduction to Measurement: Methods of Measurement, Classification of instrument | | | | | | | | | |
| Umt-1 | Analysis | laracterist | | nent & measurement system, Errors in wea | isuremen | n œ ns | 5 | | | |
| | Analog N | leasurem | ent of Ele | ctrical Quantities: Principle of operation | ons and | torque | | | | |
| | equations | for differe | ent types of | instruments, PMMC, Moving Iron, Electr | odynamo | ometer, | | | | |
| | Ammeters | & Voltm | eters, Mult | i-Range ammeter & voltmeter, Electrodyn | amomete | er type | | | | |
| Unit-2 | Wattmeter | , Power in | three Phase | e System. | | | 10 | | | |
| | Measuren | nent of El | ectrical Qu | antities: Different methods of measuring lo | w, mediu | um and | | | | |
| | high resist | ances, Me | asurement | of Inductance & Capacitance with the help | of AC l | Bridge, | | | | |
| | Measurem | ent of Fre | quency and | Power factor. | | | | | | |
| | Instrume | nt Iransi | Difference | between CT and PT transformation ratio | n the exi | tension | | | | |
| Unit-3 | error for C | T and PT | causes of | errors reduction of errors effect of second | ary open | | 7 | | | |
| | for CT | | , causes of | errors, reduction of errors, effect of second | ary open | circuit | | | | |
| T T 1 . 1 | Digital M | easureme | nt of Elect | rical Quantities: Concept of digital Measu | rement. | Digital | | | | |
| Unit-4 | voltmeter, | Digital fre | equency me | ter. | | 8 | 6 | | | |
| | Cathode | Ray Osci | lloscope: In | ntroduction, cathode ray tube, electron gu | ın, electi | ostatic | | | | |
| Unit-5 | deflection | plates, tir | ne base gei | nerator, Attenuator, synchronization, storag | ge oscillo | oscope, | 8 | | | |
| | observatio | ns of way | veform on | CRO, measurements using CRO – Volta | ge, Freq | luency, | | | | |
| | Period, Ph | ase. | | | | | 26 | | | |
| | Total Hou | ILL | | | | | 30 | | | |

Text Book:

- 1. E.W. Golding& F.C. Widdis, "Electrical Measurement & Measuring Instrument", A.W. Wheeler& Co. Pvt. Ltd. India.
- 2. A.K. Sawhney: "Electrical & Electronic Measurement & Instrument ", Dhanpat Rai& Sons, India.

References:

- Forest K. Harries, "Electrical Measurement "Willey Eastern Pvt. Ltd. India.
 M.B. Stout, "Basic Electrical Measurement" Prentice hall of India, India.

| Conversion of Technology (Electrical Engineering) Semester Third Subject Title Electromagnetic Fields Code TEB 30e Course Components Credits Contact Hours 03 01 00 Examination Theory Practical WEIGHTAGE:EVALUATION CWA MSE ESE Duration (Hrs) 03 00 WEIGHTAGE:EVALUATION CWA MSE ESE CO1 Application of various forms of vectors CO1 Application of Laplace's and Poisson's equations. CO2 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO3 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit No. Review of Vector Calculus Vector scalar and vector Weator algebra-addition, subtraction, components of vectors, scalar and vector for unitiplications, riple products, three orthogonal coordinate systems (rectangular, vector scale sherical). Vector calculus-differentiation, and tis applications. Absolute Electric potential, differentiation, integration, vector operator del, gradient, divergence and curi, integrat theorems of vectors. Conversion of a vector from one coordinate system to another. 12 Unit No. Static Electri | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|---|---|--|--|---|----------------------------------|--|-----|--|--|--|
| Semester Third Subject Title Electromagnetic Fields Code TEE 30c Course (CC) 04 Contact Hours 03 01 00 Examination Theory Practical WEIGHTAGE:EVALUATION CWA MSE ESE Duration (Hrs) 03 00 25 25 50 Course Objectives CO Application of various forms of vectors CO Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO2 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO6 Utilization of Maxwell's equation in different forms and different media. CO6 Utilization of Maxwell's equation in different forms and different media. CO6 Utilization of Maxwell's equation in different forms and different media. Go and vector Go and vector <th colspan="11">Course:- Bachelor of Technology (Electrical Engineering) Semester Third Subject Title Electromagnetic Fields Code T</th> | Course:- Bachelor of Technology (Electrical Engineering) Semester Third Subject Title Electromagnetic Fields Code T | | | | | | | | | | |
| Corres Components Credits Contact Hours L T P Core Course (CC) 04 Contact Hours 03 00 00 00 Examination Theory Practical WEIGHTAGE:EVALUATION CWA MSE ESE Duration (Hrs) 03 00 00 25 25 50 Course Objectives CO1 Application of various forms of vectors CO2 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO3 Application of Laplace's and Poisson's equations. CO4 CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO4 Hours CO4 Mequiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO4 Hours CO4 Mequiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO4 Hours CO4 Mequiring the knowledge of various characteristics Conductor, dielectric, capacitance. CO4 CO4 Mequiring | Semeste | ourse:- Bachelor of Technology (Electrical Engineering) emester Third Subject Title Electromagnetic Fields Code | | | | | | | | | |
| Core Course (CC) 04 Contact Hands 03 01 00 Examination Theory Practical WEIGHTAGE:EVALUATION CWA MSE ESE Duration (Hrs) 03 00 WEIGHTAGE:EVALUATION 25 25 50 Course Objectives CO Application of various forms of vectors 25 25 50 CO2 Acquiring the knowledge of various laws associated with electrostatics and electromagnetics CO3 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. Coc CO5 Demonstration of Maxwell's equation in different forms and different media. Hours Co6 Utilization of EM waves. Hours Unit Content Hours No. Review of Vector Calculus Vector score opartate (differentiation, partial differentiation, integration, vector opartato ed, gradient, divergence and curl: integrat theorems of vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absol | Course | Components | Credits | | Contact Hours | L | Т | P | | | |
| Examination Theory Practical WEIGHTAGE:EVALUATION CWA MSE ESE Duration (Hrs) 03 00 25 25 50 Course Objectives 25 25 50 CO1 Application of various forms of vectors 25 25 50 CO2 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. 203 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. 206 Utilization of EM waves. 4000 CO6 Utilization of EM waves. 4000 4000 4000 4000 Vector algebra-addition, subtraction, components of vectors, scalar and vector 40000 40000 40000 40000 Vector algebra-addition, subtraction, components of vectors, scalar and vector 40000 40000 40000 40000 40000 40000 40000 40000 400000 400000 400000 4000000 4000000 40000000 4000000000 4000000000000000000000000000000000000 | Core Co | ourse (CC) | 04 | - | Contact Hours | 03 | 01 | 00 | | | |
| Duration (Hrs) 03 00 25 25 50 Course Objectives CO1 Application of various forms of vectors CO2 Acquiring the knowledge of various laws associated with electrostatics and electromagnetics CO3 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Hours Hours Content Hours Review of Vector Calculus Hours 6 itilization, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. 6 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, ensity, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Static Electric Eields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic, potential differentis, Steady magnetic fields produced b | Examin | ation | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Conserve Objectives CO1 Application of various forms of vectors CO2 Acquiring the knowledge of various laws associated with electrostatics and electromagnetics CO3 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector ultiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulomb's law, Electrici field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, and Volume charge distributions. Gauss law and its application, Solution of Laylace, calculation of potential differences for different configurations. 2 Static Magnetic Fields. Such-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. Unit | Duratio | n (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| CO1 Application of various forms of vectors CO2 Acquiring the knowledge of various laws associated with electrostatics and electromagnetics CO3 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit No. Review of Vector Calculus Hours Vector algebra-addition, subtraction, components of vectors, scalar and vector Hours 1 multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, electric diplet. Electrostatic Energy and Energy density. 12 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Init . Gonductors, Dielectrics and Capacitance Capacitance | Course | Objectives | | | | | | | | | |
| CO2 Acquiring the knowledge of various laws associated with electrostatics and electromagnetics CO3 Application of Laplace's and Poisson's equations. CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit Review of Vector Calculus No. Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector unit - cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. 2 Electric dipole, Electrostatic Energy and Energy density. 3 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. 4 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielect | CO 1 | Application of | of various | forms of ve | ctors | | | | | | |
| C03 Application of Laplace's and Poisson's equations. C04 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. C05 Demonstration of Maxwell's equation in different forms and different media. C06 Utilization of EM waves. Unit Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulumb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. 12 2 Electric dipole, Electrostatic Energy and Energy density. 12 3 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Requiring and Poisson's equation, Laplace's equation, Sugnetic materials, Capacitance, and Poisson's equation formations. 12 1 Conductors, Dielectrics and Capacitance Current and current density. Ohms Law in Point form, Continuity of current, Boundary co | CO2 | Acquiring the | e knowled | ge of variou | s laws associated with electrostatic | es and el | ectromagnetic | S | | | |
| CO4 Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit No. Content Hours Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl: integral theorems of vectors. Conversion of a vector from one coordinate system to another. 6 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, entry optimized fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit 3 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. 12 Magnetic Forces, Materials and Inductance: Time Varying Fields and Maxwell's Equations 12 Magnetic For | CO3 | Application | of Lapla | ce's and Poi | sson's equations. | | | | | | |
| CO5 Demonstration of Maxwell's equation in different forms and different media. CO6 Utilization of EM waves. Unit No. Content Hours Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector unit-integration, striple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. 1 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Unit - Potential difference, Calculation of potential differences for different configurations. 12 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit - 3 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. 12 Magnetic Forces, Materials and Inductance: Crapacitance of a two wire line, Poisson's equation, Continuity of current, Boundary conditions of perfect dielectric materi | CO4 | Acquiring the knowledge of various characteristics of conductor, dielectric, capacitance. | | | | | | | | | |
| CO6 Utilization of EM waves. Unit No. Content Hours Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector unit - multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. 6 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Unit - Potential difference, Calculation of potential differences for different configurations. Electric dipole, Electrostatic Energy and Energy density. 12 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit - 3 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, and Poisson's equation, Application of Laplace's and Poisson's equations. 12 Magnetic Forces, Materials and Inductance: materials, Magnetization and permeability, Magnetic boundary conditions, Magnetic circuits, inductances and mutual inductances. 12 Unit - 3 Time Varying Fields and Maxwell's Equations Maxwell's equation, Integral form | CO5 | Demonstration of Maxwell's equation in different forms and different media. | | | | | | | | | |
| Unit No. Content Hours No. Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. 6 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Unit - Potential difference, Calculation of potential differences for different configurations. Electric dipole, Electrostatic Energy and Energy density. Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit - 3 Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permitivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. Magnetic Forces, Materials and Inductance: Force on a moving charge, Force on a differential current element, Force between differential current elements, Naure of magnetic materials, Magnetization and permeability, Magnetic boundary conditions, Magnetic circuits, inductances and mutual inductances. 12 Unit - 3 Firaday's law for Electroma | CO6 | Utilization of EM waves. | | | | | | | | | |
| Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. 6 Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. 12 2 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit - Conductors, Dielectrics and Capacitance 12 Unit - Conductors, Dielectrics and Capacitance 12 Unit - Conductors, Dielectrics and Capacitance 12 Unit - Conductors, Dielectrics and Inductance: Force on a moving charge, Force on a differential current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's end poisson's equations, Magnetic circuits, inductances and mutual inductances. 12 </td <td>Unit No.</td> <td colspan="9">it Content</td> | Unit No. | it Content | | | | | | | | | |
| Vectors. Conversion of a vector from one coordinate system to another. Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. Electric dipole, Electrostatic Energy and Energy density. 12 2 Electric dipole, Electrostatic Energy and Energy density. 12 Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors. 12 Unit - Conductors, Dielectrics and Capacitance 12 Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. 12 3 Magnetic Forces, Materials and Inductance: Force on a moving charge, Force on a differential current element, Force between differential current elements, Nature of magnetic circuits, inductances and mutual inductances. 12 Unit - Time Varying Fields and Maxwell's Equations 6 Unit - Faraday's law for Electromagnetic induction, Displacement current, Point form of Maxwell's equation, Integral form of Maxwell's equations, Motional Electromotive forces. | Unit - 1 | Review of Vector Calculus Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another. | | | | | | | | | |
| Unit 3Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations.123-Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. Magnetic Forces, Materials and Inductance: Force on a moving charge, Force on a differential current element, Force between differential current elements, Nature of magnetic circuits, inductances and mutual inductances.12Unit 4-Time Varying Fields and Maxwell's Equations Maxwell's equation, Integral form of Maxwell's equations, Motional Electromotive forces. Boundary Conditions.6Unit 5-Electromagnetic Waves Derivation of Wave Equation, Uniform Plane Waves, Maxwell's equation in Phasor form, Wave equation in Phasor form, Plane waves in free space and in a homogenous material.6 | Unit - 2 | Static Electric Field Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. Electric dipole, Electrostatic Energy and Energy density. Static Magnetic Fields. Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current | | | | | | | | | |
| Unit -Time Varying Fields and Maxwell's Equations4Faraday's law for Electromagnetic induction, Displacement current, Point form of Maxwell's equation, Integral form of Maxwell's equations, Motional Electromotive forces. Boundary Conditions.6Unit -Electromagnetic Waves Derivation of Wave Equation, Uniform Plane Waves, Maxwell's equation in Phasor form, Wave equation in Phasor form, Plane waves in free space and in a homogenous material.6 | Unit - 3 | Conductors, Dielectrics and Capacitance Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials. Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations. Magnetic Forces, Materials and Inductance: Force on a moving charge, Force on a differential current element, Force between differential current elements, Nature of magnetic materials, Magnetization and permeability, Magnetic boundary conditions, Magnetic | | | | | | | | | |
| Unit - Derivation of Wave Equation, Uniform Plane Waves, Maxwell's equation in Phasor form, Wave equation in Phasor form, Plane waves in free space and in a homogenous material. | Unit - 4 | Time Varying Fields and Maxwell's Equations Faraday's law for Electromagnetic induction, Displacement current, Point form of Maxwell's equation, Integral form of Maxwell's equations, Motional Electromotive forces. Boundary Conditions. | | | | | | | | | |
| Wave equation for a conducting medium, Plane waves in lossy dielectrics, Propagation in good conductors, Skin effect. Poynting theorem | Unit - 5 | Derivation of Wave equation Wave equation good conductor | etic Wave Wave Equ n in Phase n for a co ors, Skin e | es uation, Unif or form, Pla nducting me effect. Poynt | form Plane Waves, Maxwell's equa ne waves in free space and in a he edium, Plane waves in lossy dielec ing theorem | ation in omogen etrics, Pi | Phasor form, ous material. ropagation in | 6 | | | |
| Total Hours 42 | | Total Hours | | <u> </u> | ~ | | | 42 | | | |

M. N. O. Sadiku, "Elements of Electromagnetics", Oxford University Publication, 2014.
 G.W. Carter, "The electromagnetic field in its engineering aspects", Longmans, 1954.

- 3. W.J. Duffin, "Electricity and Magnetism", McGraw Hill Publication, 1980.
- 4. E.G. Cullwick, "The Fundamentals of Electromagnetism", Cambridge University Press, 1966.
- 5. B. D. Popovic, "Introductory Engineering Electromagnetics", Addison-Wesley Educational Publishers, International Edition, 1971.
- 6. W. Hayt, "Engineering Electromagnetics", McGraw Hill Education, 2012.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|--|---|---------------------|----------------|---|---------------|-------------|----------------|--|--|
| Course | e:- Bachelo | or of Techn | ology (ELEC | TRICAL EN | GINERING) | | | | | |
| Ser | nester | Third | Subjec | et Title | Analog Electro | nics Lab | Code | PEE 351 | | |
| Co | urse Comp | onents | Cre | dits | | L | Т | Р | | |
| C | ore Course | (CC) | 0 | 1 | Contact Hours | 00 | 00 | 02 | | |
| E | | | Theory | Practical | WEIGHTAGE: CWA MSE | | | ESE | | |
| Exa | mination D (Hrs) | nuranon | 00 | 03 | <i>EVALUATION</i> | 25 | 25 | 50 | | |
| Cours | e Objectiv | es | | | | | | | | |
| CO1 | Understar | nd the use the | he CRO and I | Multimeter for | or different application | ions. | | | | |
| CO2 | Understa | nd and Ve | erify the ph | ysical const | ruction, working a | and operation | onal chara | acteristics of | | |
| CO3 | Design ar | nd Analyze | s. the different | applications | of semiconductor di | odes. | | | | |
| CO4 | CO4 Verify and Analyze the output characteristics of Transistors (such as: BJTs, FETs) | | | | | | | | | |
| | | | | | | | | | | |
| Exper | iment | Name of the Experiment | | | | | | | | |
| <i>INO</i> . | | Plot V L abarratoristics of Junction diada under forward and reverse biased | | | | | | | | |
| 1 | | condition | (Si & Ga) | ues of jui | ction diode und | 1 IOI walu | | cise-biaseu | | |
| 2 | | Plot V-I | characteristi | cs of Zener | diode under revers | se-biased c | ondition. | | | |
| 3 | | Plot the I | nput - Outp | ut character | istics for the comm | non-base, (| Common I | Emitter and | | |
| | | To plot o | Collector c | onliguration | $\frac{15 \text{ OI a BJI}}{\text{MOFET & measurements}}$ | ire ninch_o | ff voltage | Calculate | | |
| 4 | | MOFET | parameters a | at a given of | berating point. | ite pillen-o | iii voltage | | | |
| 5 | | To study | R-C couple | d two-stage | common-emitter a | amplifier a | nd determ | ine voltage | | |
| 5 | | gain, cur | rent gain, in | put impedar | ce and output imp | edance. | | | | |
| 6 | | To study | single stage | RC-couple | d MOFET amplifi | er. | | | | |
| 7 | | To study | common-er | nitter / com | mon source amplif | fier and det | ermine vo | oltage gain, | | |
| 8 | | To study | am, mput m | ipedance an | a output impedance | e. | n_amn | | | |
| 9 | To study closed loop response of inverting and non-inverting op-amp | | | | | | | | | |
| 10 | | To design | and test or | -amp based | adder and Subtrac | ctor circuits | op-amp | | | |
| 10 | | To design | and test op | -amp based | integrator and dif | ferentiator | circuit | | | |
| 12 | | To study | op-amp bas | ed low pass | and high pass acti | ve filters | | | | |
| 13 | | To design | n and test or | -amp based | comparator circui | it | | | | |
| 14 | | To realiz | e Op-amp ba | ased triangu | lar wave generator | r | | | | |

-- Two innovative experiments can be given by the faculty In-charge.

Note: Minimum of 10 experiments to be performed.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|----------|---|---|---|-----------------|------------------------|----------------|------------|-------------|--|--|
| Course:- | Bachelo | r of Techn | ology (ELEC | CTRICAL EN | GINERING) | | | | | |
| Seme | ster | Third | Subjec | et Title | Electrical Machine | s Lab - I | Code | PEE 352 | | |
| Cours | e Compo | onents | Cre | dits | | L | T | Р | | |
| Core | Course | (CC) | 0 | 1 | Contact Hours | 00 | 00 | 02 | | |
| Enami | nation D | unation | Theory | Practical | WEICHTACE. | CWA | MSE | ESE | | |
| Exami | (Hrs) | uration | 00 | 03 | EVALUATION | 25 | 25 | 50 | | |
| Course C | Course Objectives | | | | | | | | | |
| CO 1 | Unders | tand the wo | nd the working of DC machines and its applications. | | | | | | | |
| CO2 | Unders | tand and V | erify the vari | ous operating | curves on the DC m | achines. | | | | |
| CO3 | Analyz | e the various tests on DC Machine | | | | | | | | |
| CO4 | Verify | and Analyz | the test of a | 3-phase Trans | stormer. | | | | | |
| Exnerim | ent No | Name of | the Exnerim | nt | | | | | | |
| 1 | | To estima | ate voltage rat | tio of 1-phase | e transformer. | | | | | |
| 2 | | To perfor | m Polarity te | st of 1-phase | transformer. | | | | | |
| 3 | | To determ | nine efficienc | v and voltage | e regulation of 1-pha | se transforr | ner throug | n load test | | |
| 4 | | To determ | nine core loss | es of 1-phase | e transformer using o | pen circuit | tests | | | |
| 5 | | To find th | ne copper loss | ses of 1-phase | e transformer by sho | rt circuit tes | st | | | |
| 6 | | To perfor | m 3-phase to | 2-phase conv | version by Scott com | nection. | | | | |
| 7 | | To find the efficiency and losses of dc shunt motor by Hopkinson's test | | | | | | | | |
| 8 | To find the efficiency of a dc shunt motor by Swinburne's test. | | | | | | | | | |
| 9 | | To perfor | m Speed con | trol of a dc sł | nunt motor by field f | lux method | | | | |
| 10 | | To perfor | m Speed con | trol of dc shu | nt motor by armatur | e terminal v | oltage met | hod. | | |
| 11 | 1 To perform load test on a dc shunt motor. | | | | | | | | | |
| 12 | | To find th | ne magnetizin | g characteris | tics of a dc shunt ger | nerator. | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|---|----------------|--|----------------|----------|---------|--|--|--|--|
| Course:- Bo | Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semeste | r Third | Subjec | ct Title | Career Skills (Verbal+ Log Reasoning | s - I gical | Code | XCS 301 | | | | |
| Course | Components | Cre | dits | | L | Т | Р | | | | |
| Career | Skills (CK) | 0 | 1 | Contact Hours | 02 | 00 | 00 | | | | |
| Examinat | tion Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| (| (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course Ob | jectives | | | | | | | | | | |
| CO 1 | To develop inte | | | | | | | | | | |
| CO2 | To develop prot | fessionals wi | th idealistic, | practical and moral | values. | | | | | | |
| CO3 | To develop con | To develop communication and problem solving skills | | | | | | | | | |
| CO4 | To re-engineer | | | | | | | | | | |
| Unit No. | Content | Hours | | | | | | | | | |
| Unit1. | Meeting Etiqu | ette – Introc | luctions - th | e Handshake– Exc | change of | Visiting | 8 | | | | |
| | Cards Persona | l Etiquette - | - Hygiene, C | Grooming, and Go | od sense | | | | | | |
| | Travel Etiquet | te, Sharing | Apartments | | | | | | | | |
| | Behavior at W | ork – Form | al behavior | with seniors and C | Colleagues | 5 — | | | | | |
| | Etiquette with | Women/me | n – Adherei | nce to Office Rule | s – Discip | oline | | | | | |
| | Table Manner | s and Small | Talk (unit 1 |) | | | | | | | |
| | Group Discus | sions: | | | | | | | | | |
| | Group Discuss | sion Technic | jues/ Do's a | nd Dont's / body] | language/ | mock | | | | | |
| | sessions. | | | | | | | | | | |
| Unit 2. | Logical Reaso | oning: Serie | s completio | n, Coding decodin | ig, directio | on sense | 6 | | | | |
| | test, logical Ve | enn diagram | , | | | | | | | | |
| Unit 3. | Logical Reaso | oning: math | ematical op | eration, number ra | nking, tin | ne | 6 | | | | |
| | sequence test, arithmetical reasoning. | | | | | | | | | | |
| Unit 4. | Job application: Importance of Business Communication in today's 8 | | | | | | | | | | |
| | world, Design | ing Busines | s Letters, Ty | pes of Letters . W | riting Eff | ective | | | | | |
| | Emails, Repor | Emails, Report Writing Essential parts - Cover Letter and the 'resume'. | | | | | | | | | |
| | Types of 'resu | mes ' (<i>Curr</i> | iculum Vita | e) Chronological ' | resume', | | | | | | |
| | tunctional 'res | ume' | | | | | • • | | | | |
| | Total | | | | | | 28 | | | | |

References

For Verbal Section:

Spoken English for India by R.K. Bansal and J.B. Harrison- Orient Longman

A practical English Grammar by Thomson and Martinet-Oxford University Press

Professional Communication by Malti Aggarwal

English grammar, composition and correspondence by M.A.Pink and A.E.Thomas –S.Chand and Sons. Word Power by Blum Rosen-Cambridge University Press

A Dictionary of Modern Usage-Oxford University Press

For Aptitude Section:

Quantitative aptitude by R.S Agarwal

Verbal and Non Verbal Reasoning by R.S Agarwal

All books of puzzles to puzzle to puzzle you by Shakuntala Devi.

Question Bank on the practice exercise (Created for internal use)

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|---|--|---|--|--|-------------------------------------|---------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | Fourth | Subject | Title | Digital Electronics | | Code | TEE 404 | | | |
| Course Con | mponents | Credits | | Constant House | L | Τ | Р | | | |
| Core Cours | se (CC) | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examination | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration (| Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Ou | itcomes: Aft | er succes | sful comple | tion of this course, students will | be able | to | | | | |
| CO1 | CO1 Acquiring the knowledge of digital codes and logic gates | | | | | | | | | |
| CO2 | Realization of Boolean algebra in digital circuits | | | | | | | | | |
| CO3 | Implementation of circuit elements as mathematical functions | | | | | | | | | |
| CO4 | Formulatio | on of com | binational c | ircuits | | | | | | |
| CO5 | Formulatio | on & imp | lementation | of sequential logic | | | | | | |
| CO6 | Design and | Analyse | counters. | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Number System & Codes: Binary, Octal, Hexadecimal number systems and their inter-conversion, Binary Arithmetic (Addition, Subtraction, Multiplication and Division), Diminished radix and radix compliments, BCD codes, Gray codes.10Logic Gates & Boolean Algebra: Basic Theorems and properties of Boolean Algebra, Boolean Functions, Canonical and Standard forms, Digital Logic Gate.10 | | | | | | | | | |
| Unit -2 | Simplificat The map m and Produc OR function Selection of | tion of Bo ethod, Tv t of Sums ons, The f Essentia | Dolean func vo, Three, F s Simplificat tabulation r l Prime impl | tions using Map and Tabulation Four and Five variable maps, Sum tion, NAND and NOR implement nethod, Determination of Prime licants. | n metho of produ ation, , 1 implica | o ds: acts Ex- nts, | 8 | | | |
| Unit -3 | Combinati converters, Multiplexen Logic Array | onal logi magnituc rs, Decod ys. | ic design : le comparat ers / De-mu | Design procedure, adders, subtors, Multiplexer, Binary adder a ultiplexers, Read Only Memory, | otarctors and subt Program | , code tractor, nmable | 8 | | | |
| Unit -4 | Introduction to Sequential Logic & counter design: Introduction, S-R Flip- flops, JK flip-flop, D flip-flop, T flip-flop, master slave flip-flop. Flip-flop5scitation table, Classification of sequential circuits.5 | | | | | | | | | |
| Unit – 5 | Introduction to counter design: design & analysis of Counters, mod-nsynchronous counters, BCD counter, Johnson counter, Ring counter, design ofsynchronous counter for a random sequence, mod-n Asynchronous/Ripple counter. | | | | | | | | | |
| | Total Hour | 'S | | | | | 36 | | | |

- R. P. Jain, "Modern Digital Electronics", McGraw Hill Education,2009.
 M. Mano, "Digital logic and Computer design", Pearson Education India,2016.
 A. Kumar, "Fundamentals of Digital Circuits", Prentice Hall India,2016.

| | | ELEC | TRICAL E | NGINEERING DEPARTMENT | | | | | | | |
|-------------------------|--|---|-----------------------------|--------------------------------------|-----------|----------|-------|--|--|--|--|
| Course:- Be | achelor of T | echnolog | y (Electrica | Lengineering) | | | | | | | |
| Semester | Fourth | FourthSubject TitleElectrical Machines – IICodenonentsCreditsIT | | | | | | | | | |
| Course Con | nponents | Credits | | Contact Hours | L | Τ | Р | | | | |
| Core Course | e (CC) | 03 | | Connact Hours | 03 | 00 | 00 | | | | |
| Examinatio | n | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (1 | Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Obj | ectives | | | | | | | | | | |
| CO1 | Understan | ding of v | arious wind | ings of AC machine | | | | | | | |
| CO2 | Utilization | of Pulsat | ing and Rev | olving magnetic field. | | | | | | | |
| CO3 | Evaluation | n of variou | is character | istics of 3-phase induction motor. | | | | | | | |
| CO4 | Evaluation | n of variou | is character | istics of 1-phase induction motor. | | | | | | | |
| CO5 | Analysis of The various performance parameters of an alternator. | | | | | | | | | | |
| CO6 | Understanding of construction, principle of operation, and performance of various AC mot and generator. | | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| | Fundame | ntals of A | AC machi | ne windings | | | | | | | |
| | Physical a | rrangemer | nt of windi | ngs in stator and cylindrical roto | or of ele | ectrical | | | | | |
| Unit -1 | machine. | Air-gap 1 | MMF distr | ibution with fixed current thro | ugh wi | nding- | 6 | | | | |
| | concentrate | ed and | distributed, | Sinusoidally distributed wind | ling, w | rinding | | | | | |
| | distributior | n factor | | | | | | | | | |
| | Pulsating | and rev | olving mag | gnetic fields | | | | | | | |
| T I ' ' O | Constant n | hagnetic fi | ield, pulsati | ng magnetic field, Magnetic field | produce | d by a | 7 | | | | |
| Unit -2 | single wind | ling - fix | ed current a | and alternating current, Pulsating f | ields pro | oduced | / | | | | |
| | by spatially | y displace | a windings, | urrents) revolving magnetic field | by 120 d | legrees | | | | | |
| | | | | unents), revolving magnetic neid. | | | | | | | |
| | Induction | Machin | es | | 71 | | | | | | |
| | Construction Storting on | on, Types | (squirrei c | Equivalent circuit Phaser Diagra | naracte | ristics, | | | | | |
| Unit-3 | Efficiency | Effect of | uiii Toique. narameter v | equivalent circuit. Filasof Diagra | III, LOSS | riation | 8 | | | | |
| CIIIC-5 | of rotor an | d stator 1 | esistances. | stator voltage, frequency). Metho | ds of st | arting. | 0 | | | | |
| | braking and | d speed co | ontrol for 3- | phase induction motors. | | , | | | | | |
| | 0 | 1 | | | | | | | | | |
| | Single-nha | se induct | ion motors | | | | | | | | |
| | Double rev | olving fi | eld theory. | equivalent circuit. determination | of parar | neters. | | | | | |
| Unit-4 | Split-phase | starting r | nethods and | applications | or para | | 5 | | | | |
| | | 0 | | | | | | | | | |
| | Synchron | Synchronous machines | | | | | | | | | |
| | Constructio | onal featur | es. cylindri | cal rotor synchronous machine - g | enerated | EMF. | | | | | |
| | equivalent | circuit and | l phasor dia | gram, armature reaction, synchrono | ous impe | dance. | | | | | |
| Unit -5 | voltage reg | ulation. C | perating ch | aracteristics of synchronous machine | ines, V-o | curves. | 10 | | | | |
| | Salient pol | e machin | e - two rea | ction theory, analysis of phasor d | iagram, | power | | | | | |
| | angle chara | acteristics | Parallel op | peration of alternators - synchroniz | ation an | id load | | | | | |
| | division. | | | | | | | | | | |
| | Total Hou | rs | | | | | 36 | | | | |

Text/References:

- A. E. Fitzgerald and C. Kingsley, "Electric Machinery", McGraw Hill Education, 2013.
 M. G. Say, "Performance and design of AC machines", CBS Publishers, 2002.
- 3. P. S. Bimbhra, "Electrical Machinery", Khanna Publishers, 2011.
- 4. I. J. Nagrath and D. P. Kothari, "Electric Machines", McGraw Hill Education, 2010.
- 5. A. S. Langsdorf, "Alternating current machines", McGraw Hill Education, 1984.
- 6. P. C. Sen, "Principles of Electric Machines and Power Electronics", John Wiley & Sons, 2007.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|------------|---|---|----------------|----------------------------------|------------------|---------------|---------|--|--|--|--|--|
| Course:- 1 | Bachelor of Techn | ology (Electr | ical Enginee | ring) | | | | | | | | |
| Semes | ter Fourth | Subje | ct Title | Introduction to E Energy Sour | lectrical ces | Code | TEE 402 | | | | | |
| Course | e Components | Cre | dits | Contract Hours | L | Т | Р | | | | | |
| Core | Course (CC) | 0 | 3 | Contact Hours | 03 | 01 | 00 | | | | | |
| Examin | ation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | | |
| Course O | bjectives | • | | | | | | | | | | |
| CO1 A | pply knowledge of | India's powe | er scenario, p | ower system structu | re and rela | ited agencies | S. | | | | | |
| CO2 A | cquire the knowled | lge of therma | l power plant | - | | | | | | | | |
| CO3 U | nderstanding the w | | | | | | | | | | | |
| CO4 U | nderstanding the w | | | | | | | | | | | |
| CO5 U | tilization of turbine | es and workin | ig of hydro p | ower plant | | | | | | | | |
| CO6 U | nderstand the econ | nderstand the economic aspects of power system operation | | | | | | | | | | |
| Unit No. | Content Hours | | | | | | | | | | | |
| | Introduction: Electric energy demand and growth in India. electric energy sources. | | | | | | | | | | | |
| Unit -1 | Thermal Power | Plant: Site S | Selection, Co | al Handling Plant, P | ulverising | Plant, Ash | 8 | | | | | |
| | Handling Plant, | General Lay | out and Oper | ation of Plant, Deta | ailed Desci | ription and | 0 | | | | | |
| | Use of Different | Parts. | 1 | 11 10 | | | | | | | | |
| | Nuclear Power | Plant: Site S | election, Gen | eral Layout and Ope | eration of H | Plant, Brief | | | | | | |
| Unit -2 | meterials control | l of puologra | s of reactors | lont Disposal of pr | al, lissile | and lertile | 8 | | | | | |
| | shielding. | | eactors, C00 | iant, Disposar of in | icical wasi | e materiai, | | | | | | |
| | Hydro Electric | Plants: Cl | assifications, | Location and site | e selection | , Detailed | | | | | | |
| II:4 2 | description of va | arious compo | nents, Gener | al Layout and Oper | ation of Pl | ants, Brief | o | | | | | |
| Unit -3 | description of I | mpulse, Rea | ction, Kapla | n and Francis turb | oines, Adv | antages & | 8 | | | | | |
| | Disadvantages, I | Pumped Stora | ige Plants, H | ydro-Potential in Ind | dia | | | | | | | |
| | Diesel and Gas | Turbine Pla | nts: Advanta | iges and Disadvanta | ages of Die | esel Plants, | | | | | | |
| Unit -4 | Application, Die | Application, Diesel Plant Equipment, Layout, Changing Role of Diesel Plant. | | | | | | | | | | |
| | Operational principle of gas turbine plant & its efficiency, fuels, Open and closed- | | | | | | | | | | | |
| | Economics of | Conomics of Power Generation: Energy Requirements Maximum Demand | | | | | | | | | | |
| | Types of Load | Load Curve | Load Durati | igy Requirements, | istor Rase | Load and | | | | | | |
| Unit -5 | Peak Load Plant | s Types of T | ariff Hydro | Thermal Coordinati | ion Incren | nental Fuel | 6 | | | | | |
| | Cost, Economic | Dispatch | ,, | | ien, meren | | | | | | | |
| | Total Hours | • | | | | | 36 | | | | | |

Text Books

- Deshpande, M.V., Power Plant Engineering, Tata McGraw Hill (2004).
 Soni, Gupta &Bhatnagar, A text book on Power System Engg., DhanpatRai& Co.
- 3. P.S.R. Murthy, Operation and control of Power System BS Publications, Hyderabad.
- 4. Electrical power Generation, Transmission and Distribution S.N. Singh PHI 2nd Edition, 2009

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|--|--|--|---|--|---|--------------------------------|---------|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | |
| Semester | Fourth | Subject | Title | Signals and Systems | | Code | TEE 403 | | |
| Course C | omponents | Credits | | Contract II and | L | Τ | Р | | |
| Core Cou | rse (CC) | 03 | | Contact Hours | 02 | 01 | 00 | | |
| Examinat | ion Duration | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | |
| (Hrs) | | 03 | 00 | | 25 | 25 | 50 | | |
| Course O | bjectives | | | | | | | | |
| CO1 | Understanding of | various ty | pes of signa | ls and their characteristics | | | | | |
| CO2 | Analysis of LTI sy | ystem base | ed on their re | esponse for different input signals | | | | | |
| CO3 | Implement Laplace transformation for signals analysis | | | | | | | | |
| CO4 | Application of continuous time Fourier Transform | | | | | | | | |
| CO5 | Understanding of | Discrete t | ime Fourier | Transform | | | | | |
| CO6 | Estimation of sam | pling free | quency of g | iven signal. | | | 1 | | |
| Unit No. | No. Content | | | | | | | | |
| Unit -1 | Introduction to signals: Continuous to signals. Elementative rectangular pulse, to Systems: Classific additively and home | gnals and time and o ry Signals triangular cation of s nogeneity, | systems: Si discrete time s: unit step, pulse, trapez systems, Pro Time Invari | gnals, Transformation of the indepe- e signals, Classification of signals unit impulse, sinusoidal, exponen coidal, etc. operties of systems: Causality, Stat ance, time-shift, causality, stability. | ndent va , Proper tial, unit pility, lir | rties of tramp, nearity: | 8 | | |
| Unit -2 | Linear Time Inva Convolution integra sum of Discrete tim | ariant (LT al of Cont ne LTI syst | T) Systems inuous time tems, proper | : Representation of signals in term , Properties of Convolution Integra ties of LTI systems. | ns of im al, Conv | pulses, olution | 6 | | |
| Unit -3 | The Laplace Tran Region of converge Laplace transforms. | asform fo ence for L . Analysis | r continuou aplace trans | stime signals and systems: Lapl sforms, Inverse Laplace Transforms terization of LTI systems using Lapl | ace Trar s, Proper ace trans | nsform, rties of sforms. | 8 | | |
| Unit -4 | it -4 Fourier Analysis of Continuous/Discrete time signals: Exponential form and Trigonometric form of Fourier series, Fourier symmetry. Fourier integral and Fourier transform. Transform of common functions and periodic wave forms. Properties of Fourier Transform. Representation of a periodic signals using Fourier transform. | | | | | | | | |
| Unit-5 | Sampling Theorem Aliasing and its effe | and its in ects, Reco | nplications. | Spectra of sampled signals. Samples signals. | ing tech | niques, | 6 | | |
| | Total Hours | | | | | | 36 | | |

- 1. A. V. Oppenheim, A. S. Willsky and S. H. Nawab, "Signals and systems", Prentice Hall India, 1997.
- 2. B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2009.
- 3. S. Haykin and B. V. Veen, "Signals and Systems", John Wiley and Sons, 2007.
- 4. M. J. Robert "Fundamentals of Signals and Systems", McGraw Hill Education, 2007.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|--|---|--|--|---|------------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | Fourth | Subject | Title | Mathematics – III (Probability and Statistics) | | Code | TMA 401 | | | | |
| Course Com | ponents | Credits | | | L | Т | P | | | | |
| Basic Science (BSC) | e Course | 04 | | Contact Hours | 03 | 01 | 00 | | | | |
| Examination | n | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (H | (rs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Objectives | | | | | | | | | | | |
| CO 1 Understand basics of probability | | | | | | | | | | | |
| Understand basics of multinomial distribution | | | | | | | | | | | |
| CO2 | Understa | nd probab | ility distribu | ition | | | | | | | |
| CO3 | Understa | nd bivaria | te distribution | on | | | | | | | |
| CO4 | Understa | nd basics | of statistics | | | | | | | | |
| CO5 | Understand basics of applied statistics | | | | | | | | | | |
| Unit No. | Content | | | | | | | | | | |
| Unit -1 | Probability variables, approxima sums of Variables, Inequality | y spaces, Independ ation to th independ Moment | conditiona ent random e binomial c ent random s, Variance | l probability, independence; Dis variables, the multinomial distrib listribution, infinite sequences of E variables; Expectation of Disc of a sum, Correlation coefficient | screte ra ution, P Bernoulli crete Ra t, Cheby | andom Poisson i trials, andom yshev's | 8 | | | | |
| Unit -2 | Continuou Continuou densities, r | us Probal s random normal, ex | bility Distri variables ponential a | butions and their properties, distribution nd gamma densities. | function | ns and | 10 | | | | |
| Unit -3 | Bivariate Bivariate conditiona | Distribut distribution distribution | ions ons and thei s, Bayes' rule | r properties, distribution of sums e. | and que | otients, | 8 | | | | |
| Unit -4 | Basic Statistics Measures of Central tendency: Moments, skewness and Kurtosis - Probability distributions: Binomial, Poisson and Normal - evaluation of statistical parameters for these three distributions. Correlation and regression – Rank correlation. | | | | | | | | | | |
| Unit -5 | Applied S Curve fitti parabolas single prop difference | tatistics ng by the and more portion, di of standa | method of le general cur fference of p rd deviation | ast squares- fitting of straight lines, rves. Test of significance: Large s proportions, single mean, difference s. | second sample t e of mean | degree est for ns, and | 8 | | | | |
| | 10111101 | *1.0 | | | | | 74 | | | | |

- 1. E. Kreyszig, "Advanced Engineering Mathematics", John Wiley & Sons, 2006.
- 2. P. G. Hoel, S. C. Port and C. J. Stone, "Introduction to Probability Theory", Universal Book Stall, 2003.
- 3. S. Ross, "A First Course in Probability", Pearson Education India, 2002.
- 4. W. Feller, "An Introduction to Probability Theory and its Applications", Vol. 1, Wiley, 1968.
- 5. N.P. Bali and M. Goyal, "A text book of Engineering Mathematics", Laxmi Publications, 2010.
- 6. B.S. Grewal, "Higher Engineering Mathematics", Khanna Publishers, 2000.
- 7. T. Veerarajan, "Engineering Mathematics", Tata McGraw-Hill, New Delhi, 2010.

| | | | ELECTI | RICAL ENGI | NEERING DEPARTMENT | [| | | | | |
|--|---|------------------|---------------|-----------------|---------------------------------|---------------|-----------|------------------|--|--|--|
| Course: | Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | |
| Semeste | e r | Fourth | Subject Ti | itle | Digital Electronics Lab | | Code | PEE 453 | | | |
| Course | Compone | nts | Credits | | | L | T | Р | | | |
| Core Course (CC) | | 01 | | Contact Hours | 00 | 00 | 02 | | | | |
| Examination Duration | | | Theory | Practical | | CWA | MSE | ESE | | | |
| (Hrs) | | | 00 | 03 | weightage: Evaluation | 25 | 25 | 50 | | | |
| Course | Objectiv | es | | | | | | | | | |
| CO 1 Able to explain the basic logic operations of NOT, AND, OR, NAND, NOR, and XOR. | | | | | | | | | | | |
| CO2 | Able to interpret logic functions, circuits, truth tables, and Boolean algebra expressions. | | | | | | | | | | |
| CO3 Able to understand the basic electronics of logic circuits and be able to use integrated circuit packages. | | | | | | iit packages. | | | | | |
| CO4 | Able to | model, anal | yze, and tes | t a sequential | digital circuit | | | | | | |
| Experin | Experiment No. Name of the Experiment | | | | | | | | | | |
| 1 | | To verify | the truth tab | ole of basic lo | gic gates | | | | | | |
| 2 | | To realize | e basic gates | from univers | al gates | | | | | | |
| 3 | | To verify | the Consens | sus Theorem (| (Boolean algebra functions) | using uni | versal di | igital IC Gates. | | | |
| 4 | | To design | and test a h | alf/full adder | circuit using digital IC gates | | | | | | |
| 5 | | To design | and test a h | alf/full subtra | ctor circuit using IC gates. | | | | | | |
| 6 | | To design Map | i, implemen | t and test the | function F(A,B,C,D)=m(1,3 | ,5,7,9,15 | 5)+d(4,6, | ,12,13) using K- | | | |
| 7. | | To design | 2-bit comp | arator using lo | ogic gates | | | | | | |
| 8 | | To design | binary to G | ray code con | verter | | | | | | |
| 9 To design, implement and test half/full adder functions using a multiplexer. | | | | | | | | | | | |
| 10 To design, implement and test half/full subtractor function | | | | | /full subtractor functions usir | ng a mult | tiplexer. | | | | |
| 11 To design and test RS and D flip flo | | | | | ops using logic gates. | | | | | | |
| 12 | | To design | and test JK | and T flip flo | ops using logic gates. | | | | | | |
| 13 | | To design | and test a r | nod-3 synchro | onous counter | | | | | | |
| 14 | | To design | and test an | asynchronous | s/ripple counter | | | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--|-----------|---|----------------|------------------------|---------------|-------------|--------------|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | |
| Sen | nester | Fourth | Subje | ct Title | Electrical Machir | nes- II Lab | Code | PEE 451 | | |
| Course Components | | | Cre | dits | | L | Т | Р | | |
| Core Course (CC) | | C |)1 | Contact Hours | 00 | 00 | 02 | | | |
| Fran | ination Du | ration | Theory | Practical | WEIGHTAGE | CWA | MSE | ESE | | |
| Exam | (Hrs) | ranon | 00 | 03 | EVALUATION | 25 | 25 | 50 | | |
| Course | Course Objectives | | | | | | | | | |
| CO 1 | CO 1 Understand the working of 3-phase induction motor and its applications. | | | | | | | | | |
| CO2 | CO2 Understand the working of 1-phase induction motor and its applications | | | | | | | | | |
| CO3 | CO3 Understand and Verify the various operating curves on the induction machines. | | | | | | | | | |
| CO4 | CO4 Analyse the operating difference between the induction and synchronous machine | | | | | | | | | |
| CO5 | Verify and | d Analyse | the output cl | naracteristics | of 3-phase synchron | nous machin | e | | | |
| | | | | | | | | | | |
| Fynaria | nont No | Name of | f the Experi | mont | | | | | | |
| | | To Perfo | Perform no load test on a 3-phase induction motor | | | | | | | |
| 2 | | To perfe | o perform block rotor test on 3 phase induction motor | | | | | | | |
| 2 | | To perfe | orm Load test | on a 3-phase | induction motor | /1 | | | | |
| 4 | | To perfe | orm no load t | est on 1 phas | e induction motor | | | | | |
| 5 | | To perfo | orm block rot | or test on 1 p | hase induction moto | or. | | | | |
| 6 | | To perfo | orm load test | on 1-phase in | nduction motor | | | | | |
| 7 | | To perfo | orm the synch | ronization of | f an alternator with i | nfinite bus c | or parallel | operation of | | |
| | | two alter | rnator. | | | | | | | |
| 8 To study the starters of 3-phase induction motors | | | | | | | | | | |
| 9 To perform the speed control of 3-phase induction motor by freq | | | | | | otor by frequ | ency varia | tion method. | | |
| 10 | | To perfo | orm open circ | uit test on 3 | phase alternator | | | | | |
| 11To perform short circuit test on 3 phase alternator. | | | | | | | | | | |
| 12 | | To perfo | orm load test | on 3-phase a | lternator | | | | | |
| 13 | | To draw | V-curves of | synchronous | motor. | | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|---|-------------------------|------------------|--|-------------------------------|------------|------------|--------------|--|--|--|
| Course:- | Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | |
| Seme | ester | Fourth | Subje | ct Title | Electrical Measuremen | t Lab | Code | PEE 452 | | | |
| Cour | se Compo | onents | Credits | | | L | Т | Р | | | |
| Cor | e Course | (CC) | 0 | 1 | Contact Hours | 00 | 00 | 02 | | | |
| Exami | ination D | uration | Theory | Practical | Weightage: Evaluation | CWA | MSE | ESE | | | |
| | (Hrs) | | 00 | 03 | freightage. Erataation | 25 | 25 | 50 | | | |
| Course | Course Objectives | | | | | | | | | | |
| CO 1 | Ability to analysis | perform ex | periments to | determine va | rious types of errors in mea | suremen | its and pe | erform error | | | |
| CO2 | Familiarit | ty with vari | ous measurir | ig instrument | s used to detect electrical q | uantities | | | | | |
| CO3 | CO3 To use AC and DC bridges to measure unknown resistance, inductance and capacitance. | | | | | | | | | | |
| CO4 Develop an understanding of need of calibration and to calibrate various electrical instruments. | | | | | | | ents. | | | | |
| | | - | | | | | | | | | |
| Experim | ent No. | Name of t | he Experime | ent and a second s | | | | | | | |
| 1 | | To calibra ammeter. | te AC voltm | eter and AC a | ammeter using standard AC | C voltme | ter and s | tandard AC | | | |
| 2 | | To measu | re the Quality | y factor and i | nductance of the coil using | Maxwe | l's bridg | je. | | | |
| 3 | | To measu | re the Quality | y factor and i | nductance of the coil using | Hay's b | ridge. | | | | |
| 4 | | To measur | re high value | of AC curren | nt by a low range AC amme | eter and (| Current 7 | Transformer | | | |
| 5 | | To measu | re high val | ue of AC v | oltage by a low range A | C voltr | neter an | d Potential | | | |
| 6 | | Transform To measur | re nower usi | og Current Tr | ansformer (CT) and Potent | ial Tran | sformer | (PT) | | | |
| 7 | | Calibratio | n of digital e | nergy meter i | using wattmeter method. | | | (11). | | | |
| 8 | | Calibratio | n of digital E | Energy meter | using Voltmeter/Ammeter | method | | | | | |
| 9 | | To determ | nine the unk | nown capacit | tance and dissipation factor | or of the | unknow | n capacitor | | | |
| using Schering Bridge | | | | | | | L | | | | |
| 10 | | To determ | nine the unknown | nown capacit | ance and dissipation facto | or of the | unknow | n capacitor | | | |
| 11 | | To measure (RL) load | re the power | factor in a s | ingle phase AC circuit wit | h the res | istive an | d inductive | | | |
| 12 | | To analyz | e the improv | ement of pow | ver factor of RL network th | rough ca | pacitor. | | | | |

| | | ELECTRIC | AL ENGINE | ERING DEPARTN | MENT | | | | |
|---|---|---------------|-----------------|--|---------------------|---------|---------|--|--|
| Course:- Bac | chelor of Techno | ology (Electr | rical Enginee | ring) | | | | | |
| Semester Fourth | | Subject Title | | Career Skills (Verbal+ Log Reasoning | - II gical g) | Code | XCS 401 | | |
| Course C | omponents | Cre | edits | | L | Т | Р | | |
| Career Skills (CK) | | C |)1 | Contact Hours | 02 | 00 | 00 | | |
| Examinati | on Duration | Theory | Practical | WEICHTACE | CWA | MSE | ESE | | |
| Examination (H | Irs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | |
| Course Objectives | | | | | | | | | |
| CO 1 To c | develop inter per | rsonal skills | and be an eff | ective goal oriented | team play | er. | | | |
| CO2 To c | develop professi | onals with id | lealistic, prac | tical and moral valu | es. | | | | |
| CO3 To c | develop commu | nication and | problem solv | ing skills | | | | | |
| 101 | re-engineer attitu | ide and unde | erstand its inf | luence on benavior | | | | | |
| | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | |
| Unit 1. | Functional Gra | ammar: Part | s of speech, a | urticles, parallel con | struction, s | subject | 08 | | |
| Unit 2. | 2. Logical Reasoning : Blood relation, puzzle test, syllogism, classification, seating/placing arrangements, | | | | | | | | |
| Unit 3. Logical Reasoning: ranking and comparison, sequential order and things, selection based on conditions, data interpretation | | | | | | | 06 | | |
| Unit 4. | Building Vocal | oulary: Anal | logy, Para jur | nbles, antonyms and | l synonym | s. | 08 | | |
| , | Total | | | | | | 28 | | |

References Readings

For Verbal Section:

Spoken English for India by R.K.Bansal and J.B. Harrison- Orient Longman A practical English Grammar by Thomson and Martinet-Oxford University Press Professional Communication by MaltiAggarwal English grammar, composition and correspondence by M.A.Pink and A.E.Thomas –S.Chand and Sons.Word Power by Blum Rosen-Cambridge University Press A Dictionary of Modern Usage-Oxford University Press

For Aptitude Section:

Quantitative aptitude by R.S Agarwal Verbal and Non Verbal Reasoning by R.S Agarwal All books of puzzles to puzzle to puzzle you by Shakuntala Devi. Question Bank on the practice exercise (Created for internal use)

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|---|--|--|---|----------------------------------|---|---------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | Fifth | Subject | Title | Power Systems - I | | Code | TEE 501 | | | |
| Course C | omponents | Credits | | Contract Hours | L | Т | P | | | |
| Core Cou | rse (CC) | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examinat | ion | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration | (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course O | bjectives | | | | | | | | | |
| CO 1 | Analys | is of vario | ous types of | supply systems | | | | | | |
| CO2 | Estima | tion of va | rious param | eters of transmission line | | | | | | |
| CO3 | Understanding of corona phenomenon and its effects | | | | | | | | | |
| CO4 | Mechanical designing of overhead transmission lines | | | | | | | | | |
| CO5 | Estima | tion of th | e performan | ce of overhead line insulator | | | | | | |
| CO6 | Assess | ment of th | ne various po | erformance parameters of undergro | und cab | le | | | | |
| Unit No. | Contents | | | | | | | | | |
| Unit -1 | supply Sy system and Transmiss effect, Kel | their con sion Line vin's law, | ngle line Di nparison, ch s: Configura Proximity e | agram of Power system, Differen oice of transmission voltage ations, types of conductors, resista effect | ance of | of supply line, skin | 6 | | | |
| Unit -2 | Over Hea single pha Representa Ferranti ef | d Trans use, three ation and fect, Surge | nission Lin phase, sing performance impedance | es: Calculation of inductance ar gle circuit and double circuit tra- e of short, medium and long tra- e loading. | nd capac ansmissi ansmissi | citance of on lines, ion lines, | 8 | | | |
| Unit -3 | Corona a potential g interference | nd Interf radient, co e. Electro | Terence: Phorona loss, for a loss of a loss | enomenon of corona, corona for factors affecting corona, methods of ectromagnetic interference with co | mation, of reduct mmunic | calculation ing corona cation lines | 8 | | | |
| Unit -4 | Mechanic tension, ef | al Design fects of w | of transmind and ice l | ission line: Catenary curve, calc oading, sag template, vibration dat | ulation npers | of sag & | 6 | | | |
| Unit-5 | tension, effects of wind and ice loading, sag template, vibration dampers Overhead line Insulators: Type of insulators and their applications, potential distribution over a string of insulators, methods of equalizing the potential, string efficiency Insulated cables: Type of cables and their construction, dielectric stress, grading of cables, insulation resistance, capacitance of single phase and three phase cables, dielectric loss heating of cables | | | | | | | | | |
| | Total Hou | irs | | | | | 36 | | | |

1. J. Grainger and W. D. Stevenson, "Power System Analysis", McGraw Hill Education, 1994.

2. O. I. Elgerd, "Electric Energy Systems Theory", McGraw Hill Education, 1995.

3. A. R. Bergen and V. Vittal, "Power System Analysis", Pearson Education Inc., 1999.

4. D. P. Kothari and I. J. Nagrath, "Modern Power System Analysis", McGraw Hill Education, 2003.

5. B. M. Weedy, B. J. Cory, N. Jenkins, J. Ekanayake and G. Strbac, "Electric Power Systems", Wiley, 2012.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|---|---|--|---|--|---|----------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | r Fifth Subject Title Control Systems Code | | | | | | | | | |
| Course C | omponents | Credits | | | L | Τ | Р | | | |
| Core Cou | rse (CC) | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examinat | tion | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration | (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Objectives: After successful completion of this course, students will be able to | | | | | | | | | | |
| CO 1 Understand the fundamentals of control systems and to Estimate the transfer function model of physical systems | | | | | | | | | | |
| CO2 Apply block diagram and signal flow analysis for simplification of feedback control system | | | | | | | | | | |
| | Determine | the time on | agrains. | domain responses of first and see | and and | or avatama to | aton and | | | |
| CO3 | sinusoidal | and to som | e extent, rar | np) inputs. | 0110-010 | er systems to | step and | | | |
| CO4 | Determine | the (absolu | te) stability | of a closed-loop control system | | | | | | |
| CO5 | Apply root | -locus and f | frequency re | sponse techniques to analyze and | design c | ontrol systems | 3 | | | |
| CO6 | Understan | d and Deve | lop state sp | ace model of physical systems | 0 | 2 | | | | |
| Unit No. | Content | | | | | | | | | |
| Unit -1 Control System Concepts: Basic elements in control systems, Open and closed loop systems, mathematical modelling and representation of physical systems and analogous systems, Transfer Function, block diagram reduction techniques, signal flow graphs, and Meson's gain formula. | | | | | | | 8 | | | |
| Unit -2 | Time Resp Standard to feedback c inputs, Tin Steady stat | oonse Analy est signals. ontrol syste ne domain sj e errors and | v sis Time respo ems, Transie pecification error consta | nse of first order systems, Charac ent response of second order syste s, Initial and final value theorem. S ants, Performance Indices, P, PI and | eteristics ems for teady stand d PID co | equation of standard test ate response, ntrol modes. | 10 | | | |
| Unit -3 | Concept o Introductio Output Sta Relative St | f Stability A n to stabili bility, Zero ability anal | Analysis. ity, Necessa Input Stabi ysis, Root-I | ary condition for stability (Boun lity), Characteristics equation, Rou Locus technique concept, construct | ded-Inpu 1th-Hurv ion of re | ut Bounded- witz Criteria, pot loci. | 6 | | | |
| Unit -4 | Relative Stability analysis, Root-Locus technique concept, construction of root loci. Frequency-response analysis Introduction to frequency response, Correlation between frequency domain and time domain specifications, Polar plots, Bode plots, Nyquist stability criterion. Gain and Phase margin, Closed-loop frequency response of a second order system, Frequency Domain Performance Specifications. Compensation techniques: Lag, lead, and lag-lead compensator. | | | | | | | | | |
| Unit -5 | Concept of systems, st observabili | state varial ate transien ty. | oles, State s t matrix, sol | pace representation of continuous ution of state equation, Concepts of | linear ti of contro | me invariant ollability and | 4 | | | |
| | Total Hou | irs | | | | | 36 | | | |
| L | L | | | | | | 1 | | | |

- 1. M. Gopal, "Control Systems: Principles and Design", McGraw Hill Education, 1997.
- 2. B. C. Kuo, "Automatic Control System", Prentice Hall, 1995.
- 3. K. Ogata, "Modern Control Engineering", Prentice Hall, 1991.
- 4. I. J. Nagrath and M. Gopal, "Control Systems Engineering", New Age International, 2009

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|---|--|--|---|-------------------------------|----------------------------|---------|--|--|--|
| Course:- E | Bachelor of T | echnolog | y (Electrica | l Engineering) | | | | | | |
| Semester | Fifth | Subject | Title | Microprocessors | | Code | TEE 503 | | | |
| Course Co | mponents | Credits | | | L | Τ | Р | | | |
| Core Cour | se (CC) | 03 | 1 | Contact Hours | 03 | 00 | 00 | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| Duration (| (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course Objectives | | | | | | | | | | |
| CO 1 Understanding of microprocessor 8085 and 8086 architecture and its operations. | | | | | | | | | | |
| CO2 | Acquiring | the knowl | edge of vari | ous instruction sets of 8085 and 80 | 86. | | | | | |
| CO3 | Developme | nt of mici | roprocessor | programming. | | | | | | |
| CO4 | Acquiring | the knowl | edge of inte | rfacing with data transfer devices. | | | | | | |
| CO5 | Developme | nt of inter | facing with | timing devices. | | | | | | |
| CO6 | Develop the | e underst | anding to w | ork on projects based on embedded | d systen | 1. | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Introduction to Microprocessor:Evolution of microprocessors, Architectural advancements of microprocessors, single-chip microcomputers, large and small computers, microprocessor applications.Pin diagram, hardware model and internal architecture of 8085 microprocessor, registers, Address/data bus Demultiplexing, Status Signals and the control signals, Interrupts & their types | | | | | | | | | |
| Unit -2 | Addressing sets: Data tr Machine co Timing diag | modes, A ransfer grou ntrol grou gram and y | Assembly la oup, Arithmo p. various mac | anguage programming using vario etic group, Logical group, Branch, hine cycles. | ous instr Stack, L | ruction O and | 9 | | | |
| Unit -3 | 16-bit Micr Architecture Physical add | coprocess e, register dress, mer | ors (8086): organizatio nory segme | n, bus interface unit, execution un ntation, addressing modes, Instruct | it, pin d ion set. | iagram, | 7 | | | |
| Unit -4 | Interfacing (Data Transfer) with Microprocessor:Data Transfer Schemes: Introduction, handshaking signals, Types of transmission,I/O interfacing- Peripheral mapped I/O and memory mapped I/O, 8255 (PPI), SerialData transfer (USART 8251), memory interfacing, 8257 (DMA), programmableinterrupt Controller (8259). | | | | | | | | | |
| Unit -5 | Interfacing Timer/ Co applications | of Microunter (8 1. Introduc | oprocessor 253/8254): tion to DAC | with Timing Devices: Programm Introduction, modes, Interfacing C & ADC, ADC & DAC Interfacing | mable In ng of g (0808, | nterval 8253, 0809). | 6 | | | |
| | Total Hour | s | | | | | 36 | | | |

- 1. M. A.Mazidi, J. G. Mazidi and R. D. McKinlay, "The8051Microcontroller and Embedded Systems: Using Assembly and C", Pearson Education, 2007.
- 2. K. J. Ayala, "8051 Microcontroller", Delmar Cengage Learning, 2004.
- 3. R. Kamal, "Embedded System", McGraw Hill Education, 2009.
- **4.** R. S. Gaonkar, ", Microprocessor Architecture: Programming and Applications with the 8085", Penram International Publishing, 1996
- 5. D. V. Hall, "Microprocessors & Interfacing", McGraw Hill Higher Education, 1991.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|--|---|---|---|--|--|---|--|--|--|
| Course:- Bachelor of Technology | | | | | | | | | | |
| Se | emester | Fifth | Subje | ect Title | Disaster Manag | gement | Code | UCE 501 | | |
| Ca | ourse Comp | onents | Cr | redits | Contact Hours | L | Τ | Р | | |
| (| Core Course | (CC) | | 02 | Contact Hours | 02 | 00 | 00 | | |
| Exami | nation Dura | tion (Hrs) | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | |
| Launt | | (1115) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | |
| Cours | e Objective | S | | | | | | | | |
| CO 1 | Demonstr | ate a critical | l understan | ding of key | concepts in disaster ris | sk reduction | and hum | anitarian | | |
| CO2 | response | issues and | ahallangaa | origing from | the nerves between no | radiam of da | volonmo | nt and disasters | | |
| 02 | Recognize Respond t | o disaster riv | sk reductio | ansing from | and disasters in an effe | radigili of de | ne and si | int and disasters | | |
| CO3 | manner. | | | | | | | | | |
| CO4 | Critically of | evaluate dis | aster risk r | eduction and | humanitarian respons | e policy and | practice | from multiple | | |
| 04 | perspective | es | | | | | | | | |
| CO5 | Develop a | n understand | ling of star | ndards of hur | nanitarian response an | d practical r | elevance | in specific | | |
| | types of di | sasters and o | the strengt | the and wook | nassas of disastar man | agomont on | roachas | planning and | | |
| CO6 | programm | ing in their | home cour | ntrv | nesses of disaster man | lagement app | noaches, | plaining and | | |
| | programm | ing in their | | hi y | | | | | | |
| Unit N | o. Conte | nt | | | | | | Hours | | |
| Unit -1 | Introduction, Definitions and Classification: Concepts and definitions - Disaster, Hazard, Vulnerability, Resilience, Risks Natural disasters: Cloud bursts, earth quakes, Tsunami, snow, avalanches, landslides, forest fires, diversion of river routes (ex. Kosi river), Floods, Drought, Cyclones, volcanic hazards/ disasters (Mud volcanoes): causes | | | | | | | s, si ss s, n 10 il r | | |
| Unit -2 | explosionsUnit 2: Inter-relationship between Disasters and Development: Factors affecting vulnerabilities, differential impacts, impacts of development projects such as dams, embankments, changes in land use etc., climate change adaption, relevance of indigenous knowledge, appropriate technology and local resources, sustainable development and its role in disaster mitigation, roles and responsibilities of community, panchayat raj institutions/urban local bodies, state, centre and other stake holders in disaster mitigation. | | | | | | | g s, of e 06 of e | | |
| Unit -3 | Unit 3 Post maps, land u (IEC), awaren Emerg immed Post D disaste aspect | : Disaster M disaster sta predictabilit se zoning, at disaster res ness. ency Stage: liate relief, a disaster stage r mitigation s, environme | Vlanageme age): Pre-d ty/forecastin nd prepare istant hous Rescue transsessment e-Rehabilit h: Politica ental aspec | ent (Pre-disa isaster stage ing and "war dness throug the construction atom for sea surveys the atom and rea atom and rea and admin ts. | ster stage, Emergence (preparedness): Prep ming. Preparing disast h information education on, population reduction arch & operation at nat construction of disaste istrative aspects, soc | ey stage and paring hazard for and common and common on in vulnerational & reginstrain or affected arrial aspects, | l zonation ness plan nunication able area onal leve eas; urba economi | n s, n s, 10 l, n c | | |

| Unit -4 | Disaster Management Laws and Policies in India: Environmental legislations related to disaster management in India: Disaster Management Act. 2005; Environmental policies &programmes in India- Institutions & natural centers for disaster mitigation: National Disaster Management Authority (NDMA): structure and functional responsibilities, National Disaster Response Force (NDRF): Role and responsibilities, National Institute of Disaster Management (NIDM): Role and responsibilities. | 10 |
|---------|---|-----|
| | Case studies: Natural and Man-made disasters in India A. Natural disasters in India with special reference to Uttarakhand | |
| | 1. Earth quakes: Uttarkashi (1991), Kutch (2001), Sikkim (2011) | |
| | 2. Cloud Buists. Ottal Kashi (2012) 3. Landslides along Himalayan and other regions: Malpa (Pithoragarh) (1998) | |
| | Varunavrat Hill landslide at Uttarkashi (2003) | |
| | 4. Floods: Orissa floods (2011) | |
| | 5. Tsunami : Indian Ocean earth quake and Tsunami (2004) | |
| | 6. Cyclones: Thane (2011) | |
| | 7. Droughts: Karnataka (2011) | |
| | 8. Snow Avalanche | 0.5 |
| Unit-5 | B. Man-induced disasters in India: | 06 |
| | 1. Forest fires: Forest fires in Uttarakhand, 2004, 2012 and deforestation | |
| | 3 Mining Chasnala(Bihar) mining disaster 1975 | |
| | 4. Oil spills: Mumbai oil spill, 2010. | |
| | 5. Nuclear disaster accidents: Narora atomic power station, Blandshahar (1993); | |
| | Kalpakkam atomic power station (2002); Kota Atomic power station, Rajasthan (1995) | |
| | C. Disasters relevant to the area specific to the discipline of the students. | |
| | Lectures) | |
| | Mock shows: Mock shows will be organized and conducted by expert agencies tor | |
| | understanding the vulnerability of areas in and around campus along with adopting the | |
| | prevenuve measures. | |

Text Books:

- 1. K.J. Anandha Kumar, AjinderWalia, Shekher Chaturvedi, India Disaster Report, 2011, National Institute of Disaster Management, June, 2012
- 2. R.B.Singh (Ed) Environmental Geography, Heritage Publishers New Delhi, 1990
- 3. Savinder Singh Environmental Geography, PrayagPustakBhawan, 1997
- 4. Kates, B.I& White, G.F The Environment as Hazards, oxford, New York, 1978
- 5. R.B. Singh (Ed) Disaster Management, Rawat Publication, New Delhi, 2000
- 6. H.K. Gupta (Ed) Disaster Management, Universiters Press, India, 2003

Refrences:

- 1. R,B. Singh, Space Technology for Disaster Mitigation in India (INCED), University of Tokyo, 1994
- 2. Dr. Satender, Disaster Management in Hills, Concept Publishing Co., New Delhi, 2000
- 3. A.S. Arya Action Plan For Earthquake, Disaster, Mitigation in V.K. Sharma (Ed) Disaster Management IIPA Publication New Delhi, 1994
- 4. R.K. Bhandani An overview on Natural & Man-made Disaster & their Reduction ,CSIR, New Delhi
- 5. M.C. Gupta. Manuals on Natural Disaster management in India, National Centre for Disaster Management, IIPA, New Delhi, 2001

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|--|------------------------|--|---------------|-------------------------|-------------|-------------|---------|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | |
| Sem | ester | Fifth | Subje | ct Title | Power System | - I Lab | Code | PEE 551 | | |
| Cou | rse Comp | onents | Credits | | | L | Т | Р | | |
| Co | re Course | (CC) | 01 | | Contact Hours | 00 | 00 | 02 | | |
| Fram | ination D | uration | Theory | Practical | WEICHTACE | CWA | MSE | ESE | | |
| Lxam | (Hrs) | uraiion | 00 | 03 | EVALUATION 25 25 | | | 50 | | |
| Course | Objectiv | es | | | | | | | | |
| CO 1 | CO 1 Understanding of mechanical and electrical design of a transmission line via industrial visit. | | | | | | | | | |
| CO2 | Knowle | dge of sour | ces and load | simulation. | | | | | | |
| CO3 | CO3 Evaluation of parameters of a transmission line. | | | | | | | | | |
| 04 | Underst | | bertormance | of transmissi | on nne under fault c | | | | | |
| | | | | | | | | | | |
| Experin | ient No. | Name of t | he Experime | ent | | | | | | |
| 1 | | Visit to a | Local Substa | tion or a Ger | erating Plant. | | | | | |
| 2 | | To obtain | obtain the transient response of an RLC circuit with its damping frequency and | | | | | | | |
| 3 | | To determ | determine the parameters of equivalent circuit of transformer from OC SC test data | | | | | | | |
| | | using MA | TLAB. | za thraa nhaa | a source and load us | ing SIMIT | NV | | | |
| 4 | | 10 sillula Measurem | he and analyz | and reactive | powers using SIMI | | | | | |
| 5 | | a) Optima | l dispatch ne | glecting Loss | powers using Shire | | | | | |
| 0 | | b) Optima | l dispatch in | cluding Loss | es | | | | | |
| 7 | | To calcula | te ABCD pa | rameters for | Medium line using | MATLAB. | | | | |
| 8 | | To calcula | ate ABCD pa | rameters for | long line network M | IATLAB. | | | | |
| 9 | | To determ medium li | iine voltage a ne model. | and power at | the sending end and | to regulate | the voltage | using | | |
| 10 To determine line performance when loaded at receiving end. | | | | | | | | | | |
| 11 | | To obtain | the effect of | sudden short | -circuit on a synchro | onous gener | ator output | • | | |
| 12 | | Step respo | onse of rotor | angle and gen | nerator frequency of | a Synchron | ous Machi | ne. | | |

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|---|--------------|----------------|------------------|------------------------|---------------|---------------|----------------|--|--|--|
| Course: | - Bachelo | r of Techno | ology (ELEC | CTRICAL EN | GINERING) | | | | | | |
| Sem | ester | Fifth | Subje | ct Title | Control System | ms Lab | Code | PEE 552 | | | |
| Cou | rse Comp | onents | Cre | edits | Contact Hours | L | Т | P | | | |
| Co | re Course | (CC) | |)1 | Contact Hours | 00 | 00 | 02 | | | |
| Exam | ination D | uration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | (Hrs) | | 00 | 03 | EVALUATION | 25 | 25 | 50 | | | |
| Course | Objectiv | es | | | | | | | | | |
| CO 1 | Underst | and the ope | en and closed | l loop respon | se of first and/or sec | ond order s | ystems. | | | | |
| CO2 | Study an | nd Analyse | speed contro | ol of various t | ypes of electric mot | ors in open | loop and/or | r closed loop. | | | |
| CO3 | Study an | nd Underst | and the fund | amentals of c | control systems and | effect of sta | ndard test | signals on | | | |
| 005 | unity fee | edback and | to study the | time response | e of physical system | s using MA | TLAB | | | | |
| CO4 | Design various compensators and Analyse the stability of given systems using conventional | | | | | | | | | | |
| | techniqu | es (Bode Pl | ot/Root Loc | us/Nyquist/Re | outh-Hurwitz) using | S MATLAB | | | | | |
| | | | | | | | | | | | |
| Experin | nent No. | Name of t | he Experime | ent | | | | | | | |
| Experir | ments on l | Hardware | kits/panels | | | | | | | | |
| 1 | | To study t | ime response | e of a first/sec | cond order system | | | | | | |
| 2 | | To study a | a first/second | order system | using PID controll | er | | | | | |
| 3 | | To study | the charact | eristics of d | ligital Proportiona | l + Integra | l + Deriva | ative control | | | |
| | | action on | the simulat | ed second of | rder process. | | | | | | |
| 4 To carry out the open loop speed control of BLDC motor using IPM. | | | | | | | | | | | |
| 5 | 5 To carry out the closed loop speed PI control of BLDC motor using IPM | | | | | | 1 | | | | |
| 6 | | To exami | ine the oper | ation of con | veyor control syste | em using P | LC. | | | | |
| 7 | | To carry | out the spee | ed control of | AC motor using I | PLC. | | | | | |
| 8 | | To study s | speed torque | characteristic | c of AC servomotor | | | | | | |
| 9 | | To study s | speed control | of stepper m | otor using stepper n | notor contro | oller | | | | |
| 10 | | To study t | he speed cor | trol of variou | is motors (AC/Stepp | per/DC) usin | ng micropro | ocessor | | | |
| Experir | nents usiı | ng MATLA | B/SIMULI | NK | · • • • | · | <u> </u> | | | | |
| | | To obtain | the followin | g using MAT | LAB | | | | | | |
| 11 | | I. Pole, ze | ro, gain valu | es from a giv | en transfer function | | | | | | |
| 11 | | II. Transfe | er function m | odel from po | le, zero, gain values | | | | | | |
| | | III. Pole, z | zero plot of a | transfer func | tion | | | | | | |
| 12 | | To reduce | linear system | ns, block diag | gram using series, p | arallel and f | eedback co | onfiguration | | | |
| 12 | | by using c | commands in | MATLAB. | | | | | | | |
| 13 | | Determina | ation of step | & impulse rea | sponse for a first and | d second or | der unity fe | edback | | | |
| | | system. | | - | | | | | | | |
| 14 | | To Study | the effects of | P, PD, PI, P | ID controllers on the | e response o | of a given (t | first/second | | | |
| order) system and determine the time response specifications. | | | | | | | | | | | |
| 15 | 15 To draw the Bode plot and determine the frequency domain specifications of a given | | | | | | | | | | |
| system. | | | | | | | | | | | |
| 16 | | To draw t | he Root locu | s and study th | ne stability of a give | n system. | • | 1 1 | | | |
| 17 | | To draw t | he Nyquist p | lot of a given | system and determine | ne the Gain | margin an | d phase | | | |
| 10 | | margin. | . 1 .1. | 1 · · · | | 1 | | | | | |
| 18 | | To execut | e stability an | alysis using H | Kouth- Hurwitz met | nod. | | | | | |
| 19 | | To design | a lag, lead a | nd lead – lag | compensator and ob | otain the cha | aracteristics | 5. | | | |

-- Two innovative experiments can be given by the concerned faculty in-charge. **Note:** minimum of any 10 experiments to be performed.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|--------------|--|---|---------------|--------------------------|---------------------------------|------------|-----------------------------|--|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | | |
| Semester | | Fifth | Subject Title | | Microprocessor L | .ab | Code | PEE 553 | | | |
| Cour | se Compon | ents | Cre | edits | | L | Т | Р | | | |
| Cor | e Course (O | CC) | (|)1 | Contact Hours | 00 | 00 | 02 | | | |
| Examination Dur | | ration | Theory | Practical | WEIGHTAGE: FVALUATION | CW A | MSE | ESE | | | |
| ~ | | | 00 | 03 | LVILLOIIION | 25 | 25 | 50 | | | |
| Course | e Objectives | 5 | 00051 | 1 ' | 1.000 | <u> </u> | | 1 . | | | |
| COT | Assessme | ent of the | e 8085 base | ed microproc | essor system and 8086 | $\frac{1}{2}$ and $\frac{1}{2}$ | J86A bas | ed microprocessor system | | | |
| CO2 | order. | and run | a program | for finding o | ut the largest/smallest | numbe | r and for | arranging in ascending | | | |
| CO3 | Develop a | and run a | a program | for multiplic | ation/division and con | version | of temp | erature from 0F to 0C and | | | |
| CO4 | Develop i | nterfaci | ing of 8085 | / 8086 with | various devices. | | | | | | |
| | | | | | | | | | | | |
| Experi | ment No. | Name | of the Exp | eriment | | | | | | | |
| | | A. Stu | idy Experi | ments | | | | | | | |
| 1. | | 1. To study 8085 based microprocessor system | | | | | | | | | |
| | | 2. 1 3 T | o study 800 | so and solo. | A based microprocesso | or syste | m | | | | |
| | | B. Pro | o study i ch ogramming | based Exp | eriments (anv four) | | | | | | |
| | | 1. T | o develop | and run a pro | ogram for finding out t | he large | est/smalle | est number from a given set | | | |
| | | 0 | of numbers. | | | | | | | | |
| | | 2. T | To develop and run a program for arranging in ascending/descending order of a set of | | | | | | | | |
| 2. | | п 3 т | numbers To perform multiplication/division of given numbers | | | | | | | | |
| | | 4. T | o perform | conversion c | of temperature from 0F | to 0C a | and vice- | versa | | | |
| | | 5. T | o perform | computation | of square root of a giv | en nun | nber | | | | |
| | | 6. T | 6. To perform floating point mathematical operations (addition, subtraction, multiplication | | | | | | | | |
| | | a | nd division |) | | | | | | | |
| | | Interf | acing base | d Experime | nts (any four) | 0061 | 1 . | | | | |
| | | 1. 1 2 T | o perform | interfacing o | f RAM chip to 8085/8 | 086 bas | sed syster | n | | | |
| | | 2. 1 3 T | o perform | interfacing o | f DMA controller | | | | | | |
| 3 | | 3. 1 4 т | o perform | interfacing o | f PDI | | | | | | |
| 5. | | 5. T | o perform | interfacing o | f HART/USART | | | | | | |
| | | 6. T | o perform | microproces | sor-based stepper moto | or onera | tion thro | ugh 8085 kit | | | |
| | | 7. T | o perform | microproces | sor-based traffic light | control | | | | | |
| | | 8. T | To perform microprocessor-based temperature control of hot water. | | | | | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|---------------|----------------|---|------------|------|---------|--|--|--|--|
| Course:- Ba | chelor of Techno | ology (Electr | ical Enginee | ring) | | | | | | | |
| Semester Fifth | | Subject Title | | Career Skills - III (Verbal+ Logical Reasoning) | | Code | XCS 501 | | | | |
| Course (| Components | Credits | | ~ | L | Т | Р | | | | |
| Career | Skills (CK) | 02 | | Contact Hours | 02 | 00 | 00 | | | | |
| E | ton Druggtion | Theory | Practical | WEICHTACE. | CWA | MSE | ESE | | | | |
| Examinat (. | Examination Duration (Hrs) | | 00 | <i>EVALUATION</i> | 25 | 25 | 50 | | | | |
| Course Obj | Course Objectives | | | | | | | | | | |
| CO2 To | develop professi | onals with id | ealistic, prac | tical and moral valu | es. | | | | | | |
| CO3 To | develop commu | nication and | problem solv | ing skills | | | | | | | |
| CO4 To | re-engineer attitu | ide and unde | rstand its inf | uence on behavior | | | | | | | |
| | | | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| Unit 1. | Effective Read | ing Skills: R | eading Comp | orehension Purpose | of reading | , | 6 | | | | |
| | skimming and scanning. Tips for improving comprehension skills. (For effective reading skills practice papers on Reading Comprehension will be provided to students) | | | | | | | | | | |
| Unit 2. | Unit 2. Aptitude section: Clocks, Calendar, Profit/loss, Percentage, Average. | | | | | | | | | | |
| Unit 3. | Unit 3. Aptitude Section: Ages, Trains & Boats, Simplification, Ratio & proportion, Partnership | | | | | | | | | | |
| Unit 4. | Critical Reason | ning: Analyz | e logical argu | iments. | | | 6 | | | | |
| | Total | | | | | | | | | | |

References

For Verbal Section:

Spoken English for India by R.K. Bansal and J.B. Harrison- Orient Longman A practical English Grammar by Thomson and Martinet-Oxford University Press Professional Communication by Malti Aggarwal English grammar, composition and correspondence by M.A.Pink and A.E.Thomas –S.Chand and Sons. Word Power by Blum Rosen-Cambridge University Press A Dictionary of Modern Usage-Oxford University Press

For Aptitude Section:

Quantitative aptitude by R.S Agarwal Verbal and Non-Verbal Reasoning by R.S Agarwal All books of puzzles to puzzle to puzzle you by Shakuntala Devi. Question Bank on the practice exercise (Created for internal use)

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|---|--|---------------------|--------------------------|-----------------------------|---------------|---------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Seme | ester Sixth | Subject Title | | Power Electro | onics | Code | TEE 601 | | | | |
| Cour | se Components | Cr | edits | Contract Hours | L | Т | P | | | | |
| Cor | e Course (CC) | (| 03 | Contact Hours | 03 | 00 | 00 | | | | |
| Engradia | tion Duration (IIng) | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| Examina | tion Duration (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course Objectives: After successful completion of this course, students will be able to: | | | | | | | | | | | |
| CO 1 | Understand the basics of various power semiconductor devices and thyristor. | | | | | | | | | | |
| CO2 | Design the line con | nmutated co | nverters and | Analyse their perform | mance. | | | | | | |
| CO3 | Design the single a | nd three-pha | ase inverters | and Assess their perf | ormance. | | | | | | |
| CO4 | Understand and A | nalyse the v | working and | behavior of various ty | pes of chor | oper. | | | | | |
| CO5 | Understand the wo | orking of Cy | clo-converte | rs. | | | | | | | |
| CO6 | Develop skills to be | uild, and tro | ubleshoot po | wer electronics circu | its. | | | | | | |
| | | | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| | Power Semi-Cond | luctor Devi | ces: Review | of power semicond | uctor devic | es (such as | | | | | |
| | power diode, power BJT and power MOSFET), Review of TRIAC, GTO, IGBT. | | | | | | | | | | |
| Unit -1 | Thyristor : I-V characteristics, switching characteristics, turn-on methods, Protection | | | | | | | | | | |
| | and cooling of Thyristor, Gate circuit requirements, Series- parallel operation, | | | | | | | | | | |
| | Commutation Tech | niques. | | | | | | | | | |
| | Line Commutated | Converter | 'S: • Controllad | Destifians). Dhese | Control II | alf and full | | | | | |
| | AC to DC Converters (Phase Controlled Rectifiers): Phase Control, Half and full | | | | | | | | | | |
| Unit -2 | wave-controlled rectifier and their Analysis with different types of loads (R, RL, and RLE). Dual convertees Three phase convertees | | | | | | | | | | |
| | KLE), Dual converters, I free phase converters. | | | | | | | | | | |
| | AC to AC Converters (A.C voltage controllers): Phase control & Integral cycle | | | | | | | | | | |
| | DC to AC C | control, Single-phase voltage controllers (K & RL load). | | | | | | | | | |
| | DC to AC Converters (Inverters): Principle of inverters, Types of inverters, single | | | | | | | | | | |
| Unit -3 | phase half wave and full wave voltage source inverters, Three phase bridge inverters, | | | | | | | | | | |
| | voltage control in single-phase inverters, Current Source inverters, Series inverter, | | | | | | | | | | |
| | DC to DC Convor | tong (Chan | nora). Drinci | nla of channess another | ion contro | 1 stratagias | | | | | |
| | Turnes of chorner of | rens (Chop | hers): Fillici | pie of Chopper Operation | non, contro ve voltogo g | i strategies, | | | | | |
| Unit -4 | chopper of chopper of | mmutatad | aboppor In | sis of Type-A choppe | Poort and 1 | Buck Roost | 6 | | | | |
| | chopper, current commutated chopper. Introduction to Buck, Boost and Buck-Boost | | | | | | | | | | |
| | Frequency Conver | ters (Cvelc | -converter) | Types principle of c | neration S | ingle_nhace | | | | | |
| Unit -5 | to single phase step | un & eten d | lown cyclo c | nverter three phase t | peration. S | se and three | 6 | | | | |
| | nhase to single-nha | se cvclo-co | nverter | sirverter, unce phase | is unce pla | | U | | | | |
| | Total Hours | 50 Cyc10-001 | | | | | 36 | | | | |
| L | | | | | | | 50 | | | | |

Text Books:

- 1. M.H. Rashid, "Power Electronics Circuits, Devices & Applications", PHI.
- 2. Dr. PS. Bimbhra, "Power Electronics" 4/e, Khanna Publishers.
- 3. Ned mohan, Tore. M. Undeland, Williams P. Robbins, "Power Electronics" 3/e Wiley India

Reference Readings:

- Bimal K Bose "Power Electronic and variable frequency drives", Wiley India
 M D Singh, K B Khanchandani," Power Electronics", 2nd edition, Tata McGraw hill publication

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|---|---|----------------------|--|---------------------|----------|-------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester | Sixth Subject Title Power Systems - II Code | | | | | | | | | |
| Course Components | | Credits | | | L | Τ | Р | | | |
| Core Course (CC) | | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration (| (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Ob | jectives | | | | | | | | | |
| CO1 | Application | n of per ur | it represent | ation and reactance diagram in pov | ver syste | em analy | /sis | | | |
| CO2 | Analysis of | unbalanc | ed power sy | stems through symmetrical compo | nent me | thod | | | | |
| CO3 | Design of p | ower syste | em model u | nder symmetrical and unsymmetric | al fault | conditio | ons | | | |
| CO4 | Application | n of power | flow analy | sis in assessment node parameters. | | | | | | |
| CO5 | Examine p | ower syst | em stability | under various conditions. | | | | | | |
| CO6 | Analysis of | symmetri | cal faults. | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Symmetric power in te networks. | agram. agram. al compo rms of sy | ments: Symmetrical c | m Components: Per unit System, I mmetrical Components of unbala components, sequence impedances | anced pl and see | hasors, | 8 | | | |
| Unit -2 | Unsymmetrical faults: Analysis of single line to ground fault, line-to-line fault and Double Line to ground fault on an unloaded generators and power system network 8 with and without fault impedance | | | | | | | | | |
| Unit -3 | Load Flows: Introduction, bus classifications, nodal admittance matrix (YBUS), development of load flow equations, load flow solution using Gauss Siedel and Newton-Raphson method, approximation to N-R method, line flow equations and fast decoupled method | | | | | | | | | |
| | Power Syst | em Stabi | lity: Stabilit | y and Stability limit, Steady state | stability | study, | | | | |
| Unit -4 | derivation of Swing equation, transient stability studies by equal area criterion and step-by-step method. Factors affecting steady state and transient stability and methods of improvement. | | | | | | | | | |
| Unit-5 | Symmetrical fault analysis: Transient in R-L series circuit, calculation of 3-phase short circuit current and reactance of synchronous machine, internal voltage of | | | | | | | | | |
| | loaded macl | hines unde | er transient o | conditions | | - | | | | |
| | Total Hour | s | | | | | 36 | | | |

1. J. Grainger and W. D. Stevenson, "Power System Analysis", McGraw Hill Education, 1994.

2. O. I. Elgerd, "Electric Energy Systems Theory", McGraw Hill Education, 1995.

3. A. R. Bergen and V. Vittal, "Power System Analysis", Pearson Education Inc., 1999.

4. D. P. Kothari and I. J. Nagrath, "Modern Power System Analysis", McGraw Hill Education, 2003.

5. B. M. Weedy, B. J. Cory, N. Jenkins, J. Ekanayake and G. Strbac, "Electric Power Systems", Wiley, 2012.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--|----------------|-----------------|------------------------|-----------|------|---------|--|--|--|
| Course: - Bachelor of Technology (Electrical Engineering) | | | | | | | | | | |
| Semester Sixth | | Subject Title | | Power System Prot | tection | Code | TEE 603 | | | |
| Course | e Components | Cre | dits | Contact Houng | L | Т | Р | | | |
| Core | Course (CC) | 0 | 3 | Contact Hours | 03 | 00 | 00 | | | |
| | | Theory | Practical | WEICHTACE. | CWA | MSE | ESE | | | |
| Examinatio | on Duration (Hrs) | 03 | 00 | <i>EVALUATION</i> | 25 | 25 | 50 | | | |
| Course Obj | Course Objectives | | | | | | | | | |
| CO 1 | Understanding of | the different | components | of a protection syste | ems | | | | | |
| CO2 | Developing conce | pts of various | s types of rela | ays | | | | | | |
| CO3 | Utilization of varie | ous relays in | protection of | f power system com | ponents. | | | | | |
| CO4 | Understanding of | Static relays | | | | | | | | |
| CO5 | Acquiring the kno | wledge of th | e various cha | racteristics of circui | t breaker | | | | | |
| CO6 | Application of var | rious types of | f circuit breal | kers | | | | | | |
| Unit No. | Content Hours | | | | | | | | | |
| Unit -1 | Protection Schemes: Principles and need for protective schemes – nature and causes of faults – types of faults – Fault Clearing Process – Zones of protection and essential4qualities of protection – Protection scheme4 | | | | | | | | | |
| Unit -2 | Electromagnetic Relays: Operating principles of relays – Classification – the Universal relay – Torque equation – R-X diagram – Electromagnetic Relays – Over8current Directional Distance Differential Negative sequence8 | | | | | | | | | |
| Unit -3 | Apparatus Protection: Current transformers and Potential transformers and their applications in protection schemes - Protection of transformer, generator, motor, bus bars and transmission line. | | | | | | | | | |
| Unit -4 | Static Relay: Static relays – Phase, Amplitude Comparators – Classification – Block diagram of Static relays – Over current protection, transformer differential protection, distant protection of transmission lines. | | | | | | | | | |
| Unit -5 | Circuit Breakers: Physics of arcing phenomenon and arc interruption - DC and AC circuit breaking – re-striking voltage and recovery voltage - rate of rise of recovery voltage - resistance switching - current chopping - interruption of capacitive current - Types of circuit breakers – air blast, air break, oil, SF6, MCBs, MCCBs and vacuum circuit breakers – comparison of different circuit breakers – Rating and selection of Circuit breakers. | | | | | | | | | |
| | Total Hours | | | | | | 36 | | | |

TEXT BOOKS/ REFERENCES

1. Sunil S.Rao, 'Switchgear and Protection', Khanna Publishers, New Delhi, 2008.

- 2. B.Rabindranath and N.Chander, 'Power System Protection and Switchgear', New Age International (P) Ltd., First Edition 2011.
- 3. Arun Ingole, 'Switch Gear and Protection' Pearson Education, 2017.
- 4. BadriRam, B.H. Vishwakarma, 'Power System Protection and Switchgear', New Age International Pvt Ltd Publishers, Second Edition 2011.
- 5. Y.G.Paithankar and S.R.Bhide, 'Fundamentals of power system protection', Second Edition, Prentice Hall of India Pvt. Ltd., New Delhi, 2010.

6. C.L.Wadhwa, 'Electrical Power Systems', 6th Edition, New Age International (P) Ltd., 2010

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|---|---|--|----------------|--------------------------|---------------|-------------|----------------|--|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | | |
| Semester Sixth | | Subject Title | | Electronics De | sign Lab | Code | PEE 653 | | | | |
| Co | urse Comp | onents | Cre | dits | | L | Т | Р | | | |
| C | ore Course | (CC) | C |)1 | Contact Hours | 00 | 00 | 02 | | | |
| Б | • • • • | | Theory | Practical | | CWA | MSE | ESE | | | |
| Exa | Examination Duration (Hrs) | | 00 | 03 | WEIGHTAGE: EVALUATION | 25 | 25 | 50 | | | |
| Course | e Objective: | 5 | | | | | 1 | | | | |
| CO 1 | To Becor | ne familiar | with electro | nic laborator | y equipment and D | esign and si | mulate ba | sic electronic | | | |
| 001 | circuits | | | | | | | | | | |
| CO2 | To Desig responses | n various c s. | oscillators an | d implement | them using softwar | e and also | observe the | eir frequency | | | |
| CO3 | To Desig | n various ai | nplifiers like | CE, CC, cor | nmon source FET a | nplifiers and | d impleme | nt them using | | | |
| 005 | software | and also ob | serve their fr | equency resp | onses. | | | | | | |
| CO4 | CO4 To Design and Test PCBs for various electronic circuits | | | | | | | | | | |
| D eres and | | | | | | | | | | | |
| Experi | imeni No. | Name of I | ne Experime | ni** | its on brood boom | l and tast | their men | ring through | | | |
| 1 | | CRO/DSO. | | | | | | | | | |
| 2 | | To design and simulate the basic electronic circuits on ORCAD/PSPICE software and test their working through CRO/DSO. | | | | | | | | | |
| 3 | | To make the layout of center tapped full wave rectifier through ORCAD software | | | | | | | | | |
| 4 | | To make t | he layout of | DC regulated | l power supply throu | ugh ORCAE | software | | | | |
| 5 | | Simulate | Hartley Oscil | lator and det | ermine its frequency | of oscillati | on | | | | |
| 6 | | Simulate | COLPITTS of | scillator and | determine its freque | ency of oscil | lation | | | | |
| 7 | | Simulate ' | Wein Bridge | Oscillator an | d determine its freq | uency of osc | cillation | | | | |
| 8 | | Simulate | RC Phase shi | ft Oscillator | and determine its fro | equency of o | oscillation | | | | |
| 9 | | Simulation | Simulation of half wave and full wave center tapped rectifiers through ORCAD software | | | | | | | | |
| 10 | | Simulation | Simulation of DC regulated power supply through ORCAD software | | | | | | | | |
| 11 | | Simulatio | n of CE amp | lifier using P | SPICE ORCAD sof | tware | | | | | |
| 12 | | Simulation | Simulation of FET amplifier circuit using ORCAD and compute the gain and bandwidth. | | | | | | | | |
| 13 | | To design | the PCB of t | full wave cen | ter tapped rectifier/ | DC regulate | d power su | pply | | | |
| 14 | | To drill so power sup | o drill solder the components on the PCB of full wave center tapped rectifier/DC regulated over supply | | | | | | | | |
| 15 Any experiment as suggested by the Faculty In-charge | | | | | | | | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|--|---|---------------------------------------|-----------------|------------------------|-----------------------|--------------|------------------|--|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | | |
| Semester Sixth | | Sixth | Subjec | ct Title | Power Electror | Power Electronics Lab | | PEE 651 | | | |
| Co | urse Comp | onents | Cre | dits | | L | Т | Р | | | |
| C | ore Course | (CC) | 0 | 1 | Contact Hours | 00 | 00 | 02 | | | |
| Eng | | | Theory | Practical | WEICHTACE. | CWA | MSE | ESE | | | |
| Examination Duration (Hrs) | | | 00 | 03 | EVALUATION | 25 | 25 | 50 | | | |
| Course | Course Outcomes: After successful completion of this course, students will be able to | | | | | | | | | | |
| CO 1 | CO 1 Understand the basic operation (including triggering and/or commutation) of various power semiconductor devices | | | | | | | | | | |
| CO2 | Elucidate | e the behav | vior of variou | s power semi | conductor devices t | hrough their | r characteri | stics. | | | |
| CO3 | Acquire | experience | to design and er conversion | d assemble ci | rcuits with different | t types of po | ower electro | onic devices for | | | |
| | Design at | nd simulate | e the various | power electr | onics circuits for dif | ferent types | s of loads a | and Assess their | | | |
| CO4 | performa | nce and cha | racteristics u | sing MATLA | AB/SIMULINK. | • 1 | | | | | |
| | | | | | | | | | | | |
| Experi | ment No. | Name of the Experiment** | | | | | | | | | |
| 1 | | To study triggering of (i) IGBT (ii) MOSFET (iii) Power Transistor | | | | | | | | | |
| 2 | | To study V-I characteristics of SCR. | | | | | | | | | |
| 3 | | To study the characteristics of TRAIC. | | | | | | | | | |
| 4 | | To study single-phase ac voltage regulator using TRAIC. | | | | | | | | | |
| 5 | | To study triggering circuits for SCR. | | | | | | | | | |
| 6 | | To study t | dy the commutation of SCR. | | | | | | | | |
| 7 | | To study the performance of single phase half controlled bridge rectifier with resistive and inductive loads. | | | | | | | | | |
| 8 | | To study s | single phase f | full controlle | d bridge rectifier wi | th resistive a | and inducti | ve loads. | | | |
| 9 | | To study of | operation of s | step down ch | opper circuit | | | | | | |
| 10 | | To study of | operation of s | step down ch | opper circuit | | | | | | |
| MATI | LAB/SIMU | LINK base | ed experime | nts | | | | | | | |
| 11 | | To simula | te the model | of a step dov | vn chopper | | | | | | |
| 12 | | To simula | te the model | of a step up of | chopper | | | | | | |
| 13 | | MATLAE | 3 simulation | of single pha | se fully controlled | bridge rectif | fier and dra | aw load voltage | | | |
| 1.4 | | and load c | current wavef | form for indu | ctive load. | | 11 1 1 | 1 1 1 | | | |
| 14 | | MAILAE and load c | simulation | of single pha | use full wave ac vol | tage contro | ller and dra | aw load voltage | | | |
| 15 | | To simula | te the 10 hal | f wave invert | ter with R load and | obtain the | correspond | ling waveforms | | | |
| 16 | | To simula | te the 10 ful | l wave inver | ter with R load and | obtain the | correspond | ling waveforms | | | |
| ** | | At least ty | vo innovative | e experiments | s on recent advancer | nents in pov | wer electro | nics to be given | | | |
| | | by the cor | ncerned Facul | lty In-charge | | • | | č | | | |

Note: Any 10 of above experiments are to be conducted

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|----------------------|--|--------------------------------|--------------------------------|--------------------------|----------------|--------------|-----------------|--|--|
| Course:- Bachelor of Technology (ELECTRICAL ENGINERING) | | | | | | | | | | |
| Semester Sixth | | Sixth | Subject Title | | Power System | – II Lab | Code | PEE 652 | | |
| Co | urse Comp | onents | Cre | dits | | L | Т | Р | | |
| C | ore Course | (CC) | 0 | 1 | Contact Hours | 00 | 00 | 02 | | |
| Era | mination T | Juration | Theory | Practical | WEIGHTAGE | CWA | MSE | ESE | | |
| Lxu | (Hrs) | <i>manon</i> | 00 | 03 | EVALUATION | 25 | 25 | 50 | | |
| Course | e Obiective | 5 | | | | | | | | |
| CO 1 | Analysis | of the break | kdown voltag | e of the trans | sformer oil and stud | y the charac | teristics of | MCB | | |
| CO2 | Evaluation and There | on of variou mal relav fo | s operational r time and cu | characteristi rrent setting | cs of the IDMT, Ear | rth fault, Ins | tantaneous | over current | | |
| CO3 | Assessme | ent of the va | arious parame | eter of the tra | nsmission line and | study the LC | G & LLL fa | ault analysis | | |
| | Testing c | of various U | nderground f | ault in cables | s insulator testing | | | | | |
| CO4 | and earth | resistance | testing | | , instantor testing | | | | | |
| Ewnow | mont No | Name of | ho Evnovino | | | | | | | |
| Experi | meni no. | To test the | breakdown y | oltage of the | transformer oil | | | | | |
| 1 | | Find opera | tional charac | teristics of th | e earth fault relay fo | or time and a | nurrent sett | ting | | |
| 2 | | Thermal re | lav | | le curtif fuult foldy fo | | current set | ing. | | |
| 3 | | a. Find operational characteristics of the relay. | | | | | | | | |
| | | b. Determine the current characteristics of a given fuse. | | | | | | | | |
| | | Instantaneous over current relay | | | | | | | | |
| 4 | | a. Study the pick- up current of the relay. b. Study the current vs. time characteristics | | | | | | | | |
| | | IDMT over current relay | | | | | | | | |
| 5 | | Study the operating current & de-operating current of the disc. | | | | | | | | |
| | | Study the time characteristics | | | | | | | | |
| 6 | | To study th | ne characteris | tics of MCB | | | | | | |
| 7 | | To measure | re direct axi | is synchrono | ous reactance of sy | nchronous | machine | and measure | | |
| 8 | | To study th | axis synchro ne single line | to ground fa | ult as practical appli | cation in tra | nsmission | lines | | |
| 9 | | To find our | t | Browna Iu | as praetieur appli | | | | | |
| - | | b. ABCD | b. ABCD parameters. | | | | | | | |
| c. Hyt | | | . Hybrid parameters | | | | | | | |
| 10 | | d. Image | parameter of | a given trans | smission line. | | . 1 | | | |
| 10 | | To study th | three phase | e fault as pra | ctical application in | transmissio | n line. | | | |
| 11 | | To measure | e the earth el | ectrode resis | ance using earth tes | ter | | | | |
| 12 | | To locate f | ault in a cabl | e by murray | loop test | . 400 137 1 | -1- T., 1 · | | | |
| 13 | | and to stud | y the effect of | ge distribution | on across a string of | r 400 kV di | sk insulato | or (Artificial) | | |
| 14 | | Study and | performance | of Differenti | al Relay | | | | | |
| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|---|----------------------|----------------|-----------------|--|-------------|----------|---------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | | |
| Ser | nester | Sixth | Subject Title | | Career Skills - IV (Verbal+ Logical Reasoning) | | Code | XCS 601 | | | | |
| Cor | urse C | omponents | Cre | edits | ~ | L | Т | P | | | | |
| Ca | Career Skills (CK) | | |)1 | Contact Hours | 02 | 00 | 00 | | | | |
| Enge | | on Duration | Theory | Practical | WEIGHTACE. | CWA | MSE | ESE | | | | |
| Exai | ninali (E | on Duration Irs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course Objectives | | | | | | | | | | | | |
| CO 1 | To d | evelop inter pers | sonal skills a | nd be an effe | ctive goal oriented t | eam playe | r. | | | | | |
| CO2 | To d | evelop professio | nals with ide | ealistic, pract | ical and moral value | s. | | | | | | |
| CO3 | To d | evelop commun | ication and p | roblem solvi | ng skills | | | | | | | |
| C04 | 10 re | e-engineer attitu | de and under | stand its influ | lence on benavior | | | | | | | |
| | | | | | | | | | | | | |
| Unit N | <i>o</i> . | Content | | | | | | Hours | | | | |
| Unit 1. | | Building Adva | nced Vocab | ulary | | | | 7 | | | | |
| | | Sentence compl | etion: Single | and double | vocabulary | | | | | | | |
| | | Job Applicatio | n: Personal I | nterviews an | d C.V Writing Esser | ntial parts | - Cover | | | | | |
| | | Letter and the ' | resume'. Typ | es of 'resum | es ' (Curriculum Vil | ae) Chron | ological | | | | | |
| Unit 2 | Init 2 Antitude Section: Number system P& C Probability Log | | | | | | | | | | | |
| Unit 2. Aptitude Section: Time & Work S. L& C. I. Time & Distance Mixture Chi | | | | | | | Chain | 6 | | | | |
| Rule. Pipes & Cisterns | | | | | | | | 0 | | | | |
| Unit 4. | | Advanced Gra | mmar: Spot | ting errors, su | ibject verb agreeme | nt based e | rrors. | 7 | | | | |
| | | Total | | | - | | | | | | | |
| | | | | | | | | 1 | | | | |

References

For Verbal Section:

Spoken English for India by R.K.Bansal and J.B. Harrison- Orient Longman A practical English Grammar by Thomson and Martinet-Oxford University Press Professional Communication by MaltiAggarwal English grammar, composition and correspondence by M.A.Pink and A.E.Thomas –S.Chand and Sons.Word Power by Blum Rosen-Cambridge University Press A Dictionary of Modern Usage-Oxford University Press

For Aptitude Section:

Quantitative aptitude by R.S Agarwal Verbal and Non Verbal Reasoning by R.S Agarwal All books of puzzles to puzzle to puzzle you by Shakuntala Devi. Question Bank on the practice exercise (Created for internal use)

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|---|--|---|---|---|---|---|---------|--|--|--|
| Course: - Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | • | Seventh | Subject T | itle | Electrical Drives | | Code | TEE 701 | | | |
| Course C | Compone | nts | Credits | | | L | Τ | P | | | |
| Core Cou | urse (CC) | | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| | | | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| Examina (Hrs) | ition Dur | ration | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course Objectives: CO1: Understanding of Electrical Drive and its component CO2: Acquiring the knowledge of dynamics of electrical drive CO3: Identifying suitable form of d.c drives system for Industry CO4: Appraise different braking methods and transient analysis of electric motors. CO5: Analysis of transient behavior of DC drives CO6: Appraise the speed and frequency control method of Induction motor and synchronous motor. | | | | | | | | | | | |
| Unit | Content | | | | | | | | | | |
| <i>No</i> . Unit -1 | Electric comport | c Drives | - An Intro | oduction: Ele | ectric drives, adva ectric drives. | ntage of o | electrical drives, | 04 | | | |
| Unit -2 | Dynam Multi-q measure calculat equaliza | ics of elect uadrant op ement, cor ion of tim ation. | rical drives peration, economic on ponents on the and energy | Fundamenta quivalent valu f load torque gy-loss in tra | l torque equation, spaces of drive paranes, nature and class nussensions, nature operations, | peed torque neters, mo sification steady sta | conventions and oment of inertia of load torques, te stability, load | 10 | | | |
| Unit -3 | DC Mo breakin | otor Drives g, transient | -I: DC mot analysis of | or and their pe | erformance (Shunt a ergy losses during t | nd Series r ransient an | notor), starting, alysis. | 6 | | | |
| Unit 4 | breaking, transient analysis of dc motor. Energy losses during transient analysis. DC Motor Drives-II (Uncontrolled rectifier control of DC drive): single phase fully controlled rectifier control of separately excited dc motor, single phase half controlled rectifier control of separately excited dc motor, three phase fully/half controlled of separately excited dc motor, chopper control | | | | | | | 8 | | | |
| Unit-5 | AC Mo inverter frequen | tor Drives control, ro cy generati | • Variable fotor resistant on and sync | requency cont ce control, slip chronous moto | rol from a current s power recovery, v or drives. | ource, curr ariable spe | ent source ed constant | 8 | | | |
| | Total H | lours | | | | | | 36 | | | |

Textbooks:

- 1. Fundamental of Electrical Drives, G.K. Dubey, New Age International Publication.
- 2. Electric Drives, Vedam Subrahmanyam, TMH
- 3. A first course on Electrical Drives, S.K. Pillai, , New Age International Publication.

Reference books:

- 1. Power Electronics MD Singh and K B Khanchandani, Tata McGraw-Hill Publishing company,1998
- 2. Modern Power Electronics and AC Drives by B.K.Bose, PHI.
- 3. Thyristor Control of Electric drives Vedam Subramanyam Tata McGraw Hill Publications.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|---|--|--|--|---|--|---------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | | Seventh | Subject T | itle | Non-Convention Resources | al Energy | Code | TEE 702 | | | |
| Course (| Compone | nts | Credits | | | L | Τ | P | | | |
| Core Cou | urse (CC) | I | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| E | ton Dar | · · · 4 · · · · | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| Examina (Hrs) | (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| CO1: Le CO2: Ac CO3: Uti CO4: As CO5:Un CO6: Un | CO1: Learn and justify the solar thermal applications. CO2: Acquiring the knowledge of Solar Power Generation CO3: Utilization of Geothermal energy for conversion in electrical energy CO4: Assessment of the performance of Fuel cell and MHD CO5:Understanding of wind energy and bio-mass system CO6: Understanding of Maximum Power Point Tracking and load connections | | | | | | | | | | |
| UnitNo | Conten | t | | | | | | Hours | | | |
| Unit -1 | Solar T and per solar th limitation | Thermal En formance, nermal povo ons. | nergy: Sola focusing of ver plants, | r radiation flat collectors and thermal energy | plant collectors and d their materials, ap gy storage for s | l their mate oplications a olar heati | rials, application and performance ng and cooling, | 6 | | | |
| Unit -2 | Photo v panel ar Power I | v oltaic Sys nd Array co Point Track | tem-Solar c onstructions ting (MPPT | ell characteris , Maximizing), Balance of s | tics, solar cell classi solar PV output and system components, | fications, s l Load Mate , Solar PV a | olar cell module, ching, Maximum applications | 8 | | | |
| Unit -3 | Fuel C perform Thermo limitation | Cells: Prince nance and li o-electrica ons | ciple of we imitations. | orking of var nionic Conve | tious types of fue | l cells and | their working, | 6 | | | |
| Unit -4 | Wind E classific and lim | Energy: Wi cation of re itations of e | ind power a otors, conce energy conv | nd its sources entrations and version system | , site selection, cr l augments, wind c ns. | iterion , mo haracteristi | mentum theory, cs. performance | 8 | | | |
| Unit-5 | and limitations of energy conversion systems . Geothermal Energy: Resources of geothermal energy, thermodynamics of geo-thermal energy conversion-electrical conversion, non-electrical conversion, environmental considerations Magneto-hydrodynamics (M H D) : Principle of working of M H D Power plant, performance and limitations. Big magn Augilability of his magn and its conversion theory. | | | | | | | | | | |
| | Total H | Iours | - | | | | | 36 | | | |

Text Books

- 1. B.H Khan, "Non-Conventional Energy Resources" <u>Tata McGraw-Hill Education</u> 2nd edition
- 2. Andrea Gabdel, "A Handbook for Engineers and Economists."
- 3. A. Mani, "Handbook of solar radiation Data for India."
- 4. Peter Auer, "Advances in Energy System and Technology", Vol. I & II Edited by Academic Press
- 5. F.R. the MITTRE, "Wind Machines" by Energy Resources and Environmental Series
- Reference books:
- 1. Frank Kreith , "Solar Energy Hand Book ".
- 2. N. Chermisinogg and Thomes, C. Reign, "Principles and Application of solar Energy"

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|-----------------------------------|-------------------------------------|---|------------------|----------------------|----------------|--------------|-----------------|--|--|--|--|--|
| Course:- Bachelo | r of Techn | ology (ELEC | CTRICAL EN | VGINERING) | | | | | | | | |
| Semester | Seventh | Subject Tit | le | Electrical Drives | Lab | Code | PEE 751 | | | | | |
| Course Compone | nts | Credits | | Contact Hours | L | T | P | | | | | |
| Core Course (CC) |) | 01 | 1 | Connuct Hours | 00 | 00 | 02 | | | | | |
| Examination Dur | ration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | | |
| (Hrs) | 1 | 00 | 03 | EVALUATION | 20 | 30 | 50 | | | | | |
| CO1 | Estimatio | on of the vari | ous character | ristics of DC drive | | | | | | | | |
| CO2 | Assessme | ent of AC dri | ve performan | ce parameters | | | | | | | | |
| CO3 | Analysis | Analysis of dynamic characteristics of DC drive | | | | | | | | | | |
| CO4 | Applicati | on of closed | and open loc | p control | | | | | | | | |
| Experiment No. | Name of | the Experim | ent** | | | | | | | | | |
| Experiments on M | IATLAB/S | IMULINK | | | | | | | | | | |
| 1 | To obtain | the characte | ristic curves of | of DC shunt motor a | and DC serie | es motor. | | | | | | |
| | Speed Co | ntrol of DC 1 | notor fed from | m single phase AC | source | | | | | | | |
| 2 | Armature | voltage cont | rol (using ful | l controlled convert | er) | | | | | | | |
| 2 | Field flux | control | | | | | | | | | | |
| | Armature | resistance co | ontrol. | | | | | | | | | |
| 3 | Obtain the | e slip-torque | and slip-spee | d characteristics of | induction m | otor. | | | | | | |
| 4 | To obtain | the speed-to | orque charact | eristics of an induc | tion motor b | by stator v | oltage control | | | | | |
| | method. | | | | | | | | | | | |
| 5 | To operat | e the given I | DC motor in 2 | -quadrant using cho | opper | | | | | | | |
| 6 | Study of b | oraking in de | motor. | | | | | | | | | |
| | Dynamic | braking | | | | | | | | | | |
| | Plugging | | | | | | | | | | | |
| | Regenerat | tive braking | | | | | | | | | | |
| 7 | Speed Co | ntrol of Induc | ction motor us | sing slip power reco | very method | l (static sc | herbius drive). | | | | | |
| 8 | MATLA | 3 program fo | r speed contr | ol of induction moto | or. | | | | | | | |
| Experiments on H | lardware Pa | inels | | | | | | | | | | |
| 9 | Draw Spe | eed-Torque | Characteristic | es of Separately Ex | cited DC n | notor usin | ig Open Loop | | | | | |
| | Armature | Voltage Var | iation | | | | | | | | | |
| 10 | Draw Spe | ed-Torque (| Characteristic | s of Separately Exe | cited DC m | otor using | g Closed Loop | | | | | |
| | Armature | Voltage Cor | ntrol (P/PI) | | | | | | | | | |
| 11 | Draw Spe | ed-Torque C | haracteristics | of series DC Motor | using Open | Loop Arn | nature Voltage | | | | | |
| | Variation | | | | | | | | | | | |
| 12 | Draw Spe | ed-Torque C | Characteristics | s of series DC Moto | or using Pro | portional/ | Proportional – | | | | | |
| | Integral (I | P/PI) Close L | Loop Control. | | | | | | | | | |
| 13 | Draw Spe | ed-Torque C | haracteristics | of shunt DC Motor | using Open | Loop Arn | nature Voltage | | | | | |
| | Variation | | | | | | | | | | | |
| 14 | Draw Spe | ed-Torque C | Characteristics | s of shunt DC Moto | or using Pro | portional/ | Proportional – | | | | | |
| | Integral (P/PI) Close Loop Control. | | | | | | | | | | | |
| 15 | Draw Spe | ed-Torque C | Characteristics | s of AC motor using | Open Loop | Control | | | | | | |
| 16 | Draw Spe | ed-Torque C | haracteristics | of AC motor using | Proportiona | l/Proporti | onal – Integral | | | | | |
| | (P/PI) Clo | ose Loop Cor | ntrol. | | | | | | | | | |
| 17 | To study | Linear Induc | tion Motor ar | nd perform traction | test on it usi | ng PEC16 | LM01 trainer. | | | | | |

Syllabus

Program Elective Courses

B. Tech (Electrical Engineering) BoS - 2020

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|--|----------------|----------------|--------------------------------|----------------|------------|---------|--|--|--|
| Course:- B | achelor o | of Technol | ogy (Electric | al Engineeri | ng) | | | | | | |
| Semes | ter | Fifth | Subjec | ct Title | Electrical Machine | e Design | Code | TEE 504 | | | |
| Course | e Compo | nents | Cre | dits | Contract Hours | L | Τ | Р | | | |
| Progra | m Electiv | ve – I | 0 | 3 | Contact Hours | 03 | 00 | 00 | | | |
| | | | Theory | Practical | | CWA | MSE | ESE | | | |
| Examinati | on Durat | tion (Hrs) | 02 | 00 | WEIGHIAGE: | 25 | 25 | 50 | | | |
| | | | 05 | 00 | EVALUATION | 23 | 23 | 30 | | | |
| Course Ob | jectives: | After comp | letion of this | course, stud | lents will be able to | • | | | | | |
| CO1 | Study 1 | MMF calcu | lation and the | ermal rating | of various types of e | electrical ma | chines. | | | | |
| CO2 | Design | armature a | nd field syste | ems for D.C. | machines. | | | | | | |
| CO3 | Design | | | | | | | | | | |
| CO4 | Design | | | | | | | | | | |
| CO5 | Design | stator and | rotor of syncl | nronous mac | hines and study thei | r thermal be | havior. | | | | |
| <u>CO6</u> | Unders | | ** | | | | | | | | |
| Unit No. | Conten | at and a second se | | | | | | Hours | | | |
| | Design Considerations: | | | | | | | | | | |
| | Princip. | le of De | sign, Major | considerat | ions in Electrica | Machine | Design, | | | | |
| Unit 1 | Specific | cations and | 1 Standards, | Constraints | of Design, Dimen | sions and R | tating of | o | | | |
| OIIII - I | Inculati | ing material | a Engineen | or Pating of | - Collucting, Kes | l specificatio | neuc allu | 0 | | | |
| | Therm | al consider | s, Space lact | t Dissination | Modes Temperatu | e rise and Fa | 11 Types | | | | |
| | of Cooling (Ventilation), hydrogen cooling | | | | | | | | | | |
| | Design | of Magnet | ic Circuits: | 8 | | | | | | | |
| | Basic p | principles of | of magnetic | circuits, Ma | gnetic circuit calcu | ulations, Iron | n losses, | | | | |
| | Magnet | tic leakage | calculations, | | | | | | | | |
| | Design | of Transfo | rmers: Intro | | | | | | | | |
| Unit – 2 | Equation | on, Volt per | turn of windi | 10 | | | | | | | |
| | of Core | e, Design of | Yoke, Wind | ow and Core | properties, Window | v space factor | r, Design | | | | |
| | of win | dings, Ov | erall dimens | ions, Opera | ting characteristics | s, No load | current, | | | | |
| | Temper | rature rise | in Transfor | rmers, Desi | gn of Tank, Met | hods of co | oling of | | | | |
| | Transfe | ormers. | | | | | | | | | |
| | Design | OI DC Ma | chines | Eald (on anoi | tation anatom) and | Doton Space | fications | | | | |
| | of DC 1 | machine O | struction of r | on choice of | specific electric and | d magnetic | loadings | | | | |
| Unit _ 3 | Choice | of number | of poles I in | pitations of m | ain dimensions (D | and L) Sena | ration of | 7 | | | |
| Omt = 3 | main d | imensions | (D and L) E | Estimation of | ² length of air gan | Design of a | armature | 7 | | | |
| | Design | of Commu | tator and Bru | shes. Design | of Field system of | DC machine | e. Design | | | | |
| | of Inter | poles. | | | | | , 8 | | | | |
| | Design of Three-phase induction motors : General considerations, output equation. | | | | | | | | | | |
| | choice | of specific | electric and | magnetic lo | adings, No. of slot | s in stator a | nd rotor, | | | | |
| Unit – 4 | elimina | tion of ha | rmonic torq | ues, design | of stator and roto | r windings, | leakage | 6 | | | |
| | reactance, equivalent resistance of squirrel cage rotor, magnetizing current, | | | | | | | | | | |
| | tempera | ature rise ar | nd efficiency. | | | | | | | | |
| Unit – 5 | Design | of Alterna | tors: Classifi | ication and th | eir comparison, spe | cific loading | gs, output | 5 | | | |
| | coeffici | ient, main | dimensions, | short circu | ut ratio, eliminatio | on of harm | onics in | | | | |
| | generat | ed EMF, st | ator winding | design. | | | | 25 | | | |
| | Total | Hours | | | | | | 36 | | | |

Text Books:

 Sawhney, A.K., 'A Course in Electrical Machine Design', Dhanpat Rai & Sons, New Delhi, 1984. • M.V.Deshpande "Design and Testing of Electrical Machine Design" Wheeler Publications, 2010.

Reference Books:

- V. Rajni and V.S. Nagarajan, "Electrical Machine Design" 1st ed., Person, 2018.
- A.Shanmuga Sundaram, G.Gangadharan, R.Palani 'Electrical Machine Design Data Book', New Age International Pvt. Ltd., Reprint, 2007.
- R.K.Agarwal "Principles of Electrical Machine Design" Esskay Publications, Delhi, 2002.
- Sen, S.K., 'Principles of Electrical Machine Designs with Computer Programmes', Oxford and IBH Publishing Co. Pvt. Ltd., New Delhi, 1987.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|-----------------------------------|---|--|----------------|--------------------------------------|------------|----------|--------------|--|--|--|--|--|
| Course:- B | Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | nester Fifth Subject Title Electromagnetic waves Code unage Common onte Credite I T | | | | | | | | | | | |
| Course Co | mponents | Credits | | Contact Hours | L | Τ | Р | | | | | |
| Program E | lective – I | 03 | | Comuci mours | 03 | 00 | 00 | | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | | |
| Duration (| Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | | |
| Course Objectives | | | | | | | | | | | | |
| CO 1 | Analyze tra | insmissior | lines and e | estimate voltage and current at any | point of | n transn | nission line | | | | | |
| 001 | for different load conditions. Application of Maxwell Equations | | | | | | | | | | | |
| CO2 | Application | Application of Maxwell Equations | | | | | | | | | | |
| CO3 | Acquiring | the knowl | edge of plai | ne wave | | | | | | | | |
| CO4 | Acquiring | the knowl | edge of the | characteristics of plane wave | | | | | | | | |
| CO5 | Understand | d and anal | yse radiatio | on by antennas. | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | | |
| | Transmissi | ion Lines | | | | | | | | | | |
| | Introduction | n, Concep | t of distribu | ated elements, Equations of voltage | ge and c | urrent, | | | | | | |
| Unit -1 | Standing wa | aves and in | npedance ti | ansformation, Lossless and low-los | ss transn | nission | 8 | | | | | |
| | lines, Power transfer on a transmission line, Analysis of transmission line in terms | | | | | | | | | | | |
| | of admittances, Transmission line calculations with the help of Smith chart, | | | | | | | | | | | |
| | Application | s of transi | mission line | , Impedance matching using transn | nission I | ines. | | | | | | |
| | Maxwell's | Equation | S | tion Dania large of Electrometric | . Carra | 9 a 1 a | | | | | | |
| II:4 0 | Basic quantities of Electromagnetics, Basic laws of Electromagnetics: Gauss's law, | | | | | | | | | | | |
| Unit -2 | Ampere's C | Ircuital la | iw, Faraday | 's law of Electromagnetic inducti | on. Max | well's | 0 | | | | | |
| | equations, | Surface c | narge and | surface current, Boundary condit | ions at | media | | | | | | |
| | Uniform D | ano Wov | 0 | | | | | | | | | |
| | Homogeneo | alle wav | t nd medium | Wave equation for time harmonic | Fields Sc | olution | | | | | | |
| Unit -3 | of the wave | aquation | Uniform n | wave equation for time narmonic i | vo propo | antion | 6 | | | | | |
| | in conduction | ng mediun | Dimoni p | ocity of a wave Power flow and P | overting | vector | | | | | | |
| | Plane Way | es at Med | lia Interfac | | oynting | vector. | | | | | | |
| | Plane wave | in arbitra | v direction | Plane wave at dielectric interface | Reflecti | on and | | | | | | |
| Unit -4 | refraction | of waves | at dielect | ric interface Total internal ref | lection | Wave | 8 | | | | | |
| Chit 4 | polarization | at media | interface | Brewster angle Fields and power | flow at | media | 0 | | | | | |
| | interface L | ossy med | ia interface | Reflection from conducting bou | ndary | meara | | | | | | |
| | Waveguide | es and An | tennas | , | <u></u> | | | | | | | |
| | Parallel p | lane way | veguide:] | Fransverse Electric (TE) mod | le. tran | sverse | | | | | | |
| | Magnetic(T | M) mode, | Cut-off free | quency, Phase velocity and dispersi | on. Tran | sverse | | | | | | |
| T T 1 / P | Electromagnetic (TEM) mode, Analysis of waveguide-general approach | | | | | | | | | | | |
| Unit -5 | Rectangular | Rectangular waveguides. Radiation parameters of antenna. Potential functions | | | | | | | | | | |
| Unit -5 | Solution for | potential | functions, H | Radiations from Hertz dipole, Near | field, Fa | r field, | | | | | | |
| | Total power | r radiated l | by a dipole, | Radiation resistance and radiation r | oattern of | f Hertz | | | | | | |
| | dipole, Hert | tz dipole i | n receiving | mode. | | | | | | | | |
| | Total Hou | rs | | | | | 36 | | | | | |
| | 1 | | | | | | 1 | | | | | |

1. R. K. Shevgaonkar, "Electromagnetic Waves", Tata McGraw Hill, 2005.

2. D. K. Cheng, "Field and Wave Electromagnetics", Addison-Wesley, 1989.

3. M. N.O. Sadiku, "Elements of Electromagnetics", Oxford University Press, 2007.

4. C. A. Balanis, "Advanced Engineering Electromagnetics", John Wiley & Sons, 2012.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|-----------|-----------|--|--|--|--|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester Fifth Subject Title Digital Signal Proce | essing | Code | TEE 506 | | | | | | | | |
| Course Components Credits Contact Hours | L | T | Р | | | | | | | | |
| Program Elective – I 03 | 03 | 01 | 00 | | | | | | | | |
| Examination Theory Practical WEIGHTAGE: | CWA | MSE | ESE | | | | | | | | |
| Duration (Hrs) 03 00 EVALUATION | 25 | 25 | 50 | | | | | | | | |
| Course Objectives | | | | | | | | | | | |
| CO 1 Acquire the knowledge of various types of signals and its character | eristics | | | | | | | | | | |
| CO2 Application of discrete signals using Z-Transform | | | | | | | | | | | |
| CO3 Application of discrete signals using Fourier Transform | | | | | | | | | | | |
| CO4 Realization of FIR and IIR filters | | | | | | | | | | | |
| CO5 Design of FIR and IIR filters | | | | | | | | | | | |
| CO6 Acquire the fundamental knowledge about the different types of d | CO6 Acquire the fundamental knowledge about the different types of digital signal processors | | | | | | | | | | |
| Huid Na Candand | | | TT | | | | | | | | |
| Unit No. Content | nt | | | | | | | | | | |
| Introduction: Classification of systems: Continuous, disc | crete, linear, | causal, | | | | | | | | | |
| stable, dynamic, recursive, time variance; classification of | and discrete energy and power: Mathematical representation of signals: spectral | | | | | | | | | | |
| Unit -1 and discrete, energy and power; Mathematical representation | and discrete, energy and power; Mathematical representation of signals; spectral density; sampling techniques quantization quantization error Nyquist rate | | | | | | | | | | |
| aliasing effect. Digital signal representation | aliasing effect. Digital signal representation. | | | | | | | | | | |
| Discrete time system analysis: Z-transform and its pr | operties inv | verse z- | | | | | | | | | |
| Unit -2 Unit system unity case 2 duales of the pr | transforms: difference equation – Solution by Z-transform frequency response | | | | | | | | | | |
| – Convolution. | | | _ | | | | | | | | |
| Discrete Fourier transform & computation: Fourier tr | ansform of | discrete | | | | | | | | | |
| Init 2 sequence, Discrete Fourier series, DFT properties, ma | sequence, Discrete Fourier series, DFT properties, magnitude and phase | | | | | | | | | | |
| representation, Computation of DFT using FFT algorithm | n, DIT & DI | IF, FFT | 0 | | | | | | | | |
| using radix 2, Butterfly structure. | | | | | | | | | | | |
| Design of digital filters: FIR & IIR filter realization, Di | rect form – | I & II, | | | | | | | | | |
| Parallel & cascade forms. FIR design: Windowing Tec | chniques, Ne | ed and | | | | | | | | | |
| Unit -4 choice of windows, Linear phase characteristics. IIR de | esign: Analo | og filter | 10 | | | | | | | | |
| design, Butterworth and Chebyshev approximations, d | igital desigr | n using | - | | | | | | | | |
| impulse invariant and bilinear transformation, Warping, pre | warping, Fre | equency | | | | | | | | | |
| Uransformation | oturos A J. | Iroquina | | | | | | | | | |
| Unit -5 Digital signal processors: Introduction – Architecture – Fe | Processors | nessing | 4 | | | | | | | | |
| Total Hours | 1100035015. | | 36 | | | | | | | | |

Text Books & Reference Readings:

- 1. John G. Prokias and D.G. manolakis, "Digital Signal Processing: Principles, Algorithms and Applications", PHI, 1997.
- 2. A.V Oppenheim and Schafer, "Discrete time Signal Processing", PHI, 1989.
- 3. S.K. Mitra, 'Digital Signal Processing A Computer Based Approach', Tata McGraw Hill, New Delhi, 2001.
- 4. L.R. Rabiner and B.Gold, "Theory and Applications of digital Signal Processing", PHI, 1992.
- 5. J.R. Johnson, "Introduction to Digital Signal Processing", PHI, 1992.
- 6. D.J. DeFatta, J.G. Lucas and W.S Hodgkiss, "Digital Signal Processing", J Wiley and sons, Singapore, 1988.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|---|--|--|--|---|--|-----------------------|--|--|--|
| Course:- | Bachelo | r of Techn | ology (Electr | rical Enginee | ring Department) | | | | | | |
| Semester | | Third | Subject Tit | le | Electrical Engine Material | ering | Code | TEE 507 | | | |
| Course Co | ompone | nts | Credits | | | L | Τ | Р | | | |
| Core Cour | rse (CC) |) | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examinat | ion Dur | ration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| (Hrs) | | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course C | Dbjectiv | es | | | | | | | | | |
| CO 1 | Assess | different st | ructures of m | aterials | | | | | | | |
| CO2 | Analyz | e performai | nce of materi | als by their d | ifferent properties | | | | | | |
| CO3 | Distinguish between metals, semiconductors and non-metals by different applications | | | | | | | | | | |
| CO4 | Understand the concept of dielectric materials and their properties | | | | | | | | | | |
| CO5 | Identifi | cation of m | agnetic mate | rials by their | classification | | | | | | |
| CO6 | Formulation of different mathematical expressions based on types and properties of material | | | | | | | | | | |
| Unit No. | Conte | ent | | | | | | Hours | | | |
| Unit -1 | Crystal Structure of Materials: Bonds in solids, crystal structure, co-ordination number, atomic packing factor, Miller Indices, Bragg's law and x-ray diffraction, structural Imperfections, crystal growth. Energy bands in solids, classification of materials using energy band | | | | | | | n n, 8 of | | | |
| Unit -2 | Prop semic metal | erties of conducting, s, optical p | Materials: insulating a roperties of s | Properties and super control of super control of the super control of th | and application of ducting materials. | electrical Mechanical | conducting properties of | g, of 6 | | | |
| Unit -3 | Cond factor devel semic current | luctivity in rs affecting oped in conductors, nts, continu | Metals and electrical res current car current carr ity equation, | I semicondu sistance of ma rying condu iers in semic P-N junction | ctor materials: El aterials, thermal con actors, thermoelec conductors, Hall eff a diode, junction tra | ectron theor aductivity of tric effect. fect, Drift an nsistor, FET | y of metal metals, he Types and Diffusion & IGFET. | s, at of 8 n | | | |
| Unit -4 | Dielectric Properties of Materials: Polarization and dielectric constant, dielectric constant of mono-atomic, poly atomic gases and solids, dipolar relaxation, dielectric loss, piezoelectricity, ferroelectric materials. | | | | | | | | | | |
| Unit -5 | Magi Class and F magn | netic Prope ification: D Ferri-magne etic materia | e rties of Mat Piamagnetism Ptism. Magne al | terials: Origi , Para magne tostriction. S | n of permanent mag tism, Ferromagnetis oft and hard magne | gnetic dipole sm, Anti-ferr etic materials | es in matter romagnetist s, permaner | s, n 8 nt | | | |
| | Tota | l Hours | | | | | | 36 | | | |

Text Books:

- 1. A.J. Dekker, "Electrical Engineering Materials", Prentice Hall of India
- 2. R.K. Rajput, "Electrical Engg. Materials", Laxmi Publications.
- 3. C.S. Indulkar & S.Triruvagdan, "An Introduction to Electrical Engg. Materials", S. Chand& Co.
- 4. Solymar, "Electrical Properties of Materials", Oxford University Press.

References:

- 1. Ian P. Hones, "Material Science for Electrical and Electronic Engineering", Oxford University Press.
- 2. Narula, "Material Science", Tata McGraw Hill..

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|---|--|---|--|---|--|---|---------|--|--|--|--|--|
| Course:- E | Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | Sixth Subject Title Industrial Electrical Systems Code | | | | | | | | | | | |
| Course Co | mponents | Credits | | | L | Т | Р | | | | | |
| Program E | lective - II | 03 | | Contact Hours | 03 | 00 | 00 | | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | | |
| Duration (| Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | | |
| Course Ob | jectives | | | | | | | | | | | |
| CO 1 Application of electrical wiring components, such as, Fuse, Cable, MCB, etc. | | | | | | | | | | | | |
| CO2 | Understand | d various o | components | of industrial electrical systems. | | | | | | | | |
| CO3 | Acquiring | the knowle | edge of vari | ous types of wiring and general rul | e and gu | idelines of instat | llation | | | | | |
| CO4 | Application | n of Indust | trial electric | al systems | | | | | | | | |
| CO5 | Application | n of DG sy | stem, UPS | system, Battery banks | | | | | | | | |
| CO6 | Understand | d the use of | of automatic | n in electrical systems. | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | | |
| Unit -1 | Electrical System Components LT system wiring components, selection of cables, wires, switches, distribution box, metering system, Tariff structure, protection components- Fuse, MCB, MCCB, ELCB, inverse current characteristics, symbols, single line diagram (SLD) of a wiring system, Contactor Isolator Relays MPCB Electric shock and Electrical safety practices | | | | | | | | | | | |
| Unit -2 | Residentia Types of reinstallation, protection deciding lig and sizing o | al and Co esidential load calcu levices, ea hting sche of compon | ommercial and comm alation and s arthing syste me and num ents. | Electrical Systems ercial wiring systems, general rus sizing of wire, rating of main switch em calculations, requirements of c aber of lamps, earthing of commercia | lles and a, distrib commerc al instal | guidelines for ution board and ial installation, lation, selection | 8 | | | | | |
| Unit -3 | and sizing of components.Industrial Electrical Systems - IHT connection, industrial substation, Transformer selection, Industrial loads, motors, starting of motors, SLD, Cable and Switchgear selection, Lightning Protection, Earthing design, Power factor correction – kVAR calculations, type of compensation, Introduction to PCC, MCC panels. Specifications of LT Breakers, MCB and other LT panel components.Industrial Electrical Systems II DG Systems, UPS System, Electrical Systems for the elevators, Battery banks, Sizing the | | | | | | | | | | | |
| Unit -4 | Industrial Study of ba control syst automation. Total Hour | Electric sic PLC, 1 em design | al System Role of in a , Panel Met | Automation utomation, advantages of process tering and Introduction to SCADA | automat system | ion, PLC based for distribution | 6 | | | | | |
| | 1014111001 | 3 | | | | | 54 | | | | | |

Text/Reference Books

1. S.L. Uppal and G.C. Garg, "Electrical Wiring, Estimating & Costing", Khanna publishers, 2008.

2. K. B. Raina, "Electrical Design, Estimating & Costing", New age International, 2007.

3. S. Singh and R. D. Singh, "Electrical estimating and costing", Dhanpat Rai and Co., 1997.

4. Web site for IS Standards.

5. H. Joshi, "Residential Commercial and Industrial Systems", McGraw Hill Education, 2008.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|---|--|--|---|--|-----------------------------------|------------------------------|-------------|--|--|--|--|--|
| Course:- Bac | Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | Sixth | Subject | Title | Digital Control Systems | - | Code | TEE 605 | | | | | |
| Course Com | ponents | Credits | | Contact Hours | L | Τ | P | | | | | |
| Program Elec | ctive – II | 03 | | Contact Hours | 03 | 00 | 00 | | | | | |
| Examination | l | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | | |
| Duration (H | rs) | 03 | 00 | | 25 | 25 | 50 | | | | | |
| Course Objectives: Upon successful completion of this course, students will be able to: | | | | | | | | | | | | |
| CO1 | Acquire the fundamental concept of digital control systems | | | | | | | | | | | |
| CO2 | Apply z-t linear dis | Apply z-transform to Analyze stability, transient response and steady state behavior of linear discrete-time systems | | | | | | | | | | |
| CO3 | Analyse | Analyse discrete time systems through state space representation | | | | | | | | | | |
| CO4 | Describe | and Asse | ss the control | ollability and observability of linea | r discret | e-time s | systems. | | | | | |
| CO5 | Analyse | Stability o | f linear disc | crete time systems through pole pla | cement | and state | e observers | | | | | |
| CO6 | Design d | ligital con | ntrol syster | ns using transform techniques a | nd state | -space | methods. | | | | | |
| Unit No. | Content | 0 | · | | | • | Hours | | | | | |
| Unit -1 | Discrete Representation of Continuous SystemsBasics of Digital Control Systems. Discrete representation of continuoussystems. Sample and hold circuit. Mathematical Modelling of sample and holdcircuit. Effects of Sampling and Quantization. Choice of sampling frequency.ZOH equivalent | | | | | | | | | | | |
| Unit -2 | Discrete Transfer system, ti Stability Stability | System Function, ime respon analysis analysis u | Analysis: Mapping finse of discrete of discrete using biline | Z-Transform and Inverse Z-Tra rom s-plane to z-plane, solution o ete time system e time systems: Stability analysis ear transformation. | nsform, f discret s by Jur | Pulse te time ty test. | 08 | | | | | |
| Unit -3 | State Spa State var function a and Eige Observab | ace Appro iable repr and of tran n vectors, pility. | bach for dis esentation, sfer functio Solution o | screte time systems conversion of state variable mod n to canonical state variable model of state difference equations, cont | els to t s, Eigen rollabili | ransfer values ty and | 08 | | | | | |
| Unit -4 | Pole-place feedback, regulator | cement D , Necessar design, D | esign and S y and suffic esign of sta | State Observers: Stability improv ient conditions for arbitrary pole-pl te observer. | ement b acemen | y state t. State | 6 | | | | | |
| Unit -5 | Design of Design of Design of of Discret | f Digital (f Discrete f set point te compen | Control Sys PID Contro tracker. Des sator. | tem oller, Design of discrete state feedb sign of Discrete Observer for LTI S | oack con System. I | troller. Design | 6 | | | | | |
| | Total Ho | ours | | | | | 36 | | | | | |

- 1. K. Ogata, "Digital Control Engineering", Prentice Hall, Englewood Cliffs, 1995.
- 2. M. Gopal, "Digital Control Engineering", Wiley Eastern, 1988.
- 3. B.C. Kuo, "Digital Control System", Holt, Rinehart and Winston, 1980.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|---|---|--|-------------------------|-----------------------------|---------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | Sixth | Subject | Title | Computer Architecture | | Code | TEE 606 | | | | |
| Course Com | ponents | Credits | | Contact Hours | L | Τ | Р | | | | |
| Program Elec | ctive - III | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examination | | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (H | rs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Objec | ctives | | | | | | | | | | |
| CO 1 | Underst | tand the c | oncepts of 1 | nicroprocessors, their principles an | d practi | ces. | | | | | |
| CO2 | Understand the concepts of memory organisation. | | | | | | | | | | |
| CO3 | Write efficient programs in assembly language of the 8086 family of microprocessors. | | | | | | | | | | |
| CO4 | Organiz | ze a mode | rn computer | system and be able to relate it to re | eal exan | nples. | | | | | |
| CO5 | Develop the programs in assembly language for 80286, 80386 and MIPS processors in real and | | | | | | | | | | |
| 001 | protecte | d modes. | 1 1 1 1' | | | | | | | | |
| C06 | Implem | ent embe | dded applic | ations using ATOM processor. | | | | | | | |
| Unit No. | Content | . | | • | | | Hours | | | | |
| Unit -1 | Architecture and function of general computer system, CISC Vs RISC, Data types, Integer Arithmetic - Multiplication, Division, Fixed and Floating-point representation and arithmetic, Control unit operation, Hardware implementation of CPU with Micro instruction, microprogramming, System buses, Multi-bus organization | | | | | | | | | | |
| Unit -2 | Memory System n implemen | organiza nemory, C ntation, M | tion Cache memo emory mana | ory - types and organization, Virtu agement unit, Magnetic Hard disks | al mem , Optica | ory and its l Disks. | 8 | | | | |
| Unit -3 | Input – o Accessing Interrupt Parallel a | output Or g I/O devi Controlle nd serial p | ganization ces, Direct rs, Arbitration cort. Feature | Memory Access and DMA contro on, Multilevel Bus Architecture, es of PCI and PCI Express bus. | ller, Inte Interface | errupts and e circuits - | 8 | | | | |
| Unit -4 | Parallel and serial port. Features of PCI and PCI Express bus. 16 and 32 microprocessors 80x86 Architecture, IA – 32 and IA – 64, Programming model, Concurrent operation of EU and BIU, Real mode addressing, Segmentation, Addressing modes of 80x86, Instruction set of 80x86, I/O addressing in 80x86 | | | | | | | | | | |
| Unit -5 | Pipelining Introduction to pipelining, Instruction level pipelining (ILP), compiler techniques for ILP, Data hazards, Dynamic scheduling, Dependability, Branch cost, Branch 6 Prediction, Influence on instruction set. | | | | | | | | | | |
| | Total H | ours | | | | | 36 | | | | |
| | • | | | | | | • | | | | |

Text/Reference Books

1. V. Carl, G. Zvonko and S. G. Zaky, "Computer organization", McGraw Hill, 1978.

2. B. Brey and C. R. Sarma, "The Intel microprocessors", Pearson Education, 2000.

3. J. L. Hennessy and D. A. Patterson, "Computer Architecture A Quantitative Approach", Morgan Kauffman, 2011.

4. W. Stallings, "Computer organization", PHI, 1987.

5. P. Barry and P. Crowley, "Modern Embedded Computing", Morgan Kaufmann, 2012.

6. N. Mathivanan, "Microprocessors, PC Hardware and Interfacing", Prentice Hall, 2004.

7. Y. C. Lieu and G. A. Gibson, "Microcomputer Systems: The 8086/8088 Family", Prentice Hall India, 1986.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|---|--|---|--------------------------------|------------------------------|---------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Semester | Sixth | Subject | Title | Computational Electromagnetics | | Code | TEE 607 | | | | |
| Course Com | ponents | Credits | | Contact Hours | L | Т | Р | | | | |
| Program Ele | ctive - III | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examination | ı | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (H | rs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Objectives | | | | | | | | | | | |
| CO 1 | CO 1 Understand the basic concepts of Electromagnetics. | | | | | | | | | | |
| CO2 | Computa | ation of c | omputing fi | elds. | | | | | | | |
| CO3 | Applicat | ion of Fi | nite Differen | nce Method | | | | | | | |
| CO4 | Understa | and the ba | isic concept | s Uniqueness and convergence | | | | | | | |
| CO5 | Application of Finite Elements Method | | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| Unit -1 | Introduct Convention Review of Developm Slepian, m | ion onal design of basic ent of He nagnetic D | n methodolo fundamen Imholtz equ Diffusion-tra | by, Computer aided design aspects tals of Electrostatics and Ele nation, energy transformer vectors nsients and time-harmonic. | – Adva ectromag - Poynti | ntages. metics. ng and | 10 | | | | |
| Unit -2 | Analytica Analytical Roth's me | I Method I methods ethod, inte | s of solving f gral method | ield equations, method of separations, method of images of the second second second second second second second | on of var ages. | iables, | 8 | | | | |
| Unit -3 | Finite Dif Finite Dif stability o Uniquenes | ference N fference so of FD so ss and con | fethod (FD schemes, tro lutions, Fir wergence. | M) eatment of irregular boundaries, nite-Difference Time-Domain (FI | accurac DTD) m | cy and nethod- | 8 | | | | |
| Unit -4 | Finite Ele Overview higher ord element co | ement Me of FEM, V er elemen omputatio | thod (FEM Variational a ts, vector elens. |) and Galerkin Methods, shape funct ements, 2D and 3D finite elements, | ions, low efficien | ver and t finite | 8 | | | | |
| | Total Ho | urs | | | | | 34 | | | | |

1. P. P. Silvester and R. L. Ferrari "Finite Element for Electrical Engineers", Cambridge University press, 1996

2. M. N. O. Sadiku, "Numerical Techniques in Electromagnetics", CRC press, 2001.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|--|---|--|------------------------------------|-----------------------------|---------|--|--|--|--|
| Course:- E | Bachelor of T | echnology | v (Electrica | l Engineering) | | | | | | | |
| Semester | Sixth | Subject | Title | High Voltage Engineering | - | Code | TEE 608 | | | | |
| Course Co | mponents | Credits | | | L | Τ | Р | | | | |
| Program E | lective – III | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (| (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Ob | Course Objectives | | | | | | | | | | |
| CO 1 | CO 1 Understand breakdown phenomena in gases, liquid, solid, vacuum and composite dielectrics | | | | | | | | | | |
| CO2 | Elucidate th | e concept | s used for th | ne measurement of high voltages an | nd curre | nts and c | lesign | | | | |
| CO3 | Interpret hi | gh voltage | e testing tec | hniques of Power apparatus and ca | uses of | over vol | tage in | | | | |
| | Power syste | ems. | Jac Inculate | d substations and to know the cond | ents of | inculatic | m | | | | |
| CO4 | coordination. | | | | | | | | | | |
| CO5 | Understan | d Over-vo | ltage pheno | omenon | | | | | | | |
| CO6 | Elucidate t | he concep | ts used for t | he generation of high voltages and | currents | 5. | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| Unit-1 | Break down of: gaseous, | n Phenom liquid, so | lenon: Basi lid, vacuum | c Process of breakdown, breakdown and composite dielectrics | n pheno | menon | 6 | | | | |
| Unit-2 | Generation multiplier c cascade tran | of high- ircuit and ircormer a | test voltag electrostati nd resonant | es: Generation of high DC voltatic generators, generation of high <i>L</i> transformers. | ige by v AC volt | oltage/ age/by | 6 | | | | |
| Unit -3 | Measureme capacitance Generating | e nt of Hig and resis voltmeter. | h Voltage tance poten | and Current: Series Resistance n tial dividers, sphere gap, electrost | nicro-an atic vol | nmeter, tmeter, | 8 | | | | |
| Unit -4 | High Volta impulse and cables, circu and loss fac | ge Testing l power fre uits breake tor. | g: Requiren equency test rs and isola | hent of high voltage test circuit, IS t of transformer, lighting, arrester, h tor; measurement of resistivity, die | specific oushing, lectric co | ations; power onstant | 8 | | | | |
| Unit -5 | Over Volt switching p and substati | age Pher henomence on against | nomenon a on as causes t over voltag | and Insulation Coordination: s of over voltage, protection of tra ge, insulation coordination. | Lightnin | ag and on line | 8 | | | | |
| | Total Hour | s | | | | | 36 | | | | |

- 1. M. S. Naidu and V. Kamaraju, "High Voltage Engineering", McGraw Hill Education, 2013.
- 2. C. L. Wadhwa, "High Voltage Engineering", New Age International Publishers, 2007.
- 3. D. V. Razevig (Translated by Dr. M. P. Chourasia), "High Voltage Engineering Fundamentals", Khanna Publishers, 1993

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--|----------------|----------------|-------------------------|----------------|------------|---------|--|--|--|--|
| Course:- | Bachelor of Techn | ology (Electr | ical Enginee | ring) | | | | | | | |
| Seme | ster Sixth | Subje | ct Title | Optimisation Tec | chniques | Code | TEE 609 | | | | |
| Cours | se Components | Cre | edits | Contact Hours | L | Т | Р | | | | |
| Progra | am Elective - VI | 0 | 13 | Contact Hours | 03 | 00 | 00 | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE:EV | CWA | MSE | ESE | | | | |
| | (Hrs) | 03 | 00 | ALUATION | 25 | 25 | 50 | | | | |
| Course (| Objectives: Upon s | accessful con | npletion of tl | nis course, students w | vill be able t | 0 | | | | | |
| CO1 | Understand the | Concept of | optimizatior | and classification o | f optimizati | ion proble | ems. | | | | |
| CO2 Understand and apply unconstrained optimization theory for continuous problems, | | | | | | | | | | | |
| CO3 | Understand and apply constrained optimization theory for continuous problems | | | | | | | | | | |
| CO4 | Enumerate fundamentals of Dynamic programming | | | | | | | | | | |
| CO5 | Understand and | apply the (| Queuing Mo | del, poison and expo | nential dist | ributions | | | | | |
| CO6 | Use and apply Genetic Algorithm on real applications | | | | | | | | | | |
| Unit | Content | | | | | | | | | | |
| No. | | | | | | | | | | | |
| Unit_1 | Introduction: Ma | thematical Ba | ackground, in | cluding convex sets an | d functions. | Need for | 04 | | | | |
| Unit -1 | constrained metho | ds in solving | constrained j | problems. | | | 04 | | | | |
| | Unconstrained o | ptimization: | Optimality | conditions, Line Sea | rch Method | s, Quasi | 00 | | | | |
| Unit -2 | Newton Methods, | Trust Region | n Methods. C | onjugate Gradient Me | thods. Least | Squares | 08 | | | | |
| | Constrained Ont | imization · () | ntimality Cou | ditions and Duality (| Onvey Prog | ramming | | | | | |
| Unit -3 | Problem. Linear | Programmin | g Problem. | Quadratic Programm | ing. Dual I | Methods. | 08 | | | | |
| | Penalty and Barrie | r Methods, I | nterior Point | Methods. | | | 00 | | | | |
| | Dynamic Progra | mming: Mu | ltistage decis | ion problems, comput | tation proce | dure and | | | | | |
| Unit -4 | case studies. Fun | damentals of | queuing sys | tem, Poisson process, | the birth a | nd death | 08 | | | | |
| | process, special qu | euing metho | ds. | | | | | | | | |
| | Genetic Algorith | ms: Fundan | nentals, basic | c concepts, working | principle, e | ncoding, | | | | | |
| Unit -5 | fitness function, | reproduction. | Genetic mo | odeling: Inheritance of | operator, cro | oss over, | 08 | | | | |
| | inversion & del | A Application | ion operator | , ыtwise operator, | Generationa | i Cycle, | | | | | |
| | | л, Applicatio | Total 1 | Hours | | | 36 | | | | |
| | | | Total I | 10015 | | | 30 | | | | |

Text Books:

- 1. S.S. Rao "Optimisation Theory and Applications", Wiley Eastern Limited, New Delhi. 1991
- 2. Chong, E.K.P.and Zak, S. H.. An Introduction to Optimisation, John Wiley & Sons, N.Y.
- 3. Hadely, G., 'Linear Programming', Addition Wesley, 1962.

Reference Readings :

- 1. Pierre, D.A. 'Optimisation Theory with Applications' John Wiley & Sons, 1969
- 2. Peressimi A.L., Sullivan F.E., Vhl, J.J..Mathematics of Non-linear Programming, Springer – Verlag.
- 3. Fletcher R. Practical methods of Optimisation, John Wiley. 1980

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|---|---|--|---|---|---|-----------------------------------|---------|--|--|
| Course: | - Bache | lor of Tec | hnology (E | lectrical En | gineering) | | | | | |
| Semeste | r | Sixth | Subject Ti | itle | Industrial Instrume | entation | Code | TEE 610 | | |
| Course | Compon | ents | Credits | | | L | T | P | | |
| Program | Elective | e – III | 03 | | Contact Hours | 03 | 00 | 00 | | |
| Framin | ation Di | iration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | |
| (Hrs) | unon Du | iration | 03 | 00 | EVALUATION | 25 | 25 | 50 | | |
| Unit No. | Conten | ıt | | | | | · | Hours | | |
| Unit -1 | Unit -1 MEASUREMENT OF FORCE, TORQUE AND SPEED: Different types of load cells: Hydraulic, Pneumatic, Strain gauge, Magneto-elastic and Piezoelectric load cells - Different methods of torque measurement: Strain gauge, Relative angular twist. Speed measurement: Capacitive tacho, Drag cup type tacho, D.C and A.C tacho generators - Strohoscope | | | | | | | | | |
| Unit -2 | MEASUREMENT OF ACCELERATION, VIBRATION AND DENSITY Accelerometers: LVDT, Piezoelectric, Strain gauge and Variable reluctance type accelerometers - Mechanical type vibration instruments - Seismic instruments as -2 accelerometer – Vibration sensor - Calibration of vibration pickups - Units of density and specific gravity – Baume scale and API scale – Densitometers: Pressure type densitometers, Float type densitometers, Ultrasonic densitometer and gas densitometer. | | | | | | | | | |
| Unit -3 | gas densitometer. MEASUREMENT OF VISCOSITY, HUMIDITY AND MOISTURE Viscosity: Saybolt viscometer - Rotameter type and Torque type viscometers – Consistency Meters – Humidity: Dry and wet bulb psychrometers – Resistive and -3 capacitive type hygrometers – Dew cell – Commercial type dew meter. Moisture: Different methods of moisture measurements –Thermal, Conductivity and Capacitive sensors, Microwave, IR and NMR sensors, Application of moisture measurement - | | | | | | | | | |
| Unit -4 | Moisture measurement in solids. TEMPERATURE MEASUREMENT Definitions and standards – Primary and secondary fixed points – Different types of filled in system thermometers – Sources of errors in filled in systems and their compensation – Bimetallic thermometers – IC sensors – Thermocouples: Laws of thermocouple, Fabrication of industrial thermocouples, Reference junctions compensation, Signal conditioning for thermocouple, Commercial circuits for cold junction compensation, Response of thermocouple, Special techniques for measuring high temperature using thermocouple. | | | | | | | 8 | | |
| Unit – 5 | PRESSU Units of Bourdo element resistive McLeoo hot cath | IRE MEASU f pressure – n tube, Bel ts with LVI e pressure s d gauge, Th node type. | REMENT - Manometer lows, Diaphi DT and strain sensor-Reson hermal condu | s: Different tragms and Ca agms and Ca aguges - Ca ator pressure activity gauge | ypes, Elastic type pres psules - Electrical me pacitive type pressure sensor - Measuremen , lionization gauges, G | sure gauges thods: Elast gauge - Pie t of vacuum Cold cathode | : ic zo i: e type and | 6 | | |
| | Total H | Hours | | | | | | 36 | | |

TEXT BOOKS/REFERENCES

1. Doebelin, E.O. and Manik, D.N., "Measurement systems Application and Design", 6th McGraw-Hill Education Pvt. Ltd, 2011.

- 2. Jones, B.E., "Instrument Technology", Vol.2, Butterworth-Heinemann, International Edition, 2003.
- Liptak, B.G., "Instrumentation Engineers Handbook (Measurement)", CRC Press, 2005. 2. Patranabis, D., "Principles of Industrial Instrumentation", 3rd Edition, McGraw-Hill Education, 2017.
- 4. Eckman D.P., "Industrial Instrumentation", Wiley Eastern Limited, 1990.
- 5. Singh,S.K., "Industrial Instrumentation and Control", Tata Mc-Graw-Hill Education Pvt. Ltd., New Delhi, 2009.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|--|---|--|--|--|---|--|---------|--|--|
| Course: | Master | • of Techn | ology (Con | trol System) | | | | | | |
| Semeste | r | Sixth | Subject T | itle | Special Electrical | Machines | Code | TEE 611 | | |
| Course | Compon | ents | Credits | | | L | Τ | Р | | |
| Program | Elective | e – III | 03 | | Contact Hours | 03 | 00 | 00 | | |
| | | | Theory | Practical | WEIGHTAGE | CWA | MSE | FSF | | |
| Examin | ation Dı | uration | Incory | Tachcai | FVALUATION | СИА | MISE | LSL | | |
| (Hrs) | | | 03 | 00 | | 25 | 25 | 50 | | |
| Unit | Conter | nt | | | | | | Hours | | |
| No. | SUNCHDONOUS DELLICTANCE MOTODS | | | | | | | | | |
| Unit -1 | Unit -1 SYNCHRONOUS RELUCTANCE MOTORS Constructional features – Types – Axial and Radial flux motors – Operating principles – Variable Reluctance Motors – Voltage and Torque Equations – Phasor diagram – performance characteristics – Applications. | | | | | | | | | |
| Unit -2 | STEPPER MOTORS Constructional features – Principle of operation – Variable reluctance motor – Hybrid t -2 motor – Single and multi-stack configurations – Torque equations – Modes of excitation – Characteristics – Drive circuits – Microprocessor control of stepper motors – Closed loop control-Concept of lead angle – Applications | | | | | | | 8 | | |
| Unit -3 | SWITC Linear predicti Rotor p – Appli | CHED RE SRM – Pri ion- Analytoosition sen ications. | CLUCTAN nciple of op tical method sing – Senso | ICE MOTO eration – Tor -Power Con or less operation | RS constructional feque production – Steventers and their control $-$ Characteristics and the contr | eatures – Ro ady state per atrollers – M nd Closed loo | otary and formance ethods of op control | 8 | | |
| Unit -4 | PERM Perman Charact circuit a and the | ANENT Magnuteristics – analysis – Firstical for the second | IAGNET B et materials Permeance EMF and tor rs – Motor c | RUSHLESS – Minor I coefficient -P que equations haracteristics | D.C. MOTORS hysteresis loop and rinciple of operation –Commutation – Pov and control– Applica | recoil line- – Types – wer Converte tions. | Magnetic Magnetic r Circuits | 8 | | |
| Unit – 5 | and their controllers – Motor characteristics and control – Applications. PERMANENT MAGNET SYNCHRONOUS MOTORS Principle of operation – Ideal PMSM – EMF and Torque equations – Armature MMF – Synchronous Reactance – Sine wave motor with practical windings – Phasor diagram – Torque/speed characteristics – Power controllers – Converter Volt-ampere requirements – Applications | | | | | | | | | |
| | Total H | Hours | | | | | | 36 | | |
| L | 1. Ken | jo T., Suga | awara A, <i>St</i> | epping Moto | ors and their Microp | processor Co | ontrol, Cla | arendon | | |

Press, Oxford, 1994
2. Miller T. J. E., *Switched Reluctance Motor and Their Control*, Clarendon Press, Oxford, 1993.

- 3. Miller T. J. E., *Brushless Permanent Magnet and Reluctance Motor Drives*, Clarendon Press, Oxford, 1989.
- 4. B K Bose, *Modern Power Electronics & AC drives*, Pearson, 2002.
- 5. Janardanan E.G, "Special Electrical Machines" Prentice Hall India Learning Private Limited (2014)

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|---|----------------|---------------------------------------|-----------|-----------|------------|--|--|--|--|
| Course:- E | Bachelor of Te | echnology | (Electrical | Engineering) | | | | | | | |
| Semester | Seventh | Subject | Title | Advanced Power Electronics | | Code | TEE 703 | | | | |
| Course Co | mponents | Credits | | | L | Т | Р | | | | |
| Program E | lective - IV | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (| (Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Ob | jectives | | | | | | | | | | |
| CO 1 | Analyse con | trolled red | ctifier circui | ts for various loads and with variou | us types | of filter | s. | | | | |
| CO2 | Understand | l and Ana l | lyse the ope | ration of multiphase converter | | | | | | | |
| CO3 | Understand | l and Ana l | lyse operati | on of Single-phase ac-dc single-s | witch be | oost cor | verter | | | | |
| CO4 | Understand | l and Ana l | lyse operati | on of ac-dc bi-directional boost c | converte | r | | | | | |
| CO5 | Understand | l and Ana l | lyse operati | on of Isolated single-phase ac-dc | fly back | conve | rter | | | | |
| CO6 | Apply the | knowled | ge to desi | gn the advanced power electro | onic cii | cuits f | or various | | | | |
| 000 | applications | 5. | | | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| | Thyristor r | ectifiers | with passiv | ve filtering | | | | | | | |
| Unit -1 | Half-wave thyristor rectifier with RL and RC loads; 1-phase thyristor rectifier with | | | | | | | | | | |
| | L and LC fi | and LC filter; 3-phase thyristor rectifier with L and LC filter; continuous and | | | | | | | | | |
| | discontinuou | is conduct | 10n, 1nput c | urrent wave-shape. | | | | | | | |
| | Multi-Pulse | e convert | er | | 1, 6 | 2 | | | | | |
| Unit -2 | Review of t | ransforme | r phase shi | tting, generation of 6-phase ac vo | oltage fr | om 3- | 07 | | | | |
| | phase ac, 6-pulse converter and 12-pulse converters with inductive loads, steady | | | | | | | | | | |
| | State analysi | s, commu | ingle swite | h boost convortor | | | | | | | |
| Unit_3 | Bariow of d | le de boor | ingle-swill | power circuit of single switch of | n da con | wortor | 06 | | | | |
| Onit -5 | steady state | analysis r | nity nower | factor operation closed-loop contr | ol struct | ure | 00 | | | | |
| | Ac-dc bidir | ectional | hoost conv | erter | of struct | ure. | | | | | |
| | Review of 1 | -phase inv | verter and 3 | -nhase inverter nower circuits of | 1-phase | and 3- | | | | | |
| Unit -4 | phase ac-dc | boost con | verter, stead | v state analysis, operation at leadir | ng, laggi | ng and | 08 | | | | |
| | unity power | factors. R | ectification | and regenerating modes. Phasor dia | igrams, (| closed- | 00 | | | | |
| | loop control structure. | | | | | | | | | | |
| | Isolated sin | gle-phas | e ac-dc flv | back converter | | | | | | | |
| T T 1 / F | Dc-dc flybad | ck convert | er, output v | oltage as a function of duty ratio a | nd trans | former | ormer | | | | |
| Unit -5 | turns ratio. | Power cire | cuit of ac-d | c flyback converter, steady state | analysis | , unity | 08 | | | | |
| | power factor | operatior | n, closed loo | p control structure. | - | 2 | | | | | |
| | Total Hours | | | | | | 36 | | | | |

1. G. De, "Principles of Thyristorised Converters", Oxford & IBH Publishing Co, 1988.

2. J.G. Kassakian, M. F. Schlecht and G. C. Verghese, "Principles of Power Electronics", Addison-Wesley,

1991.

3. L. Umanand, "Power Electronics: Essentials and Applications", Wiley India, 2009.

4. N. Mohan and T. M. Undeland, "Power Electronics: Converters, Applications and Design", John Wiley

& Sons, 2007.

5. R. W. Erickson and D. Maksimovic, "Fundamentals of Power Electronics", Springer Science & Business Media, 2001.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|--|--|--|---|------------------------------------|---|---------|--|--|--|
| Course:- Ba | chelor of T | echnology | v (Electrica | l Engineering) | | | | | | |
| Semester | Seventh | Subject | Title | Electrical and Hybrid Vehicles | | Code | TEE 704 | | | |
| Course Com | ponents | Credits | | Contract Hours | L | Т | Р | | | |
| Program Ele | ctive - IV | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examination | n | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| Duration (H | (rs) | 03 | 00 | | 25 | 25 | 50 | | | |
| Course Obje | ectives | | | | | | | | | |
| CO1 | Understa | nd the mo | dels to desc | ribe hybrid vehicles and their perfe | ormance | | | | | |
| CO2 | Analysis | of Electric | Traction | | | | | | | |
| CO3 | Understand the different possible ways of energy storage. | | | | | | | | | |
| CO4 | Understa | nd the dif | ferent strate | gies related to energy storage syste | ems. | | | | | |
| CO5 | Applicati | on various | s energy ma | nagement schemes. | | | | | | |
| CO6 | Design di | fferent el | ectrical veh | icles | | | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| Unit -1 | Introduction to Hybrid Electric Vehicles : History of hybrid and electric vehicles, social and environmental importance of hybrid and electric vehicles, impact of modern drive-trains on energy supplies. Hybrid Electric Drive-trains: Basic concept of hybrid traction, introduction to various hybrid drive- train topologies, power flow control in hybrid drive-train topologies, fuel efficiency analysis. | | | | | | | | | |
| Unit -2 | Electric Trains Electric Drive-trains: Basic concept of electric traction, introduction to various electric drive- train topologies, power flow control in electric drive-train topologies, fuel efficiency analysis. Electric Propulsion unit: Introduction to electric components used in hybrid and electric vehicles, Configuration and control of DC Motor drives, Configuration and control of Induction Mater drives | | | | | | | | | |
| Unit -3 | Energy S Energy St system. H the interna | torage orage: An ybridizational combustional | alysis of Ba on of differ tion engine | ttery/ fuel cell/ super capacitor/ fly ent energy storage devices. Match (ICE), sizing of drive system | wheel-ling the e | based energy storage electric machine and | 6 | | | |
| Unit -4 | Energy M Energy M and electr different strategies. | Ianageme anagemen ic vehicles energy n | ent Strategi at Strategies s, classifica nanagement | es : Introduction to energy managemetion of different energy managemet strategies, implementation issue | ent strat ent strate es of e | egies used in hybrid egies, comparison of energy management | 8 | | | |
| Unit -5 | Case Stud Design of | lies: a Hybrid | Electric Vel | hicle (HEV), Design of a Battery E | lectric V | Vehicle (BEV). | 4 | | | |
| | Total Ho | urs | | | | | 36 | | | |

- 1. C. Mi, M. A. Masrur and D. W. Gao, "Hybrid Electric Vehicles: Principles and Applications with Practical Perspectives", John Wiley & Sons, 2011.
- 2. S. Onori, L. Serrao and G. Rizzoni, "Hybrid Electric Vehicles: Energy Management Strategies", Springer, 2015.
- 3. M. Ehsani, Y. Gao, S. E. Gay and A. Emadi, "Modern Electric, Hybrid Electric, and Fuel Cell Vehicles: Fundamentals, Theory, and Design", CRC Press, 2004.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|--|---------------------|-----------------|-------------------------|---------------|------------|---------|--|--|--|--|
| Course:- | Bachelor of Techno | ology (Electr | ical Enginee | ring) | | | | | | | |
| Seme | ester Seventh | Subje | ct Title | Modern Contro | 1 System | Code | TEE 705 | | | | |
| Cour | se Components | Cre | dits | Contract House | L | Т | Р | | | | |
| Progra | am Elective – IV | 0 | 13 | Contact Hours | 03 | 00 | 00 | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course | Objectives | | | | | | | | | | |
| CO 1 | Understand the co | oncept of stat | e space appro | bach. | | | | | | | |
| CO2 Analyze discrete data control system | | | | | | | | | | | |
| CO3 | Estimate stability | and Design s | state observer | s and controllers | | | | | | | |
| CO4 | Formulate optima | l control pro | blem and its s | solution. | | | | | | | |
| CO5 | Apply different ad | aptive contro | ol system tech | niques and optimization | ation. | | | | | | |
| CO6 | Analyze different nonlinear control schemes | | | | | | | | | | |
| | · | | | | | | | | | | |
| Unit | Content | | | | | | | | | | |
| No. | | | | | | | | | | | |
| | State Space analysis: introduction, state space representation of continuous linear | | | | | | | | | | |
| Unit -1 | time invariant syst | tem, transfer | function and | d state variables, st | ate transitio | n matrix | 06 | | | | |
| | (STM), solution of | state equation | ons. | | | | | | | | |
| | State feedback co | ntrol and ol | oserver desig | gn: Pole placement | (state variab | le feedbac | | | | | |
| Unit -2 | State and output | controllabil | ity and obs | ervability, design | of state of | oservers a | 06 | | | | |
| | controllers. | | | | | | | | | | |
| | Analysis of Discre | te Systems: | Introduction | to discrete time syste | ems; sample | and hold | | | | | |
| Unit -3 | circuits; representa | ation by diffe | erence equati | ons and its solution | n using Z-Tr | ansform, | 08 | | | | |
| ome s | pulse transfer func | tion, represei | ntation of disc | crete system in state | variable for | m and its | 00 | | | | |
| | solution. | | | | | | | | | | |
| | Introduction | to Optin | mal Con | trol & Ad | aptive (| Control: | | | | | |
| TT T L | Introduction, form | nation of c | optimal cont | rol problem, calc | ulus of va | riations, | 10 | | | | |
| Unit -4 | minimization of fu | inctions& fu | inctionals. Co | onstrained optimiza | tion, Introdu | iction to | 10 | | | | |
| | adaptive control, modal reference adaptive control systems, controller structure self- | | | | | | | | | | |
| | tuning regulators, | various adapt | ive control s | ystems. | · • | | | | | | |
| TT 1. 7 | Non-Linear Syste | ms: Lineari | zation technic | ques of non-linear | systems, Lya | apunov's | 0.6 | | | | |
| Unit -5 | method, methods | for generatir | ng Lyapunov | 's function, phase-j | plane and de | escribing | 06 | | | | |
| | Tunction technique | s. | | | | | 26 | | | | |
| | I otal Hours | | | | | | 36 | | | | |

Text Books:

1. N. S. Nise: Control Systems Engineering, 4th Ed., Wiley, 2004.

2. K. Ogata: Modern Control Engineering, 3rd Ed., Prentice Hall, 1999.

3. M. Gopal: Modern Control System Theory, 2nd Ed., New Age International, 1993

Reference Readings:

- 1. M. Gopal: Control Systems Principles and Design, 3rd Ed., Tata McGraw Hill, 2002.
- 2. B. Friedland: Control System Design, McGraw Hill, 1986.
- 3. E. Bryson and Y-C Ho: Applied Optimal Control, Taylor and Francis, 1975

| Course:- Bachelor of Technology (Electrical Engineering)SemesterSeventhSubject TitleUtilization of Electrical EnergyCodeTEE 7(Course ComponentsCreditsContact HoursLTPProgram Elective - IV03000000Examination DurationTheoryPractical 03WEIGHTAGE: EVALUATIONCWAMSEESE(Hrs)03005050 | 706 | | | | | | | | | |
|---|-----|--|--|--|--|--|--|--|--|--|
| SemesterSeventhSubject TitleUtilization of Electrical EnergyCodeTEE 70Course ComponentsCreditsContact HoursLTPProgram Elective - IV0300000000Examination DurationTheoryPracticalWEIGHTAGE:CWAMSEESE(Hrs)0300FVALUATION252550 | 706 | | | | | | | | | |
| Course ComponentsCreditsContact HoursLTPProgram Elective - IV03030000Examination DurationTheoryPracticalWEIGHTAGE:CWAMSEESE(Hrs)0300FVALUATION252550 | | | | | | | | | | |
| Program Elective - IV03Contact Hours030000Examination DurationTheoryPracticalWEIGHTAGE:CWAMSEESE(Hrs)0300EVALUATION252550 | | | | | | | | | | |
| Examination DurationTheoryPracticalWEIGHTAGE:CWAMSEESE(Hrs)0300EVALUATION252550 | | | | | | | | | | |
| (H_{rs}) 03 00 EVALUATION 25 25 50 | Ε | | | | | | | | | |
| $(1115) \qquad 0.5 \qquad 0.0 \qquad EVALUATION \qquad 2.5 \qquad 2.5 \qquad 30$ | | | | | | | | | | |
| Course Objectives | | | | | | | | | | |
| CO1 Understanding concept of Utilization of electric power in various fields | | | | | | | | | | |
| CO2 Application of various characteristics in illumination | | | | | | | | | | |
| CO3 Understand different types heating | | | | | | | | | | |
| CO4 Comprehend the different issues related to heating welding | | | | | | | | | | |
| CO5 Understanding of concept of Traction and Electrification | | | | | | | | | | |
| CO6 Analyzing various characteristics of electrical traction motor | | | | | | | | | | |
| | | | | | | | | | | |
| UnitContentHoursNo. | | | | | | | | | | |
| Illumination: Laws of illumination, Polar curves, Photometry, Integrating sphere, | | | | | | | | | | |
| Unit _1 Types of Lamps: Conventional and Energy Efficient, Basic principle of Light 8 | | | | | | | | | | |
| control, Different lighting scheme & their design methods, Flood and Street lighting. | | | | | | | | | | |
| | | | | | | | | | | |
| Heating: Types of heating, Resistance heating, Induction heating, Arc furnace, | | | | | | | | | | |
| Unit -2 Dielectric heating, Microwave heating 0 | | | | | | | | | | |
| Welding: Resistance welding Arc welding Ultrasonic welding Flectron beam | | | | | | | | | | |
| Unit -3 welding Laser beam welding Requirement for good welding Power supplies for 6 | | | | | | | | | | |
| different welding schemes | | | | | | | | | | |
| Traction: System of Traction Electrification. Train movement & energy consumption | | | | | | | | | | |
| (Speed-time curves, Crest speed, Average speed & Schedule speed), Tractive effort, | | | | | | | | | | |
| Unit -4 Factors affecting energy consumption (Dead weight, Acceleration weight & Adhesion 8 | | | | | | | | | | |
| weight), Protective devices. | | | | | | | | | | |
| Electric Traction motor & their control: Starting, braking with special emphasis on | | | | | | | | | | |
| Unit -5 power electronic controllers, Current collector, Interference with telecommunication 8 | | | | | | | | | | |
| circuit. A brief outline of linear Induction motor principle in Traction. | | | | | | | | | | |
| Total Hours 36 | | | | | | | | | | |

Text Books:

1. Wadha C L: Generation, Distribution and Utilization of electrical energy - New Age International Ltd.

2. Partab H: Art and Science of Utilization of Electrical Energy, DhanpatRai& Sons.

References:

1. E.Openshaw Taylor – Utilisation of Electric Energy – Orient Longman

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | | |
|-----------------------------------|--|--|---|---|--|---|---|---------|--|--|--|--|--|
| Course:- B | achelor | of Technol | ogy (Electric | al Engineeri | ng) | | | | | | | | |
| Semes | ter | Seventh | Subjec | et Title | Electrical Energy Management and Auditing | | Code | TEE 707 | | | | | |
| Cours | e Compo | nents | Cre | dits | Contact Hours | L | Τ | Р | | | | | |
| Progra | m Electiv | ve – V | 0 | 3 | Contact Hours | 03 | 00 | 00 | | | | | |
| | | | Theory | Practical | WEICHTACE. | CWA | MSE | ESE | | | | | |
| Examinati | on Dura | tion (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | | |
| Course Ob | jectives | | | | | | | | | | | | |
| CO 1 | Unders | stand the cu | urrent energy | scenario and | l importance of ener | gy conserva | tion. | | | | | | |
| CO2 | Unders | Understand the concepts of energy management. | | | | | | | | | | | |
| CO3 | Unders | Understand the concepts of energy audit. | | | | | | | | | | | |
| CO4 | Unders | stand the m | ethods of im | proving ener | gy efficiency in diff | erent electri | cal system | s. | | | | | |
| CO5 | Unders | stand the co | oncepts of dif | ferent energ | y efficient devices. | | | | | | | | |
| Unit No | Analys | as of the air | type compre | ssor. | | | | Uoung | | | | | |
| Unu No. | Comen | <i>u</i> | | | | | | nours | | | | | |
| Unit -1 | Energy Scenario Commercial and Non-commercial energy, primary energy resources, commercial energy production, final energy consumption, energy needs of growing economy, long term energy scenario, energy pricing, energy sector reforms, energy and environment, energy security, energy conservation and its importance, restructuring of the energy supply sector, energy strategy for the future, air pollution, climate change. Energy Conservation Act-2001 and its features. | | | | | | | | | | | | |
| Unit -2 | Basics Electric improv energy heat, ev and cor | of Energy a city tariff, 1 ement, sele contents of vaporation, nversion. | and its vario load manage ection & loc f fuel, tempe condensation | us forms ment and m ation of cap rature & pre a, steam, moi | naximum demand c pacitors, Thermal I essure, heat capacity st air and humidity | ontrol, pow Basics-fuels, v, sensible a & heat trans | er factor thermal nd latent fer, units | 8 | | | | | |
| Unit -3 | Energy Definit approad energy energy | y Managem ion, energy ch- understa use to req requiremen | audit, need, audit, need, anding energy uirement, ma ts, fuel & end | types of en costs, bench aximizing sy ergy substitu | ergy audit. Energy n marking, energy pe ystem efficiencies, o tion, energy audit in | managemer erformance, r optimizing t struments. | nt (audit) matching the input | 8 | | | | | |
| Unit -4 | Energy Electric demand capacite losses. | Energy Efficiency in Electrical and Industrial Systems Electrical system: Electricity billing, electrical load management and maximum demand control, power factor improvement and its benefit, selection and location of capacitors, performance assessment of PF capacitors, distribution and transformer losses | | | | | | | | | | | |
| Unit -5 | Compression Types of Compression affectin | Compressed Air and HVAC System:6Types of air compressors, compressor efficiency, efficient compressor operation, Compressed air system components, capacity assessment, leakage test, factors affecting the performance and savings opportunities in HVAC.6 | | | | | | | | | | | |
| | Total | Hours | | | | | | 36 | | | | | |
| Text | /Referen | ces: | | | | | | | | | | | |

1. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-1, General Aspects (available online)

2. Guide books for National Certification Examination for Energy Manager / Energy Auditors Book-3, Electrical Utilities (available online)

3. S. C. Tripathy, "Utilization of Electrical Energy and Conservation", McGraw Hill, 1991.

4. Success stories of Energy Conservation by BEE, New Delhi (www.bee-india.org)

Page 19 of 27

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|---|--|---|----------------------|-----------------|---------|--|--|--|--|
| Course: - I | Bachelor of T | Fechnolog | y (Electrica | al Engineering) | | | | | | | |
| Semester | Seventh | Subject | Title | HVDC Transmission Systems | | Code | TEE 708 | | | | |
| Course Co | mponents | Credits | | Contact Hours | L | Τ | Р | | | | |
| Program E | lective - V | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examinati | on | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| Duration (| (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course Ob | jectives | | | | | | | | | | |
| CO 1 | Application | n of dc tr | ansmission | and ac transmission. | | | | | | | |
| CO2 | Analysis of HVDC converter | | | | | | | | | | |
| <u>CO3</u> | Analysis of | Analysis of control strategies used in HVDC transmission system. | | | | | | | | | |
| CO4 | Understand | the vario | us character | ristics of HVDC systems | | | | | | | |
| 005 | Stability and | alysis of F | 1VDC syste | em | | | | | | | |
| | Understand | reactive p | ower and co | ontrol strategies | | | 11 | | | | |
| Unu No. | Content | | | | | | Hours | | | | |
| Unit -1 | DC Transmission Technology: Comparison of AC and DC Transmission (Economics, Technical Performance and Reliability). Application of DC Transmission. Types of HVDC Systems. Components of a HVDC system. Modern trends in DC transmission.6 | | | | | | | | | | |
| Unit -2 | Analysis of HVDC converters: Pulse number, Choice of converter configuration, Simplified analysis of Graetz circuit, Converter bridge characteristics, Characteristics of a twelve-pulse converter, Detailed analysis of converters with and without overlap. Converter and HVDC system control: General, Principles of DC link control, Converter control characteristics, System control hierarchy, firing angle control, Current and extinction angle control, Starting and stopping of DC link Derese converter | | | | | | | | | | |
| Unit -3 | Component Smoothing DC line: Co systems. dc | ts of HVE Reactors, rona Effec line faults | C systems: Reactive Po cts. Insulato s in VSC sys | : ower Sources and Filters in LCC F rs, Transient Over-voltages. dc line stems. dc breakers. | IVDC s e faults i | ystems n LCC | 6 | | | | |
| Unit -4 | Stability En Basic Conce Modulation: Stability Pre | systems. dc line faults in VSC systems. dc breakers. Stability Enhancement using HVDC Control Basic Concepts: Power System Angular, Voltage and Frequency Stability. Power Modulation: basic principles – synchronous and asynchronous links. Voltage Stability Problem in AC/dc systems. | | | | | | | | | |
| Unit 5 | Reactive p Sources of during tran of AC filter | Reactive power control: Reactive power requirements in steady state, Sources of reactive power, Static VAR systems, Reactive power control luring transients, Harmonics and filters, Generation of harmonics, Design of AC filters, DC filters. | | | | | | | | | |
| | Total Hou | rs | | | | | 36 | | | | |

1. K. R. Padiyar, "HVDC Power Transmission Systems", New Age International Publishers, 2011.

2. J. Arrillaga, "High Voltage Direct Current Transmission", Peter Peregrinus Ltd., 1983.

- 3. E. W. Kimbark, "Direct Current Transmission", Vol.1, Wiley-Interscience, 1971.
- 4. Arrillaga, J., HVDC Transmission, IEE Press (2007).

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|---|--|---|--|--|---|---------|--|--|--|
| Course | :- Bachelor of Techn | ology (Electi | rical Enginee | ring) | | | | | | |
| Sen | nester Seventh | Subje | ct Title | Electrical Design and Costi | Estimation ng | Code | TEE 709 | | | |
| Соц | urse Components | Cre | edits | Contract Hours | L | Т | Р | | | |
| Prog | gram Elective - V | (|)3 | Contact Hours | 03 | 00 | 00 | | | |
| Exan | nination Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course | e Objectives | | | | | | | | | |
| CO 1 | Analyze principle of | f estimation, | costing, surve | eying and source sel | ection. | | | | | |
| CO2 | Understand the con | cept of electi | ification of re | esidential. | | | | | | |
| CO3 | Understand the con | cept of electi | ification of c | ommercial building | s. | | | | | |
| CO4 | Understand the con | cept of electi | ical installati | on for power circuit | s. | | | | | |
| CO5 | Comprehend the co | ncept of Sub | station design | 1. | | | | | | |
| CO6 | Understand the app | lication of sv | vitchgear and | auxiliaries in substa | ation. | | | | | |
| | | | | | | | | | | |
| Unit | Content | | | | | | | | | |
| No. | | | | | | | | | | |
| Unit -1 | Unit -1 General principle of estimation: Introduction to estimation & costing, Electrical Schedule, Catalogues, Market Survey and source selection, Recording of estimates, Determination of required quantity of material, Labour conditions, Determination of cost material and labour, Contingencies, Overhead charges, Profit, Purchase system, Purchase enquiry and selection of appropriate purchase mode, Comparative statement, Purchase orders, Payment of bills, Tender form | | | | | | | | | |
| Unit -2 | Tender form. Electrification of residential and commercial buildings: General rules for wiring, Determination of number of points, Determination of total load, Determination of number of sub circuits, Determination of ratings of main switch/isolator, Distribution Board, Single line diagram using standard electrical signs and symbols of single phase/three phase circuits. Wiring estimation for single phase/three phase residential/ commercial consumers, Earthing of the electrical installation | | | | | | | | | |
| Unit -3 | Electrical installa motor installation motors, Determina size of Conduit, di | tion for pow wiring, Dete ation of rating stribution Bo | er circuits: I permination of g of cables, d pard main swi | Introduction, Import input power, Deter etermination of rationation itch and starter. | ant considera mination of ng of fuse, D | ations regarding input current to etermination of | 08 | | | |
| Unit -4 | Design and estim substations, Outdo | nation of sub por substation | stations: Int | roduction, Classific and location of site f | ation of sub or substatior | station, Indoor 1, Main | 04 | | | |
| Unit -5 | Substation Electr circuit elements or Equipment for su Substation Earthin | rical Connec n substation n ubstation and ng. | tions: Graph nain connecti d switchgear | ical symbols for var on diagram, Key dia installations, Sub | ious types of gram of typic station auxi | f apparatus and cal substations, liaries supply, | 04 | | | |
| | Total Hours | Ŭ | | | | | 36 | | | |
| · | 1 | | | | | | L | | | |

Text Books

1. .K.B.Raina, S.K.Bhattacharya, *Electrical Design Estimating and Costing*, 2nd Edition, New Age International (P) Ltd.

Reference Readings:

1. J.B.Gupta, *Electrical Installation Estimating & Costing*, 8th Edition S.K. Katria& Sons.

2. Uppal, *Electrical Wiring Estimating and Costing*, Khanna Publishers, New Delhi.

3. National Electric Code, Bureau of Indian Standard Publications.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|---|---|---|---|---|---------------------|-------------|--|--|--|--|
| Course:- Bo | ichelor of T | echnology | v (Electrica | l Engineering) | | | | | | | |
| Semester | Seventh | Subject 2 | Title | Power Quality and FACTS | | Code | TEE 710 | | | | |
| Course Con | nponents | Credits | | Contact Hours | L | Т | Р | | | | |
| Program Ele | ective - V | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Examinatio | n | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| Duration (H | Hrs) | 03 | 00 | | 25 | 25 | 50 | | | | |
| Course Obj | ectives | | | | | | | | | | |
| CO1 | Analysis compensa | of the c tion. | haracteristic | cs of ac transmission system. | shunt ai | nd serie | es reactive | | | | |
| CO2 | Analysis of shunt and series reactive compensation. | | | | | | | | | | |
| CO3 | Understa | nd the wo | rking princi | ples of FACTS devices and their o | perating | charact | eristics. | | | | |
| CO4 | Analysis | of STATC | COM | | | | | | | | |
| CO5 | Understa | nd the wo | rking princi | ples of devices to improve power of | quality. | | | | | | |
| CO6 | Understa | nd the bas | ic concepts | of power quality. | | | | | | | |
| Unit No. | Content | | | | | | Hours | | | | |
| Unit -1 | Transmission Lines and Series/Shunt Reactive Power CompensationBasics of AC Transmission. Analysis of uncompensated AC transmission lines.Passive Reactive Power Compensation. Shunt and series compensation at themid-point of an AC line. Comparison of Series and Shunt Compensation. | | | | | | | | | | |
| Unit -2 | Thyristor- Description Compensat Controlled | based Fle n and Cha tor (SVC) Braking F | exible AC T aracteristics , Thyristor Resistor and | Fransmission Controllers (FACT) of Thyristor-based FACTS device Controlled Series Capacitor (TC Single Pole Single Throw (SPST) | S) es: Static SC), Th Switch. | e VAR yristor | 8 | | | | |
| Unit -3 | Voltage So Voltage So Converters Sinusoidal | ource Con ource Con , Pulse-W PWM and | verter bas verters (VS idth Modul d Space Vec | ed (FACTS) controllers C): Six Pulse VSC, Multi-pulse a ation for VSCs. Selective Harmon ctor Modulation. | nd Mult ic Elimi | ti-level nation, | 6 | | | | |
| Unit-4 | STATCOM: Principle of Operation, Reactive Power Control: Type I and Type II controllers, Static Synchronous Series Compensator (SSSC) and Unified Power 6 Flow Controller (UPFC) 6 | | | | | | | | | | |
| Unit -5 | Power Quality Problems in Distribution Power Quality problems in distribution systems: Transient and Steady state variations in voltage and frequency. Unbalance, Sags, Swells, Interruptions, Wave-form Distortions: harmonics, noise, notching, dc-offsets, fluctuations. | | | | | | | | | | |
| | Total Hou | irs | | | | | 36 | | | | |
| | | | | | | | | | | | |

1. N. G. Hingorani and L. Gyugyi, "Understanding FACTS: Concepts and Technology of FACTS Systems", Wiley-IEEE Press, 1999.

- 2. K. R. Padiyar, "FACTS Controllers in Power Transmission and Distribution", New Age International (P) Ltd. 2007.
- 3. T. J. E. Miller, "Reactive Power Control in Electric Systems", John Wiley and Sons, New York, 1983.
- 4. R. C. Dugan, "Electrical Power Systems Quality", McGraw Hill Education, 2012.
- 5. G. T. Heydt, "Electric Power Quality", Stars in a Circle Publications, 1991

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|-------------------------------|---|-----------------------|---------------|--------------|----------------------|-----------|-----------|----|--|--|
| Course:- | Bachelo | r of Techn | ology (Electi | ical Enginee | ring) | | | | | |
| Semester Seventh | | Subject Title | | Industry 4.0 | | Code | TEE 711 | | | |
| Course | Course Components | | Credits | | | L | T | Р | | |
| Program | Program Elective – IV | | 03 | | Contact Hours | 03 | 00 | 00 | | |
| Examination Duration (Hrs) | | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course | Outcom | es: | | | | | | | | |
| CO1 | Unders | stand the d | rivers and e | nablers of I | ndustry 4.0 | | | | | |
| CO2 | Apprecessors and a smart s | ciate the sistervices | martness in | Smart Fact | ories, Smart cities, | smart pro | ducts and | | | |
| CO3 | Able to outline the various systems used in a manufacturing plant and their role in an Industry 4.0 world | | | | | | | | | |
| CO4 | Appreciate the power of Cloud Computing in a networked economy | | | | | | | | | |
| CO5 | Understand the opportunities, challenges brought about by Industry 4.0 and how | | | | | | | | | |
| | organisations and individuals should prepare to reap the benefits | | | | | | | | | |
| Unit | Content | | | | | | | | | |
| No. | Introduction to Inductor 40 | | | | | | | | | |
| Unit -1 | Introduction to Industry 4.0 The Various Industrial Revolutions, Digitalisation and the Networked Economy, Drivers, Enablers, Compelling Forces and Challenges for Industry 4.0, The Journey so far: Developments in USA, Europe, China and other countries, Comparison of Industry, Factory and Today's Factory, Trends of Industrial Big Data and Predictive Analytics for Smart Business Transformation | | | | | | | 10 | | |
| Unit -2 | Road to Industry 4.0 Internet of Things (IoT) & Industrial Internet of Things (IIoT) & Internet of Services, Smart Manufacturing, Smart Devices and Products, Smart Logistics, Smart Cities, Predictive Analytics | | | | | | | 6 | | |
| Unit -3 | Related Disciplines, System, Technologies for enabling Industry 4.0 3 Cyberphysical Systems, Robotic Automation and Collaborative Robots, Support System for Industry 4.0, Mobile Computing, Related Disciplines, Cyber Security | | | | | | | 6 | | |
| Unit -4 | Role of data, information, knowledge and collaboration in future organizations Resource-based view of a firm, Data as a new resource for organizations, Harnessing and sharing knowledge in organizations, Cloud Computing Basics, Cloud Computing and Industry 4.0 | | | | | | | | | |
| Unit – 5 | Other Applications and Business issues in Industry 4.0 Industry 4.0 laboratories, IIoT case studies, Opportunities and Challenges, Future of Works and Skills for Workers in the Industry 4.0 Era, Strategies for competing in an Industry 4.0 world | | | | | | | | | |
| | Total H | Hours | | | | | | 36 | | |

Text Books / Reference Readings

- 1. Alasdair Gilchrist, "Industry 4.0: The Industrial Internet of Things", Apress; 1st ed. edition (4 January 2017)
- 2. Sabina Jeschke, Christian Brecher, Houbing Song, Danda B. Rawat, "Industrial Internet of Things: Cyber manufacturing Systems", 1ST ed., Springer, 2017
- 3. Research Papers

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|----------------------|--|---|---------------|----------------------|----------------|------------------|---------|--|--|--|
| Course | e:- Bachelor of Techno | ology (Electr | ical Enginee | ring) | | | | | | |
| Sen | nester Eighth | Subje | ct Title | Power Plant Instru | umentation | Code | TEE 801 | | | |
| Course Components | | Cre | dits | Contact Hours | L | Τ | Р | | | |
| Prog | gram Elective - VI | C | 3 | Contact Hours | 03 | 00 | 00 | | | |
| Examination Duration | | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Cours | e Objectives | | | | | | | | | |
| CO 1 | Application of instru | mentation in | power gener | ation | | | | | | |
| CO2 | Analysis of control n | nethod in the | rmal power p | olant | | | | | | |
| CO3 | Analysis of burner ti | lting, up byp | ass damper si | uper heater Spray an | d gas re circ | ulation controls | , etc | | | |
| CO4 | Understand the cond | cept of Turbi | ne monitorin | g and control | | | | | | |
| CO5 | Analysis in power pl | ant | | | | | | | | |
| CO6 | Understand the role | of computer | s in instrume | ntation | | | | | | |
| | | | | | | | | | | |
| Unit | Unit Content | | | | | | | | | |
| No. | | | | | | | | | | |
| | An Overview Dep | An Overview Dependence of instrumentation on the method of power generation thermal | | | | | | | | |
| Unit -1 | power plants general structures, pulverization and burners fans, dampers and actuators super | | | | | | | | | |
| | heaters stern traps- Economizer, Recirculation and regenerators, Cooling towers feed water | | | | | | | | | |
| | generators Turbine | cooling syst | em radiation | detectors | | | | | | |
| | Control loops and | Control loops and inter and Annunciation systems: Combustion control of main header, | | | | | | | | |
| TT | pressure, air, tuel ratio control, turnace and excess control drum level (three element control) | | | | | | | | | |
| Unit -2 | main and re-near systems temperature control, burner tilting up bypass damper super heater | | | | | | | | | |
| | Spray and gas re circulation controls, not well level control inter lock – MFT Turbine trip | | | | | | | | | |
| | Turbing monitor | ing and co | ntral: Cond | nser vacuum cont | rol gland s | taam axhaust | | | | |
| Unit -3 | pressure control si | pressure control speed vibration shell temperature monitoring lubricating cil temperature | | | | | | | | |
| Omt-C | control hydrogen | peed vibrance | ling system | crature monitoring, | idoneating c | in temperature | 0 | | | |
| | Analysis in nowe | r nlant: The | rmal conduc | tive type paramagn | etic type ox | voen analyzer | | | | |
| Unit -4 | hydrogen purity m | eter chromat | ography. PH | meter fact analyzer | pollution n | onitoring and | 8 | | | |
| 0 | control. | control | | | | | | | | |
| T T •/ • | . Computer in pow | er plants: lo | ad dispatchir | ig computer, genera | tion station c | omputer, mini | - | | | |
| Unit -5 | computers, and sur | pervisory con | trol | | | 1 7 | 6 | | | |
| | Total Hours | 2 | | | | | 36 | | | |
| | Text Books | | | | | | | | | |

- 1. El wakil, MM, power plant technology, Mc Graw hill.1984
- 2. Richard Delezal and ludrikVarcop, Process Dynamics Automatic Control of steam Generation plant, ElevierPulishing Co Amesternam 1972.

Reference books:

- 1. J Balsubramnian and RK Jain Modern power plant engineering, Khanna Publisher, New Delhi 1987
- 2. Stephen Michael Elonka&antomyLawerencekohal / standard Boiler operation, question and answer TMH

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|-----------------------------------|--|-----------------------|----------------------|--------------------------------------|-----------|-----------|---------|--|--|--|
| Course: - 1 | Bachelor of T | Technolog | y (Electrica | ll Engineering) | | | | | | |
| Semester Eighth | | Subject Title | | Wind and Solar Energy Systems | | Code | TEE 802 | | | |
| Course Co | mponents | Credits | | Contract Hours | L | Τ | P | | | |
| Program E | lective - VI | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examinati | on | Theory Practical W | | WEIGHTAGE: | CWA | MSE | ESE | | | |
| Duration (| (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course Ob | jectives | | | | | | | | | |
| CO 1 | Understand renewable e | d the energenergy sou | gy scenario rces. | and the consequent growth of the p | ower ge | eneration | n from | | | |
| CO2 | Understand | d the basic | physics of | wind and solar power generation. | | | | | | |
| CO3 | Understand | d the powe | er electronic | interfaces for wind and solar gene | ration. | | | | | |
| CO4 | Understand | d the issue | s related to | the grid-integration of solar and wi | ind ener | gy syste | ems. | | | |
| CO5 | Understand | d the issue | s related to | power quality | | | | | | |
| CO6 | Understand | the conc | epts of MPI | PT for generation of solar Photo Vo | ltaic po | wer | | | | |
| Unit No. | Content | | | | | | Hours | | | |
| | Physics of | Wind Po | ower | | | | | | | |
| TT *4 1 | History of v | vind powe | er, Indian an | d Global statistics, Wind physics, | Betz lin | nit, Tip | 4 | | | |
| Unit -1 | speed ratio, stall and pitch control. Wind speed statistics, probability distributions | | | | | | | | | |
| | Wind speed | and powe | er-cumulativ | ve distribution functions. | , , | , | | | | |
| | Wind gene | erator to | pologies | | | | | | | |
| | Review of | modern v | vind turbing | e technologies, Fixed and Variab | le speed | l wind | | | | |
| Unit -2 | turbines, Ir | nduction | Generators, | Doubly-Fed Induction Generat | orsand | l their | 8 | | | |
| | characteristics, Permanent-Magnet Synchronous Generators, Power electronics | | | | | | | | | |
| | converters. | Generator | -Converter | configurations, Converter Control. | | | | | | |
| | The Solar | Resourc | e | | | | | | | |
| | Introduction | n, solar ra | diation spec | etra, solar geometry, Earth Sun an | gles, ob | server | | | | |
| | Sun angles, | solar day | length, Esti | mation of solar energy availability. | - | | | | | |
| Unit -3 | Solar photovoltaic | | | | | | | | | |
| | Technologies-Amorphous, monocrystalline, polycrystalline; V-I characteristics of | | | | | | | | | |
| | a PV cell, PV module, array, Power Electronic Converters for Solar Systems, | | | | | | | | | |
| | Maximum Power Point Tracking (MPPT) algorithms. Converter Control. | | | | | | | | | |
| | Grid-Conne | ected Dist | ributed Gen | eration Systems | | | | | | |
| | Global scenario of Distributed Generators (DGs) Characteristics of different | | | | | | | | | |
| | Renewable | Energy . | Source bas | ed Distributed Generators Powe | er Elec | tronics | | | | |
| Unit -4 | Structure for | or grid ir | nterfacing of | of different DGs Standards and | guidelin | les for | 8 | | | |
| | Integration | of DGs [1 | 5471 Criter | ia for synchronizing DGs utility g | rid Chal | lenges | | | | |
| | related to P | V based D | Gs and win | d based DGs | | lienges | | | | |
| | Telated to I | V Dused D | | | | | | | | |
| | Network I | ntegratio | on Issues | | | | | | | |
| | Overview of | f grid cod | e technical | requirements. Fault ride-through fo | r wind f | farms - | | | | |
| Unit 5 | real and read | ctive powe | er regulatior | , voltage and frequency operating l | imits, sc | olar PV | 8 | | | |
| Omt 5 | and wind f | arm beha | viour durin | g grid disturbances. Power qualit | y issues | s. Grid | | | | |
| | Synchroniza | ation of P | V based DG | s Hybrid and isolated operations o | f solar I | PV and | | | | |
| | wind system | ns. | | | | | | | | |
| | Total Hour | s | | | | | 36 | | | |

1. T. Ackermann, "Wind Power in Power Systems", John Wiley and Sons Ltd., 2005.

2. G. M. Masters, "Renewable and Efficient Electric Power Systems", John Wiley and Sons, 2004.

3. S. P. Sukhatme, "Solar Energy: Principles of Thermal Collection and Storage", McGraw Hill, 1984.

4. H. Siegfried and R. Waddington, "Grid integration of wind energy conversion systems" John Wiley and Sons Ltd., 2006.

5. G. N. Tiwari and M. K. Ghosal, "Renewable Energy Applications", Narosa Publications, 2004.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|----------------------|---|---|---|--|---------|-----------|---------|--|--|--|
| Course: - B | Bachelor of Techn | ology (Ele | ctrical Engin | eering) | | | | | | |
| Semester | Eighth | Subject T | <i>`itle</i> | Advanced Electric Drives Code | | | TEE 803 | | | |
| Course Con | nponents | Credits | | Contract House | L | Τ | P | | | |
| Program El | ective - VI | 03 | | Contact Hours | 03 | 00 | 00 | | | |
| Examination Duration | | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course Obj | iectives | | | | | | | | | |
| CO 1 | CO 1 Understand the operation of power electronic converters. | | | | | | | | | |
| CO2 | Understand various control strategies for different converters | | | | | | | | | |
| CO3 | Understand the | e vector con | ntrol strategies | s for ac motor drives | | | | | | |
| CO4 | Modelling of synchronous motor drive | | | | | | | | | |
| CO5 | Understand the basics of permanent magnet motors | | | | | | | | | |
| C06 | Understand the basics of reluctance motor drive | | | | | | | | | |
| Unit No. | Content | Content | | | | | | | | |
| Unit -1 | Power Converters for AC drivesPWM control of inverter, selected harmonic elimination, space vectormodulation, current control of VSI, three level inverter, Different topologies,SVM for 3 level inverter, Diode rectifier with boost chopper, PWM converteras line side rectifier, current fed inverters with self-commutated devices. | | | | | | | | | |
| Unit -2 | Induction motor drives Different transformations and reference frame theory, modeling of induction machines, voltage fed inverter control-v/f control, vector control, direct torque and flux control(DTC) | | | | | | | | | |
| Unit -3 | Synchronous motor drives Modeling of synchronous machines, open loop v/f control, vector control, direct torque control, CSI fed synchronous motor drives. | | | | | | | | | |
| Unit -4 | Permanent magnet motor drivesIntroduction to various PM motors, BLDC and PMSM drive configuration, comparison, block diagrams, Speed and torque control in BLDC and PMSM.6 | | | | | | | | | |
| Unit-5 | Switched reluc Evolution of sw comparison, Clo | tance mote vitched relu osed loop s | or drives actance motor peed and torq | rs, various topologies ue control of SRM. | for SRM | 1 drives, | 6 | | | |
| Total Hours | | | | | | | | | | |

- 1. K. Bose, "Modern Power Electronics and AC Drives", Pearson Education, Asia, 2003.
- 2. P.C. Krause, O. Wasynczuk and S.D. Sudhoff, "Analysis of Electric Machinery and Drive Systems", John Wiley & Sons, 2013.
- **3.** H. A. Taliyat and S. G. Campbell, "DSP based Electromechanical Motion Control", CRC press, 2003.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | |
|-----------------------------------|---|------------------|---------------|--------------------------------------|-----------|---------|---------|--|--|
| Course: - 1 | Bachelor of T | Technolog | y (Electrica | al Engineering) | | | | | |
| Semester | eighth | Subject | Title | Power System Dynamics and Control Co | | | TEE 804 | | |
| Course Co | mponents | Credits | | Contact Hours | L | Τ | Р | | |
| Program E | lective - VI | 03 | | Contact Hours | 03 | 00 | 00 | | |
| Examinati | on | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | |
| Duration (| Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | |
| Course Ob | jectives | | | | | | | | |
| CO1 | Analysis of | linear dy | namic system | m | | | | | |
| CO2 | Analysis of power system stability | | | | | | | | |
| CO3 | Designing of | of Synchro | onous machi | ine and controllers | | | | | |
| CO4 | Modelling | of power s | system com | ponents | | | | | |
| CO5 | Understand | d the meth | ods to impr | ove stability. | | | | | |
| | | | | | | | 1 | | |
| Unit No. | Content | | | | | | Hours | | |
| | Introductio | on: Introd | uction to po | ower system stability. Power System | em Ope | rations | | | |
| Unit -1 | and Contro | l. Stabilit | y problems | s in Power System. Impact on l | Power S | System | 6 | | |
| | Operations and control. | | | | | | | | |
| | | | | | | | | | |
| | Analysis of Linear Dynamical System and Numerical Methods | | | | | | | | |
| Unit -2 | Analysis of dynamical System, Concept of Equilibrium, Small and Large | | | | | | | | |
| | Disturbance Stability. Modal Analysis of Linear System. Analysis using Numerical | | | | | | | | |
| | Integration | f Complete | es. Issues in | Modeling: Slow and Fast Transient | s, Suir s | system | | | |
| | Modeling 0 | of synchro | Dhous Maci | alines and Associated Controllers | Datan m | | | | |
| | Modeling of synchronous machine: Physical Characteristics. Rotor position | | | | | | | | |
| Unit 2 | dependent model. D-Q Transformation. Model with Standard Parameters. Steady | | | | | | | | |
| Unit-5 | State Analysis of Synchronous Machine. Snort Circuit Transfert Analysis of a | | | | | | | | |
| | Synchronous Machine. Synchronization of Synchronous Machine to an Infinite Bug Modeling of Excitation and Prime Mover Systems, Automatic Valtage | | | | | | | | |
| | Bus, would be excitation and rinne wover Systems. Automatic voltage | | | | | | | | |
| | Modeling o | f other D | ower System | m Components | | | | | |
| | Modeling of Transmission Lines and Loads Transmission Line Divised | | | | | | | | |
| Unit -4 | Characterist | tics Trans | smission Li | ne Modeling Load Models - indu | iction m | achine | 8 | | |
| Omt 4 | model Freq | mency and | d Voltage D | ependence of Loads Other Subsys | tems –] | HVDC | 0 | | |
| | and FACTS controllers. Wind Energy Systems | | | | | | | | |
| | Stability A | nalysis an | d Enhanci | ng System Stability | | | | | |
| | Frequency | Stability: | Centre of | Inertia Motion. Load Sharing: Go | overnor | droop. | | | |
| Unit -5 | Single Mac | chine Loa | d Bus Svs | stem: Voltage Stability. Introduc | tion to | signal | 8 | | |
| | Oscillations | and the S | SR phenom | enon. Stability Analysis Tools: Tra | nsient St | ability | | | |
| | Programs, S | mall Sign | al Analysis | Programs. | | J | | | |
| | Total Hou | rs | ~ | ~ | | | 36 | | |

1. K.R. Padiyar, "Power System Dynamics, Stability and Control", B. S. Publications, 2002.

2. P. Kundur, "Power System Stability and Control", McGraw Hill, 1995.

3. P. Sauer and M. A. Pai, "Power System Dynamics and Stability", Prentice Hall, 1997.

Syllabus

Open Elective Courses

B. Tech (Electrical Engineering) BoS - 2020

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---------|---|--|---|--|---|--|--|---------------|--|--|--|
| Course: | - Bachel | or of Techn | ology (Elect | rical Engine | ering) | | | | | | |
| Seme | ester | Fifth | Subject Title | | Data Structure | | Code | TOE 501 | | | |
| Cour | se Comp | onents | Cre | dits | | L | Т | Р | | | |
| Open | Elective | Course | 0 | 3 | Contact Hours | 03 | 00 | 00 | | | |
| Evam | nation D | uration | Theory | Practical | WEIGHTAGE | CWA | MSE | ESE | | | |
| Exami | (Hrs) | uraiion | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course | Objectiv | es | 1 | | | | | L | | | |
| CO 1 | Describ perform | be the concentration the concentration of the conce | ept of Data Sograms. | Structures and | d assess how the ch | noice of data | structure | s impacts the | | | |
| CO2 | Compa comple | re and cont xity. | rast merits a | nd demerits o | of various data struc | ctures in term | ns of time | and memory | | | |
| CO3 | Identify | and propo | se appropriat | e data structu | re for providing the | solution to the | he real wo | rld problems. | | | |
| CO4 | Implem structur | ient operationes | ons like sear | ching, inserti | on, deletion, travers | sing mechani | sm etc. or | various data | | | |
| CO5 | Be fam priority | iliar with a queues. Al | dvanced data | a structures s | such as balanced se | earch trees, h | ash tables | s, AVL trees, | | | |
| CO6 | To aug subject | ment merit | s of particula | ar data struc | tures on other data | structure to | develop | innovation in | | | |
| Unit | Conten | et | | | | | | Hours | | | |
| Unit -1 | Elementary Data Organization, Data Structure operations, Algorithm Complexity and Time-Space trade-off Arrays: Array Definition, Representation and Analysis, Single and Multidimensional Arrays, address calculation, application of arrays, Array as Parameters, Ordered List, Sparse Matrices. Stacks: Array. Representation and Implementation of stack, Operations on Stacks: Push & Pop, Array Representation of Stack, Linked Representation of Stack, Operations Associated with Stacks, Application of stack: Conversion of Infix to Prefix and Postfix Expressions, Evaluation of postfix expression using stack. Recursion: Recursive definition and processes, recursion in C, example of recursion, Tower of Hanoi Problem, tail | | | | | | | 8 | | | |
| Unit -2 | Queues: Array and linked representation and implementation of queues, Operations on Queue: Create, Add, Delete, Full and Empty. Circular queue, Dequeue, and Priority Queue. Linked list: Representation and Implementation of Singly Linked Lists, Two-way Header List, Traversing and Searching of Linked List, Overflow and Underflow, Insertion and deletion to/from Linked Lists, Insertion and deletion Algorithms, doubly linked list, Linked List in Array, Polynomial representation and addition, Generalized linked list | | | | | | | | | | |
| Unit -3 | Trees: Express Repress Thread Huffma Searchi Hash Implem | Basic tern sions, Com entation of ed Binary an tree. ing and Has Table, Ha entation | minology, B aplete Binary Binary trees, trees. Traven shing: Seque sh Functior | inary Trees, 7 Tree. Exte Traversing E rsing Thread ntial search, ns, Collision | Binary tree repro- nded Binary Trees Binary trees, ed Binary trees, H binary search, com Resolution Stra | esentation, a s, Array and fuffman algo parison and tegies, Hasl | algebraic Linked rithm & analysis, h Table | 8 | | | |
| Unit -4 | Sorting | : Insertion S on Differe | Sort, Bubble nt Keys, Prac | Sorting, Quic ctical conside | k Sort, Two Way M ration for Internal S | lerge Sort, Hoorting. | eap Sort, | 6 | | | |

| | Binary Search Trees: Binary Search Tree (BST), Insertion and Deletion in BST, | |
|---------|---|----|
| | Complexity of Search Algorithm, Path Length, AVL Trees | |
| Unit -5 | File Structures: Physical Storage Media File Organization, Organization of records into Blocks, Sequential Files, Indexing and Hashing, Primary indices, Secondary indices, B+ Tree index Files, B Tree index Files, Indexing and Hashing Comparisons, Graph, Traversal (DFS,BFS), Minimum spanning tree | 6 |
| | Total Hours | 36 |

Text/ Reference Books:

Horowitz and Sahani, "Fundamentals of data Structures", Galgotia Publication Pvt. Ltd., New Delhi.
 R. Kruse etal, "Data Structures and Program Design in C", Pearson Education Asia, Delhi-2002

3. A. M. Tenenbaum, "Data Structures using C & C++", Prentice-Hall of India Pvt. Ltd., New Delhi.
4. K Loudon, "Mastering Algorithms with C", Shroff Publisher & Distributors Pvt. Ltd.

5. Bruno R Preiss, "Data Structures and Algorithms with Object Oriented Design Pattern in C++", Jhon Wiley & Sons, Inc.

6. Adam Drozdek, "Data Structures and Algorithms in C++", Thomson Asia Pvt

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|--|--|---|---|--|---|-----------------------|----------------------|------------|--|--|
| Course: | - Bachelo | r of Tec | chnology (| Electrical I | Engineering) | | | | | |
| <i>Semester</i> Fi | | Fifth | Subject Title | | Computer Based Numerical and Statistical Techniques | | | TOE 502 | | |
| Course Components | | | Cr | edits | | L | Т | Р | | |
| Oper | n Elective | - I | | 3 | Contact Hours | 3 | 0 | 0 | | |
| Examination Duration (Hrs) | | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| | | | 3 | 0 | | 25 | 25 | 50 | | |
| Course | Objectiv | es | | | | | | | | |
| CO 1 | Be awar errors in | e of the numerio | use of nur cal compu | nerical meth tation. | nods in modern scientific computin | ig as wel | l as vario | ous | | |
| CO2 | Master u root find | uster using the bisection method, Newton's method, and the secant method in single variable | | | | | | | | |
| CO3 | Be famil | iar with | numerica | l interpolati | on and approximation of functions | | | | | |
| CO4 | Be famil | iar with | numerica | l integratior | and differentiation | | | | | |
| CO5 | Be famil | iar with | numerica | l solution of | f ordinary differential equations | | | | | |
| | | | | | | | | | | |
| Unit No | . Cor | ntent | | | | | | Hours | | |
| Unit -1 Introduction: Numbers and their accuracy, Errors, Type of Error and their Computation, General error formula, Error in series approximations. Solution of Algebraic and Transcendental Equation: Bisection Method, Iteration method, Method of false position, Secant Method, Newton-Raphson method, Muller's method, Rate of convergence of Iterative methods | | | | | | | 10 | | | |
| Unit -2 Interpolation: Finite Diffe Newton's forward and back forward and backward form interpolation, Newton divide | | | on: Finite forward a d backwar n, Newtor | e Differenc nd backwa rd formula. n divided dif | aces, Difference tables, Polynomial Interpolation: ard formula, Central difference formulae: Gauss a. Interpolation with unequal intervals: Lagrange's lifference formula. | | | | | |
| Unit -3 | Unit -3 Numerical Differentiation and Integration: Numerical differentiation of interpolation formulae, Numerical Integration: Trapezoidal rule, Simpson's 1/3 and 3/8 rule, Boole's Rule ,Weddle's rule, Euler –Maclarian formula. | | | | | 8 | | | | |
| Unit -4 | Nui Me Pre | merical thod, E dictor C | Solution uler's and orrector M | of differ 1 modified 1ethod | ential Equations: Taylor's Me Euler's method, Runge-Kutta M | ethod, F lethod, 1 | Picard's ∕Iilne's | 8 | | |
| | То | tal Hour | S | | | | | 36 | | |

Text Books:

Numerical MethodsM.K. Jain, S.R.K. Iyenger and R.K. Jain
 Schaum's Outline of Theory and Problems of Statistics: Murray R. Spiegel

References:

1. Applied Numerical Analysis: Curtis F. Gerald and Patrick O. Wheatley
| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|--|---|---|---|--|-------------------------------------|--------------------------------|------------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Sem | ester | Fifth | Subje | ect Title | Electronic Devices | | Code | TOE 503 | | | |
| Cours | e Compo | nents | Cr | redits | Contract Hours | L | Т | P | | | |
| Ope | n Electiv | e - I | | 3 | Contact Hours | 0 | 0 | | | | |
| Examir | tation Di (Hrs) | ıration | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | |
| | | | 3 | 0 | | 25 | 25 | 50 | | | |
| Course Objectives | | | | | | | | | | | |
| CO 1 | Understand the principles of semiconductor Physics | | | | | | | | | | |
| CO2 | Underst | and the | basics of J | unction dio | des | | | | | | |
| CO3 | Underst transiste | Understand and utilize the mathematical models of semiconductor junctions and BJT/MOS transistors for circuits and systems. | | | | | | | | | |
| CO4 | Analysi | alysis of the characteristics of BJT/MOS transistors for circuits and systems. | | | | | | | | | |
| CO5 | Underst | and the | IC fabrica | tion process | es | | | | | | |
| | | | | | | | | | | | |
| Unit No | o. Co | ntent | | | | | | Hours | | | |
| Unit -1 | Int in Ca res | roductio periodic rrier tran istance, | n to Semio Lattices, nsport: din design of | conductor P E-k diagran ffusion curr resistors | hysics: Review of Quantum Mecha ns. Energy bands in intrinsic and e rent, drift current, mobility and re | anics, El xtrinsic esistivity | ectrons silicon; ; sheet | 9 | | | |
| Unit -2 | Ge jur Av | neration action ch alanche | and reco aracterist breakdow | mbination o ics, I-V cha n, Zener dio | of carriers; Poisson and continuity aracteristics, and small signal swi ode, Schottky diode | y equation tching r | on P-N nodels; | 9 | | | |
| Unit -3 | Unit -3 Bipolar Junction Transistor, I-V characteristics, Ebers-Moll Model, MOS capacitor, C-V characteristics, MOSFET, I-V characteristics, and small signal models of MOS transistor, LED, photodiode and solar cell; | | | | | | | 9 | | | |
| Unit -4 Integrated circuit fabrication process: oxidation, diffusion, ion implantation, photolithography, etching, chemical vapor deposition, sputtering, twin-tub CMOS process. | | | | | | 9 | | | | | |
| | То | otal Hour | :s | | | | | 36 | | | |

Text /Reference Books:

1. G. Streetman, and S. K. Banerjee, "Solid State Electronic Devices," 7th edition, Pearson, 2014.

2. D. Neamen , D. Biswas "Semiconductor Physics and Devices," McGraw-Hill Education 3. S. M. Sze and K. N. Kwok, "Physics of Semiconductor Devices," 3rd edition, John Wiley &Sons, 2006.

4. C.T. Sah, "Fundamentals of solid state electronics," World Scientific Publishing Co. Inc, 1991.

5. Y. Tsividis and M. Colin, "Operation and Modeling of the MOS Transistor," Oxford Univ.Press,

2011.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--------------------|-----------------------------------|---|--|--------------------------|------------------------------|------------------------------|-------------|------------|--|--|--|--|
| Course:- | Bachelor | of Techno | ology (ELI | ECTRICAL | ENGINERIN | / G) | | | | | | |
| Semester | | Fifth | Subject T | Title | Data Structur | re Lab | Code | POE 501 | | | | |
| Course C | omponen | ts | Credits | Credits | | L | Т | P | | | | |
| Open Ele | ctive Cou | rse | | 1 | Hours | 0 | 0 | 2 | | | | |
| Examinat (Hrs) | tion Dura | tion | Theory | Practical | Weightage: Evaluation | Weightage: CWA Evaluation | | ESE | | | | |
| | | | 0 3 25 25 50 | | | | | | | | | |
| Course (| Objective | S | | | | | | | | | | |
| CO1 | This wil program | l boost the ming. | basic prog | gramming sl | cills of the stud | dent in C a | nd C++ | | | | | |
| CO2 | Better un dynamic | nderstandi memory a | ng to the coallocation. | oncept of th | e stacks and q | ueue and tl | heir use wi | th | | | | |
| CO3 | Learning | g and unde | rstanding i | in a better w | ay to sort the | arrays and | lists. | | | | | |
| CO4 | Impleme | entation of | various al | gorithms. | | | | | | | | |
| | | | | | | | | | | | | |
| Experime | ent No. | Name of | the Exper | iment | | | | | | | | |
| 1 | | Write Program in C or C++ for Array implementation of Stack, Queue, Circular Queue, List. | | | | | | | | | | |
| 2 | | Write Pro Queue, L | Vrite Program in C or C++ for Implementation of Stack, Queue, Circular ueue, List using Dynamic memory Allocation. | | | | | | | | | |
| 3 Write Tree, 7 | | | Write Program in C or C++ for Implementation of Tree Structures, Binary Tree, Tree Traversal, Binary Search Tree, Insertion and Deletion in BST. | | | | | | | | | |
| 4 | | Write Pro Algorith | Write Program in C or C++ for Implementation of Searching and Sorting Algorithms. | | | | | | | | | |
| 5 | | Write Pro | ogram in C ming tree, | or C++ for shortest path | Graph Implen n algorithm. | nentation, | BFS, DFS | , Min. | | | | |

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|---|---|--|---------------------|---------------------------|---|------------------|----------|------------|--|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) Samestar Fifth Subject Tide Industrial Engineering | | | | | | | | | | | | |
| Sem | ester | Fifth | Subje | ect Title | Industrial Engineering | | Code | TOE 504 | | | | |
| Cours | e Compo | nents | Cr | redits | Contact Hours | L | T | P | | | | |
| Ope | n Elective | e - I | | 3 | | 3 | 0 | 0 | | | | |
| Examir | nation Du | ration | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| | (Hrs) | | 3 | 0 | | 25 | 25 | 50 | | | | |
| Course | Objectiv | 'es | | | | | | | | | | |
| CO 1 | Product | ivity and | l Partial P | roductivity of | calculation for an organization. | | | | | | | |
| CO2 | Design | a method | d for manu | ifacturing fo | or a new Process and Modify the ex | isting Pr | ocess, | | | | | |
| CO3 | Draw th | e flow p | rocess cha | arts for a giv | ven process | | | | | | | |
| CO4 | Apply work measurement techniques for a given job | | | | | | | | | | | |
| C05 | Identify | and per | torm time | study for si | mple applications. | | | | | | | |
| CO6 | Apply e | rgonomi | c concept | s in work en | vironment. | | | | | | | |
| T T 1 / 3 7 | 0 | | | | | | | ** | | | | |
| Unit No | $\frac{Co}{Co}$ | ntent | CELON | | | | | Hours | | | | |
| | | | CTION: | C T 1 / | | | | | | | | |
| Unit -1 Definition and scope of Industrial engineering role of an industrial engineer in | | | | | | | | 6 | | | | |
| industry, functions of industrial engineering department and its organization, qualities of an industrial engineer. | | | | | | | | | | | | |
| | | qualities of an industrial engineer. | | | | | | | | | | |
| | F N | ductivit | | t and defin | NSIUDI: | f produ | otivity | | | | | |
| | Pro | ductivit | y concep | ment at nat | tional industrial and enterprise less | val Ban | clivity, | | | | | |
| | hig | her pro | ductivity | Productivi | ity in the individual enterprise le | · Introd | uction | | | | | |
| | Pro | Productivity measurement approaches at the enterprise level. Productivity of | | | | | | | | | | |
| Unit -2 | ma | materials. Productivity of land, buildings, machines and manpower, Factors | | | | | | | | | | |
| | cor | contributing to productivity improvement Techniques for productivity | | | | | | | | | | |
| | im | oroveme | nt: Intro | duction, W | ork content and ineffective tin | ne, Imp | oroving | | | | | |
| | pro | ductivit | y for red | lucing worl | content, Improving productivit | y by re | ducing | | | | | |
| | ine | ffective | time, Mar | nagement of | productivity | | _ | | | | | |
| | W | ORK ST | TUDY: | | | | | | | | | |
| | Inti | roductio | n, basic pr | ocedure, pre | erequisites of conducting a work stu | ıdy. The | human | | | | | |
| | fac | tor in ap | plication | of work stud | ly: Introduction, management and s | uperviso | r; their | | | | | |
| Unit -3 | role | e in wor | k study, t | he works stu | udy man. The influence of workin | g conditi | ons on | 8 | | | | |
| | WO | rk study | : Introduc | tion, factors | affecting working conditions, occu | ipational | safety | | | | | |
| | anc | i nealth, | fire preve | ention and p | rotection, layout and housekeeping | g, lightni | ng and | | | | | |
| | ciii | nate cor | usion | , noise and | vibrations, ergonomics, arrangem | ent of w | orking | | | | | |
| | | THOP | STUDV. | | | | | | | | | |
| | Ivii | roductic | n to moth | od study on | d the selection of job. Introduction | definiti | on and | | | | | |
| | obi | ective of | f method s | study proce | dure of method study | , uermin | | | | | | |
| | Flo | w and l | handling <i>i</i> | of materials | · Introduction plant layout deve | loning th | ne new | | | | | |
| | lav | out, the | handling | of material | s Tools for recording the movem | ient of v | vorker: | - | | | | |
| Unit -4 | Inti | roduction | n, string c | liagram, flo | w process chart; man type, travel | chart, n | ultiple | 6 | | | | |
| | activity chart. | | | | | | | | | | | |
| | Inti | Introduction, the principles of motion economy, classification of movements, further | | | | | | | | | | |
| | not | es on w | orkplace l | ayout, notes | s on the design of jigs, tools and fin | xtures, m | achine | | | | | |
| | con | ntrols and | d displays | of dials, the | e two handed process chart, Simo c | hart. | | | | | | |
| | W | ORK M | EASURE | MENT: | | | | | | | | |
| Unit -5 | Pur me | pose of asureme | work m nts, Work | easurement sampling: I | , the basic procedure, the techn introduction, basic concept and pro | iques of cedure, | f work | 8 | | | | |

| Time study: rating: Introduction, the quality worker, the average worker, standard rating and standard performance. Predetermined time standards (PTS): Introduction, definition, advantages of PTS system, Criticisms of PTS system, different forms of | |
|--|----|
| PTS system, use of PTS system, and application of PTS system. | |
| Total Hours | 36 |

Text /Reference Books:

- "Work study", ILO, Second Edition, Oxford and IBH Publishing 2010
- "Industrial Engineering and management", O.P. Khanna, Dhanpat Rai Publisher. 2010
- "Industrial Engineering and Production management", Martand Telsang, S. Chand Publisher.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|---|--|---|--|--|---|--|------------|--|--|--|
| Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Sem | ester | Sixth | Subje | ect Title | Computer Networks | | Code | TOE 601 | | | |
| Cours | e Com | ponents | Cr | edits | Contact Hours | L | Т | Р | | | |
| Oper | n Elect | ive - II | | 3 | Contact Hours | 3 | 0 | 0 | | | |
| Examin | nation | Duration | Theory | Practical | WEIGHTAGE·EVALUATION | CWA | MSE | ESE | | | |
| | (Hrs |) | 3 | 0 | | 25 | 25 | 50 | | | |
| Course | Obje | ctives | | | | | | | | | |
| CO 1 Understand the concepts of networking thoroughly. | | | | | | | | | | | |
| CO2 Design a network for a particular application. | | | | | | | | | | | |
| CO3 | Anal | yze the perf | formance of | of the netwo | ork. | | | | | | |
| CO4 | Unde | erstanding o | f transpor | t layer | | | | | | | |
| CO5 | Unde | erstanding o | f Network | t layer | | | | | | | |
| | | - | | | | | | | | | |
| Unit No | . (| Content | | | | | | Hours | | | |
| Unit -1 Introduction to computer networks and the Internet: Application layer: Principles of network applications, The Web and Hyper Text Transfer Protocol, File transfer, Electronic ail, Domain name system, Peer-to-Peer file sharing, Socket programming, Layering concepts. | | | | | | | 8 | | | | |
| Unit -2 | | Switching switch, Cir Crossbar sw networks, I packet swite | in networ cuit Swit vitch and e Packet sw ches, swite | ks: Classifi ching, Tim evaluation o itching, Blo ch fabric, B | cation and requirements of swite ne-division switching, Space-divis f blocking probability, 2-stage, 3-st ocking in packet switches, Three uffering, Multicasting, Statistical N | ches, a g sion swi age and generati fultiplex | generic tching, n-stage ions of ing. | 10 | | | |
| Unit -3 | DescriptionDescriptionUnit -3Transport layer: Connectionless transport - User Datagram Protocol, Connection- oriented transport – Transmission Control Protocol, Remote Procedure Call.Unit -3Congestion Control and Resource Allocation: Issues in Resource Allocation, Queuing Disciplines, TCP congestion Control, Congestion Avoidance Mechanisms and Quality of Sarving | | | | | | | | | | |
| Unit -4 and Quality of Service. Network layer: Virtual circuit and Datagram networks, Router, Internet Protocol, Routing algorithms, Broadcast and Multicast routing Link layer: ALOHA, Multiple access protocols, IEEE 802 standards, Local Area Networks, addressing, Ethernet, Hubs, Switches. | | | | | | | | | | | |
| | | Total Hour | S | | | | | 36 | | | |

Text Reference books:

1. J.F. Kurose and K. W. Ross, "Computer Networking – A top down approach featuring the

2. Internet", Pearson Education, 5th Edition

3. L. Peterson and B. Davie, "Computer Networks – A Systems Approach" Elsevier Morgan

4. Kaufmann Publisher, 5th Edition.

5. T. Viswanathan, "Telecommunication Switching System and Networks", Prentice Hall

6. S. Keshav, "An Engineering Approach to Computer Networking", Pearson Education

7. B. A. Forouzan, "Data Communications and Networking", Tata McGraw Hill, 4th Edition

8. Andrew Tanenbaum, "Computer networks", Prentice Hall

9. D. Comer, "Computer Networks and Internet/TCP-IP", Prentice Hall

10. William Stallings, "Data and computer communications", Prentice Hall

| | | | ELECT | RICAL EN | GINEERING DEPARTMENT | | | |
|--|--|---------------------------------------|-------------------------------------|--|---|---------------------------------|---------------------|------------|
| Course: | - Bachel | or of Tec | chnology (| Electrical I | Engineering) | | | |
| Sem | ester | Sixth | Subje | ect Title | Object Oriented programming an | nd C++ | Code | TOE 602 |
| Cours | e Compo | nents | Cr | edits | Constant House | L | Т | Р |
| Oper | n Elective | e - II | | 3 | Contact Hours | 3 | 0 | 0 |
| Examin | nation Di | ıration | Theory | Practical | WEICHTACE.EVALUATION | CWA | MSE | ESE |
| | (Hrs) | | 3 | 0 | WEIGHTAGE: EVALUATION | 25 | 25 | 50 |
| Course | Objecti | ves | | | | | | |
| CO 1 | Explain methodo | the bene plogy to | efits of obj use. | ect oriented | l design and understand when it is a | an approj | priate | |
| CO2 Apply good programming style and understand the impact of style on developing and maintaining programs. | | | | | | | | |
| CO3 Understand the different models of object oriented programming: abstract data types, encapsulation, inheritance and polymorphism | | | | | | | | |
| CO4 Analyze the Fundamental features of an object oriented language in context to object classes an interfaces, exceptions and libraries of object collections | | | | | | | | ses and |
| CO5 Design object oriented solutions for small systems involving multiple objects. | | | | | | | | |
| | | | | | | | | |
| Unit No | o. Co | ntent | | | | | | Hours |
| Unit -1 | Ob Ag | ject & gregation | classes, n, Abstrac | Links and t classes, G | Associations, Generalization ar eneralization, Multiple Inheritance, | nd Inhei Meta da | ritance, ata. | 6 |
| Unit -2 | Eve Rel | ents and lation of | States, O Object an | perations and Dynamic | nd Methods, Nested state diagrams | s, Concu | rrency, | 8 |
| Unit -3 | Fui | nctional thodolog | Models, E gies, exam | Data flow dia ples and cas | agrams, Specifying Operations, Co se studies to demonstrate methodol | onstraints ogy | , OMT | 8 |
| Unit -4 | t -4 Methodologies, examples and case studies to demonstrate methodology Principles of object oriented programming, Tokens, Expressions, classes, Functions, Constructors, Destructors, Functions overloading, Operator Overloading, I/O Operations. Real life applications, Inheritance Extended Classes, Pointer. Virtual functions, Polymorphisms, Working with files, Class templates, Function templates, Exception handling, String manipulation. Translating object oriented design into implementations. | | | | | | | |
| Unit -5 | Intr ord Bas | roduction linary fil sic system | n to Unix es, conce m adminis | /Linux oper pt of shell, stration. | rating systems. Concept of file sy vi editor, Basicile attributes, conc | vstem, hat the compared of p | andling process, | 6 |
| | To | tal Hour | s | | | | | 36 |

Text Books:

- 1. Rambaugh James etal, "Object Oriented Design and Modeling", PHI-1997
- 2. Balagurusamy E," Object Oriented Programming with C++", TMH, 2001 '
- 3. Sumitabha Das "Unix concepts & application" TMH

References:

- 1. Dillon and Lee, "Object Oriented Conceptual Modeling", New Delhi PHI-1993
- 2. Lipman, Stanley B, JonsceLajoie, C++ Primer Reading", AWL, 1999
- 3. Stephen R. Shah, "Introduction to Object Oriented Analysis and Design", TMH
- 4. Berzin Joseph, "Data Abstraction: the object oriented approach using C + +", McGraw Hill
- 5. Budd, Timothy, "An Introduction to Object Oriented Programming", Pearson 2000

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--------|--|--|--|---|--|--|------------|--|--|
| Course. | :- Bac | helor of Tec | chnology (| (Electrical I | Engineering) | | | | | |
| Sem | ester | Sixth | Subje | ect Title | Industrial Automation | | Code | TOE 603 | | |
| Cours | se Con | nponents | Cr | redits | Contact Hours | L | T | Р | | |
| Ope | n Elec | ctive - II | | 3 | Contact Hours | 3 | 0 | 0 | | |
| Exami | nation | n Duration | Theory | Practical | WFIGHTAGE·EVALUATION | CWA | MSE | ESE | | |
| | (Hr | s) | 3 | 0 | | 25 | 25 | 50 | | |
| Course | e Obje | ectives | | | | | | | | |
| CO1 Describe working of various blocks of basic industrial automation system | | | | | | | | | | |
| CO2 Use various PLC functions and develop small PLC programs | | | | | | | | | | |
| CO3 | Acq | uire the know | wledge of | Distributed | l control system and interfacing w | ith PLC | S | | | |
| CO4 | Acq | uire the kn | owledge | of SCADA | system and interfacing with PLC | s | | | | |
| COF | Con | sider such | aspects of | f the autom | nation system as network comm | unicatio | n, huma | in | | |
| machine interface, safety and protection against interference. | | | | | | | | | | |
| | | | | | | | | | | |
| Unit No |). | Content | | | | | | Hours | | |
| | 1 | Introduction process configuration Centralized Types of communical | on: Autor ntrol syst control, I data ava tion comp | nation syste ems, Evolu Distributed ailable, Anaponents and | ems, Advantages of automation, on ation of Control systems. Single control systems, Open systems, SC alog, Digital, Pulse data, Redu protocols. | Compone e loop c CADA sy undancy. | ents of control, /stems. Data | 10 | | |
| | 2 | Programm Selection of Operator In software. | able Logi f processo terface, s | ic Controlle or, Input/out study of SC | ers: Introduction of Advanced PLC put modules, Interfacing of Input/ ADA software, Interfacing of PLC | C program output d C with So | nming, evices, CADA | 8 | | |
| Distributed Control Systems (DCS): PLC Vs DCS systems, DCS architecture, Local control units, dedicated card controllers, Unit Operations controllers, DCS multiplexers, DCS system integration, Automation Standards, salient features. | | | | | | | 8 | | | |
| | 4 | Supervisor supervisory (RTU), Co subsystem, Data concer | y Contro systems, ommunica test and p ntrator and | ol and Da , Componention subsystem power suppled communic | ta acquisition (SCADA) System ts of SCADA Systems. Remote stem, Protocols, Logic subsystem ly subsystem, Phasor measurement ation, Intelligent Electronic Device Total Hours | ems: Tyj e termina m, termina t Units, es. | pes of al unit ination Phasor | 10 | | |
| | | | | | 10101110015 | | | 50 | | |

Text Books:

- 1. Bela G. Liptak, "Automation Handbook Vol I", CRC Press.
- 2. B.G. Liptak, 'Handbook of Instrumentation- Process Control', 4th edition, 2012
- 3. Gary Dunning, 'Introduction to Programmable logic Controllers', Delmar Publisher, 2009
- 4. Webb & Reis, 'Programmable logic Controllers', 5th edition, Prentice Hall of India, 2009

Reference Books:

- 1. Fundamentals of Supervisory systems, IEEE tutorial
- 2. Statistical Process Control –ISA Handbook

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|--|------------------------|---|--|---|---|---------------------------------------|------------------------------|------------|--|--|--|
| Course: | - Bachel | or of Tea | chnology (| Electrical I | Engineering) | | | | | | |
| Sem | ester | Sixth | Subje | ect Title | Communication Engineerin | ıg | Code | TOE 604 | | | |
| Cours | e Compo | nents | Cr | edits | Contact Hours | L | Т | Р | | | |
| Oper | n Elective | e - II | | 3 | Contact Hours | 3 | 0 | 0 | | | |
| Exami | nation Di | uration | Theory | Practical | WEIGHTAGE·EVALUATION | CWA | MSE | ESE | | | |
| ~ | (Hrs) | | 3 | 0 | | 25 | 25 | 50 | | | |
| Course | Objecti | ves | | | | | | | | | |
| CO 1 | Underst modula | and the tion | fundame | ntals conce | pts of elements of communication | on system | m and i | need of | | | |
| CO2 | Analysi | s of vario | ous analog | modulation | n techniques | | | | | | |
| CO3 Evaluate fundamental communication system parameters, such as bandwidth, power, signal quantization noise ratio, and data rate. | | | | | | | | ignal to | | | |
| CO4 Convert analog signals to digital while satisfying certain specs. | | | | | | | | | | | |
| CO5 Analysis of various digital modulation techniques | | | | | | | | | | | |
| | | | | | | | | | | | |
| Unit No | о. <i>Со</i> | ntent | | | | | | Hours | | | |
| Unit -1 | An det AN cir | nplitude tection of A transm cuits Fre | Modulat f DSB-SC nitters and quency Di | ion: Ampli , SSB and v l receivers, vision multi | itude modulation and detection, over vestigial side band modulation, can super heterodyne receiver, IF an iplexing | Generation rrier acqu mplifiers | on and iisition , AGC | 8 | | | |
| Unit -2 | An mo fre not | gle Mo dulation quency r ise ratio, | dulation: , transmis nodulation noise in A | Basic defi sion bandw n, External M and FM | nitions, Narrow band and widel idth of FM Signals, Generation a noise, internal noise, noise calcula systems. | oand free nd detec ations, si | quency tion of gnal to | 8 | | | |
| Unit -3 Pulse Modulation & Waveform coding Techniques: Introduction, sampling process, Analog Pulse Modulation Systems-Pulse Amplitude Modulation, Pulse width modulation and Pulse Position Modulation, Discretization in time and amplitude, Quantization process, quantization noise, Pulse code Modulation, Differential Pulse code Modulation, Delta Modulation and Adaptive Delta Modulation | | | | | | | | | | | |
| Unit -4Digital Modulation Techniques & Information Theory: Types of digital modulation, waveforms for amplitude, frequency and phase shift keying, methods of generation and detection of ASK, FSK and PSK, comparison of above digital techniques, TDM & PCM, Measure of information, Entropy & Information rate.1Total Hours3 | | | | | | | | 10 | | | |
| | 10 | | 0 | | | | | 50 | | | |

Text Books

- 1. R.P.Singh& S.D. Sapre, "Communication Systems Analog and Digital" Tata McGraw Hill.
- 2. Simon Haykin, "Communication Systems" John Wiley & Sons 4th Edition
- 3. G.Kennedy and B. Davis," Electronic Communication Systems" 4th Edition, Tata McGraw Hill
- 4. Simon Haykin, "Digital Communications" John Wiley & Sons

Reference Readings:

- 1. B.P. Lathi, "Modern Analog & Digital Communication Systems" Oxford University Press.
- 2. Taub& Schilling, "Communication System: Analog and Digital" Tata McGraw Hill.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | |
|---|--|---|---|--|---|-----------------------|---------------------|------------|--|--|
| Course: | - Bach | elor of Tec | hnology (| Electrical E | Engineering) | | | | | |
| Seme | ester | Seventh | Subje | ect Title | Condition Monitoring and Diagr | nostics | Code | TOE 701 | | |
| Cours | se Com | ponents | Cr | edits | Contract Hours | L | Т | P | | |
| Open 1 | Electiv | e Course | | 3 | Contact Hours | 3 | 0 | 0 | | |
| Exami | nation | Duration | Theory | Practical | WEICHTACE.EVALUATION | CWA | MSE | ESE | | |
| | (Hrs |) | 3 | 0 | WEIGHTAGE: EVALUATION | 25 | 25 | 50 | | |
| Course | Obje | ctives | | | | | | | | |
| CO 1 To impart knowledge about diagnostic | | | | | | | | | | |
| CO2 | Understand maintenance and various techniques for condition monitoring | | | | | | | | | |
| CO3 | Asses | sessment of the various health monitoring equipment | | | | | | | | |
| CO4 | Unde | Inderstand different condition monitoring equipment | | | | | | | | |
| CO5 | Asses | Assessment of the various characteristics of machine vibration and hydraulic system | | | | | | | | |
| Unit No | o. Content He | | | | | | | Hours | | |
| Unit -1 | P N b | roductivity, Iaintainabil reakdown a | quality ity vs Ro nalysis. | circles in a eliability, F | maintenance, Reliability, Reliabil Failure analysis, equipment dowr | ity Assu time an | urance, nalysis, | 8 | | |
| Unit -2 | M n C | laintenance aintenance ondition ba | type, Bre , Routine sed maint | eakdown Ma maintena enance syste | aintenance, Corrective Maintenanc nce, Preventive and predictive em, Design out maintenance | e, Oppo mainte | ortunity enance, | 8 | | |
| Unit -3 | E te | quipment h mp. monito | ealth mor | nitoring, Sig kage monito | gnals, Online and Offline monitorioring, Lubricating monitoring. | ng, Visı | al and | 6 | | |
| Unit -4 | F n | errography, 10nitoring, 1 | Spectros noise mon | copy, Crac itoring, sme | k monitoring, Corrosion monito ll/odour monitoring, thermography | ring, thi | ickness | 6 | | |
| Unit -5 | V 0 0 | ibration ch f machine v f C.M techr | aracteristi ibration. C iiques, adv | cs, vibration C.M of lubes vantages. | n monitoring causes, identification and hydraulic systems, C.M of pipe | , measu elines, se | rement lection | 8 | | |
| | of C.M techniques, advantages. | | | | | | | | | |

Text books:

- 1. Mechanical Fault Diagnosis and condition monitoring by R.A. Collacott, Chapman and Hall, London
- 2. Designing Knowledge Based System by T R Addis, Prentice-Hall, New Jersey.

Reference :

- 1. ASM Handbook, Volume 11, Failure Analysis and Prevention, published in 2002
- 2. Handbook of Reliability, Availability, Maintainability and Safety in Engineering Design by Rudolph Frederick Stapelberg, Springer-Verlag London Limited, London
- 3. Maintenance Engineering Handbook, 7th Edition, by R. Keith Mobley (Editor in Chief), McGraw-Hill Companies, Inc.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------|---|---|------------------------------|------------------------------|----------------------|---|------------|---------|--|--|--|--|
| Course: | Course:- Bachelor of Technology (Electrical Engineering) | | | | | | | | | | | |
| Sem | ester | | Subjec | ct Title | IT in Busin | ness | Code | TOE 702 | | | | |
| Cour | rse Compo | onents | Credits | | | L | Т | Р | | | | |
| Open | Elective | Course | 03 | | Contact Hours | 03 | 00 | 00 | | | | |
| Exam | ination D | uration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| | (Hrs) 03 00 EVALUATION 25 25 | | | | | | | | | | | |
| Course | Objectiv | es | | | | | | | | | | |
| CO1 | Understa | anding the c | concept of str | ategic manag | gement | | | | | | | |
| CO2 | Develop | ment of Str | ategic manag | ement thinki | ng. | | | | | | | |
| CO3 | Understa | Inderstanding Electronic commerce and market system | | | | | | | | | | |
| CO4 | Understa | anding of co | orporate IT st | rategy. | | | | | | | | |
| CO5 | Knowled | lge of Impa | ect of IT in co | ompetitive str | ategy. | | | | | | | |
| | | | | | | | | | | | | |
| Unit No. | . Conter | nt | | | | | | Hours | | | | |
| | | | | | | | | | | | | |
| Unit -1 | Busine | ess drivers | IT's Comp | petitive Pote | ntial, Strategic Al | ignment, | Strategic | 08 | | | | |
| | Manag | gement and | Competitive | strategy | | | Y . | | | | | |
| | Rethin | king Busi | ness through | n II Develo | opment a Competi | itive Strateg | gy, Inter | 10 | | | | |
| Unit -2 | organi | zation infoi | rmation syste | m business to | o business system, I | Electronic C | ommerce | 10 | | | | |
| 11 4 2 | | arket Syste | | D 1 ' | | 1 , | | 00 | | | | |
| Unit -3 | Forming a corporate IT strategy, Developing and Information Architecture 08 | | | | | | | | | | | |
| Unit -4 | Incorp of IT in | orating bus | iness innovational business, | tion into the The changin | corporate IT strateg | gy, The chan | ging role | 10 | | | | |
| | Total | Hours | | | | | | 36 | | | | |

Text Book:

1. Cellion, Jack D. "Competitve Advantage Through Information Technology" Mc Graw Hill.

Reference Book:

2. Ttapscott Don, "The Digital Economy" Mc Graw Hill, 1996

| | | | ELECTR | ICAL ENGL | NEERING DEPAR | TMENT | | | |
|--|------------|------------------|------------------|---------------|----------------------|--------------------|-----------------|----------|-------|
| Course | :- Bach | elor of Techn | ology (Electr | ical Enginee | ring) | | | | |
| Sen | nester | Seventh | Subje | ct Title | Bio-Medical Ele | ectronics | Code | TOE | 703 |
| Сог | irse Co | nponents | Cre | dits | Contract House | L | T | P |) |
| Ope | n Electi | ve Course | C | 3 | Contact Hours | 03 | 00 | 00 |) |
| Exan | ninatior | n Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ES | E |
| | (Hr | s) | 03 | 00 | EVALUATION | 25 | 25 | 5(|) |
| Course | e Objec | tives | | | | | | | |
| CO 1 | To fan | niliarize studer | nts with vario | ous medical e | quipment and their t | echnical asp | oects | | |
| CO2 | Under | stand the vario | ous types of the | ansducers an | d electrodes used fo | r biomedica | l applications | , | |
| To introduce students to the measurements involved in some medical equipment (such as: ECG, EEG, | | | | | | | | | |
| 05 | EMG | etc) and patien | t care monito | oring | | | | | |
| CO4 Acquired knowledge about the measurement in respiratory system | | | | | | | | | |
| CO5 | Have a | ı firm understa | inding of the | diagnostic te | chniques. | | | | |
| | | | | | | | | | |
| Unit N | o. Cor | ntent | | | | | | | Hours |
| | Int | roduction: Th | e age of bior | nedical engin | eering, developmen | t of biomedi | cal instrumen | tation, | |
| Unit -1 | man | n instrumenta | tion system | , componen | ts physiological s | ystem of t | he body, Pr | oblem | 8 |
| | enc | ountered in me | easuring a liv | ring system. | | | | | |
| | Tra | insducers & | electrodes: | The transduc | ers & transduction | principles a | active transdu | cers, | |
| | pas | sive transduce | rs, transduce | r for biomedi | cal applications. | | c | | |
| | 501 | irces of bloele | ectric potent | als: Resting | & action potentials, | propagation | i of active pot | tential, | |
| | | e bioelectric po | otentials-ECC | J, EEG, EMC | and evoked respon | ses. | | مليم ملم | |
| Unit -2 | Ele | dla alastrodas | biochemical | tronoducoro | Electrode-Microele | ctrodes Bod | y surface Elec | ctrode, | 12 |
| | Ca | diovescular | Monsurama | talisuuceis, | rdiography FCG | zs, mplifiers e | lactrodae and | loade | |
| | EC | G recorders- | three chan | nel vector o | ardiography -LCO a | mpiners, e | recording (| Holter | |
| | rec | ording) Blood | pressure me | asurements F | alood flow measurer | nent Hearts | sound measure | ement | |
| | 1000 | Julig), Dioou | pressure me | asurements, I | nood now measurer | nont, mourt | sound measure | cincint. | |
| | Me | asurements i | n Respirato | rv system: | Physiology of respi | ratory syste | m measurem | ent of | |
| Unit -3 | bre | athing mechar | nics – Spiro | meter, Respir | atory therapy equir | ments: inha | lators ventila | tors & | 08 |
| | Res | pirators, Hum | idifiers, Neb | ulizers & Asp | pirators. | | | | |
| | Dia | gnostic Tech | niques: Ultr | asonic diagn | osis Eco- cardiogra | aphy, Eco e | ncephalograp | hy, | |
| Unit -4 | oph | thalmic scan | s, X-Ray | & Radio-iso | otope Instrumentati | on, CAT | scan, Emiss | ion | 08 |
| | Con | nputerized To | mography, a | nd MRI. | - | | | | |
| | То | tal Hours | | | | | | | 36 |

Textbooks:

- 1. Khandpur R.S, "Biomedical Instrumentation", TMH
- 2. Cromwell, "Biomedical Instrumentation and Measurements", PHI.

Reference Book:

1. Tompkins, "Biomedical DSP: C language Examples and Laboratory Experiments for the IBM PC", PHI

| | | | ELECT | RICAL ENGI | NEERING DEPART | "MENT | | | | |
|--|---|---|---|-----------------|-------------------------|-----------------|---------------|------------|-----|--|
| Course: | :- Bachelor | of Technolo | gy (Electrical | Engineering) | 1 | | | | | |
| Ser | nester | Seventh | Subjec | ct Title | Fundamentals | of IoT | Code | TOE | 704 | |
| Со | ourse Comp | onents | Cre | dits | Contact Hours | L | Т | Р | 1 | |
| Op | en Elective | Course | 0 | 3 | Contact Hours | 03 | 00 | 00 |) | |
| Frami | nation Dur | ntion (Hrs) | Theory | Practical | WEIGHTAGE:E | CWA | MSE | ES | E | |
| Елити | | <i>uion</i> (1173) | 03 | 00 | VALUATION | 25 | 25 | 50 |) | |
| Course | Objectives | | | | | | | | | |
| CO 1 | Explain th | e terms used | in IoT. | | | | | | | |
| CO2 | Describe l | cey technolog | gies in Internet | of Things. | | | | | | |
| CO3 | Identify co | omponents ne | eeded to provi | de a solution f | or certain applications | | | | | |
| CO4 | Analyze s | ecurity requi | rements in an l | loT system. | | | | | | |
| CO5 Design wireless sensor network architecture and its framework along with WSN applications. | | | | | | | | | | |
| CO6 Understand business models for the Internet of Things. | | | | | | | | | | |
| Unit No. Content Hours | | | | | | | | | | |
| | INTRODUCTION | | | | | | | | | |
| Unit -1 | nit -1 Introduction to Internet of Things: History of IoT, About IoT, Overview and Motivations, Examples of | | | | | | | | | |
| ome i | Applications, Internet of Things Definitions and Frameworks: IoT Definitions, IoT Architecture, General | | | | | | | | | |
| | Observations, ITU-T Views, Working Definition, IoT Frameworks, Basic Nodal Capabilities | | | | | | | | | |
| | FUND | AMENTAL | IoT MECHA | NISMS AND | KEY TECHNOLO | GIES | | | | |
| | Identif | Identification of IoT Objects and Services, Structural Aspects of the IoT, Environment Characteristics, | | | | | | | | |
| Unit -2 | Traffic | Characterist | Isues, Scalability, Interoperation Canabilities, Mobility Support, Davice Dower, Sensor | | | | | | | |
| | Techno | plogies, Devi | ce Intelligence | , Communicat | ion Capabilities, Mob | ility Support, | Device Pow | er, Sensor | | |
| | Techno | Diogy, RFID | lechnology, S | atellite Techn | ology. | | | | | |
| | RADIO DEID: | UFREQUE | Dringinle of I | IFICATION | IECHNOLOGY | om Jaquaa EI | CClobal A | abitaatura | | |
| | Eromo | marke EDCIS | , Finciple of I | ion issues To | ahnological ahallong | elli, issues Er | hollongos I | D for IoT | | |
| Unit -3 | Webo | f Things Wi | reless Sensor N | Jetworks: Hist | ory and context WSN | J Architecture | the node of | connecting | 8 | |
| Omt-5 | nodes | Networking | Nodes Securi | or Communics | ation WSN specific Io | T applications | , the houe, e | · Security | 0 | |
| | OoS (| Configuration | voues, becam | oration appro | aches Data link lave | r protocols | routing nro | tocols and | | |
| | infrast | ucture establ | lishment. | Gradion appro | aches, Data mix lay | n protocols, | routing pro | tocols and | | |
| | RESO | URCE MAN | NAGEMENT | IN THE INT | ERNET OF THING | S | | | | |
| | Cluster | ring. Softwar | re Agents. Cl | ustering Princ | iples in an Internet of | of Things Ar | chitecture. | Design | | |
| TT | Guidel | ines, and Sof | ftware Agents | for Object Rer | presentation, Data Syn | chronization. | Identity por | traval. | 0 | |
| Unit -4 | Identit | y manageme | nt, various ide | entity manage | ment models: Local, | Network, Fee | derated and | global | 8 | |
| | web ic | lentity, user- | centric identit | y managemen | nt, device centric ide | ntity manage | ment and h | nybrid- | | |
| | identit | y managemei | nt, Identity and | l trust. | | | | • | | |
| | INTE | RNET OF T | HINGS PRIV | ACY, SECU | RITY AND GOVER | NANCE | | | | |
| | Vulner | abilities of I | oT, Security re | equirements, T | hreat analysis, Use ca | ases and misu | ise cases, Io | T security | | |
| Unit 5 | tomogr | raphy and lay | yered attacker | model, Identit | y establishment, Acce | ess control, M | essage integ | rity, Non- | Q | |
| Unit -5 | repudia | repudiation and availability, Security model for IoT. | | | | | | | | |
| | Interne | t of Things A | Application: S | mart Metering | Advanced Metering | Infrastructure | e, e-Health I | Body Area | | |
| | Netwo | rks, City Aut | tomation, Auto | motive Applic | cations, Home Autom | ation, Smart (| Cards. | | | |
| | Total | Hours | | | | | | | 36 | |

Text Books

1. Daniel Minoli, "Building the Internet of Things with IPv6 and MIPv6: The Evolving World of M2M Communications", ISBN: 978-1-118-47347-4, Willy Publications

2. Bernd Scholz-Reiter, Florian Michahelles, "Architecting the Internet of Things", ISBN 978-3-642-19156-5 e-ISBN 978-3-642-19157-2, Springer

3. Parikshit N. Mahalle& Poonam N. Railkar, "Identity Management for Internet of Things", River Publishers, ISBN: 978-87-93102-90-3 (Hard Copy), 978-87-93102-91-0 (ebook).

Reference Books

1. HakimaChaouchi, "The Internet of Things Connecting Objects to the Web" ISBN : 978-1- 84821-140-7, Willy Publications

2. Olivier Hersent, David Boswarthick, Omar Elloumi, The Internet of Things: Key Applications and Protocols, ISBN: 978-1-119-99435-0, 2 nd Edition, Willy Publications

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|---|--|---|---|---|------------------------------------|---------|--|--|--|--|
| Course:- | Bachelor of Techno | ology (Electr | ical Enginee | ring) | | | | | | | |
| Seme | ester Eight | Subjec | ct Title | Quality Co | ntrol | Code | TOE 705 | | | | |
| Cour | se Components | Cre | dits | Contact Hours | L | Т | Р | | | | |
| Open | Elective Course | 0 | 3 | Contact Hours | 03 | 00 | 00 | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course | Objectives | | | | | | | | | | |
| CO 1 | Understand the b | asic concept | ts of Quality | v Control (QC). | | | | | | | |
| CO2 | Describe, distingui | sh and use th | e several tecl | hniques and quality | managemen | t tools. | | | | | |
| CO3 | Explain and distinguish the normalisation, homologation and certification activities. | | | | | | | | | | |
| CO4 | Identify the elements that are part of the quality measuring process in the industry. | | | | | | | | | | |
| CO5 | Predict the errors in the measuring process, distinguishing its nature and the root causes. | | | | | | | | | | |
| CO6 | Understand and calculate the correction and uncertainty parameters as a result of an instrument calibration. | | | | | | | | | | |
| Unit | Content | | | | | | Hours | | | | |
| No. | | | | | | | | | | | |
| Unit -1 | Concepts of quality: Quality - Quality control - Quality assurance - Quality management- Quality costs Total Quality Management: Axioms - Management commitment- Deming's approach - Quality council - Customer satisfaction and retention - Employee involvement and empowerment-Suggestion system - Quality circle -Continuous process improvement - Juran's trilogy - PDSA cycle - Kaizen - Six-sigma -Crosby's quality treatment | | | | | | | | | | |
| Unit -2 | Management tools -Quality function | and techniqu deployment | es: Benchma - Quality by | rking - ISO quality design - | management | t systems | 6 | | | | |
| Unit -3 | Failure mode and Fish bone diagram Diagram. | effect analys - Flow chart | sis -Affinity - Run chart - | diagram - Block dia Scatter diagram - T | igram - Paret ree diagram | to chart - - Matrix | 7 | | | | |
| Unit -4 | Diagram. Statistical tools 1-control charts: Basic concepts - Attributes and variables - Random and assignable causes of variations- Patterns of variation - Measures of central tendency and dispersion - Probability distributions: Binomial, Poisson and Normal Control charts for variables : ⁻ X, R and sigma charts - Details of construction and uses Control charts for attributes: p, np, c and u charts - Details of construction and uses (Numerical problems included) | | | | | | | | | | |
| Unit -5 | Statistical tools 2- inspection - OC cu -Bathtub curve - M problems included) | Acceptance rve - Single a /ITBF - OC (| sampling, Re nd double sa curve for Lif | eliability and Life t mpling plans - ATI e testing - System r | esting: Samj - AOQL - Lir eliability (N | pling Vs fe testing umerical | 7 | | | | |
| | I otal Hours | | | | | | 36 | | | | |

Text/ Reference Books:

- Bester Field, Dale H, Carol Boeterfreld Muchna, Glen H, Boeterfreld MeryBoeterfeld-Scare, 2003, Total Quality Management,3rd edition, Pearson, Education, New Delhi.
- Grant.E.L., Stastical Quality Control, McGraw Hill
- Juran J.M, Gryna I.M., Quality Planning and Analysis, Tata McGraw Hill Publishing Company
- Gerals M Smith- 2004, Statistical Process Control and Quality Improvement- 5th edition

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|--|-------------------|------------------|-------------------------|---------------|------------|------------|--|--|--|--|
| Course:- | Bachelor of Tech | nology (Electr | ical Enginee | ring) | | | | | | | |
| Seme | ester Eight | Subje | ct Title | Optical Fi Communica | ber ation | Code | TOE 706 | | | | |
| Cours | se Components | Cre | dits | | L | Т | Р | | | | |
| Open | Elective Course | C | 3 | Contact Hours | 03 | 00 | 00 | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course | Objectives | | | | | | | | | | |
| CO 1 | Understanding I | Block diagram a | and different | types of optical wav | reguides and | merits of | OFC, types | | | | |
| 001 | and propagation | mechanism. | | | | | | | | | |
| CO2 | Analysis of atter | uation, losses a | and polarizati | on for different type | es of optical | fiber | | | | | |
| CO3 | Analysing different optical transmitter sources. | | | | | | | | | | |
| CO4 | Understanding g | enesis of optica | al detectors w | vith noise considerat | tions. | | - | | | | |
| CO5 | Analysis of optical fiber link by integrating optical transmitter and receiver circuits with | | | | | | | | | | |
| | application in multiplexing and optical networking. | | | | | | | | | | |
| CO6 | Successful com | oletion of this c | ourse enables | s students to apply c | oncepts of op | ptical com | munication | | | | |
| T T •4 | to build optical i | | | | | | | | | | |
| Unit | Content | 11. 1 | £ | | A -1 | | Hours | | | | |
| | Introduction: I | Block diagram (| of optical fiber | er communication sy | /stem, Advai | itages of | | | | | |
| | optical fiber communication, Optical fiber waveguides: Structure of optical wave | | | | | | | | | | |
| Unit 1 | guide, Step Index fiber, Graded index Fiber, Single mode, Multimode, light | | | | | | | | | | |
| Unit -1 | skew rays wave theory for optical propagation modes in a planar and cylindrical | | | | | | | | | | |
| | side mode volume single mode fibers cutoff wavelength mode field diameter | | | | | | | | | | |
| | effective refract | ve index and g | roup and more | de delay factor for s | ingle mode f | iber | | | | | |
| | Attenuation in | optical fibers: | Intrinsic and | extrinsic absorption | linear and r | onlinear | | | | | |
| | scattering losses | fiber bend los | ses. Dispersi | on and pulse broade | ning, intram | odal and | | | | | |
| Unit -2 | intermodal dispersion for step and graded index fibers modal noise over all fiber | | | | | | | | | | |
| | dispersion for multimode and monomode fiber. modal birefringence and polarization | | | | | | | | | | |
| | maintaining fibe | rs. | | <i>,</i> 0 | I | | | | | | |
| Unit 2 | Optical Source | s: LED structur | es and Charac | cteristics, LASER, N | d: YAG LA | SER, He | 0 | | | | |
| Unit -5 | Ne Laser, CO2 | Laser, Distribut | ed Feedback | Laser. | | | 0 | | | | |
| | Optical detecto | rs: Requirement | nt for photo d | letections p-n photo | diode, chara | cteristics | | | | | |
| Unit -1 | of photo dete | ctions, p-i-n | and avalan | che photodiodes, | phototransi | stors & | 6 | | | | |
| 0mt -4 | photoconductor | s. Direct detec | ction receive | rs. Performance co | onsiderations | s: Noise | 0 | | | | |
| | sources in optical fiber communication, noise in p-n, p-i-n and APD receivers. | | | | | | | | | | |
| | Receiver struct | ure Optical fib | er communi | cation systems: Print | ncipal compo | onents of | | | | | |
| | an optical fiber communication system, optical transmitter circuits, LED and laser | | | | | | | | | | |
| Unit -5 | drive circuits, optical receiver block diagram, simple circuits for pre-amplifier, | | | | | | | | | | |
| | automatic gain control and equalization, optical system design, Multiplexing, | | | | | | | | | | |
| | Coherent and | noncoherent d | etection, W | DM, OTDM, Intro | oduction to | Optical | | | | | |
| | Total Userra | | | | | | 26 | | | | |
| | 1 otal Hours | | | | | | 56 | | | | |

Text Books

1. Optical fiber Communication: John M.S Senior PHI, 3rd Ed. 2009

Reference Books

- Optical Communication: J. Gowar PHI, 2nd Ed 2002
 Optical fiber Communication: G.E. Keiser Mc Graw-Hill, 4rd Ed. 2010
- 3. Optoelectronics: Wilson & Hawkes PHI, 3rd Ed.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|----------|--|--------------------|------------------|------------------------|----------------|------------|----------------|--|--|--|--|--|
| Course:- | Bachelor of Techno | ology (Electr | ical Enginee | ring) | | | | | | | | |
| Seme | ester Eight | Subje | ct Title | Artificial Intel | ligence | Code | TOE 707 | | | | | |
| Cour | se Components | Cre | edits | Contact Hours | L | T | Р | | | | | |
| Open | Elective Course | 0 |)3 | Contact Hours | 03 | 00 | 00 | | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | | |
| Course | Objectives | | | | | | | | | | | |
| CO 1 | Understand the bas | sics of the the | eory and prac | tice of Artificial Int | elligence. | | | | | | | |
| CO2 | Learn the basics o | f Artificial II | ntelligence pr | ogramming. | | | | | | | | |
| CO3 | Understand various searching techniques use to solve the AI problems. | | | | | | | | | | | |
| CO4 | Apply knowledge | e representa | tion techniq | ues and problem-s | olving strat | egies to | common AI | | | | | |
| C04 | 4 applications. | | | | | | | | | | | |
| CO5 | Build self-learning | and research | n skills to tack | le a topic of interest | t on his/her o | wn or as p | art of a team. | | | | | |
| CO6 | Apply the knowledge of AI and agents in developing multidisciplinary real world projects | | | | | | | | | | | |
| Unit | Content | | Hours | | | | | | | | | |
| | Introduction Intro | icated & | | | | | | | | | | |
| Unit -1 | Intelligent Behavi | anguage, | 6 | | | | | | | | | |
| Unit -1 | automated reasoning visual perception, heuristic algorithm versus solution guaranteed | | | | | | | | | | | |
| | algorithms | | | | | | | | | | | |
| | Understanding | Natural La | inguages Pa | arsing techniques, | context f | ree and | | | | | | |
| Unit_2 | transformational g | grammars, tr | ansition nets | , augmented transi | tion nets, F | illmore's | 8 | | | | | |
| Ont -2 | grammars, Shanks Conceptual Dependency, grammar free | | | | | | | | | | | |
| | analyzers, sentence | e generation, | and translati | on. | | | | | | | | |
| | Knowledge Repre | esentation | | | | | | | | | | |
| Unit -3 | First order predicat | te calculus, H | lorn Clauses, | Introduction to PRC | DLOG, Sema | ntic Nets | 8 | | | | | |
| eme s | Partitioned Nets, | Minskey f | rames, Case | Grammar Theory | , Productio | n Rules | Ũ | | | | | |
| | Knowledgebase, T | he Inference | System, For | ward & Backward I | Deduction | | | | | | | |
| | Expert System | | | | | | _ | | | | | |
| Unit -4 | Existing Systems | (DENDRAI | L, MYCIN), | domain exploration | n, Meta Kno | owledge, | 6 | | | | | |
| | Expertise Transfer | , Self-Explai | ning System | | | | | | | | | |
| | Pattern Recogniti | | | | | | | | | | | |
| TT :. 7 | Introduction to pattern Recognition, Structured Description, Symbolic Description, | | | | | | | | | | | |
| Unit -5 | Machine perception, Line Finding, Interception, Semantic, & Model, Object | | | | | | | | | | | |
| | Identification, Spe | ech Recogni | tion. | | | | | | | | | |
| | Programming La | nguage: Intr | oduction to p | rogramming Langu | age, LISP, P | KULUG | 26 | | | | | |
| | Total Hours | Total Hours 36 | | | | | | | | | | |

Text/ Reference Books:

Charnick "Introduction to Artificial Intelligence." Addision Wesley.
 Rich & Knight, "Artificial Intelligence". TMH
 Winston, "LISP", Addison Wesley.
 Marcellous, "Expert Systems Programming", PHI.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | | | | |
|--------------|---|----------------|---------------|----------------------|---------------|-------------------------|----------|--|--|--|--|--|--|--|--|--|
| Course:- | Bachelor of Techno | ology (Electi | rical Enginee | ering) | | 1 | I | | | | | | | | | |
| Seme | ester Eight | Subje | ct Title | Mechatron | nics | Code | TOE 708 | | | | | | | | | |
| Cour | se Components | Cre | edits | Contact Hours | L | T | P | | | | | | | | | |
| Open | Elective Course | 03 | | | 03 | 00 | 00 | | | | | | | | | |
| Exami | nation Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | | | | | | |
| | (Hrs) | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | | | | | | |
| Course | Objectives | | | | 1. 1 | | | | | | | | | | | |
| <u>CO 1</u> | Construct the block | k diagram of | any physical | mechatronics devic | e used in day | y-to- day l | life. | | | | | | | | | |
| <u>CO2</u> | Calculate the outpu | ut to input re | lation of any | physical model in th | torm of a | transfer fu | inction. | | | | | | | | | |
| <u>CO3</u> | Evaluate the perfor | rmance of an | y physical sy | stem in terms of its | performance | paramete | ers. | | | | | | | | | |
| C04 | Develop the mathematical model of any physical model from any engineering domain. | | | | | | | | | | | | | | | |
| 005 | Content | | | | | | | | | | | | | | | |
| Unit | Content | | | | | | Hours | | | | | | | | | |
| <i>INO</i> . | I | | - f | English Englishing | - f | | | | | | | | | | | |
| | Introduction: 1 | atronics, | | | | | | | | | | | | | | |
| Unit -1 | Integration of | science | 6 | | | | | | | | | | | | | |
| | engineering, Elei | | | | | | | | | | | | | | | |
| | Open-loop and closed-loop system. | | | | | | | | | | | | | | | |
| | Physical and Ma | ions of | | | | | | | | | | | | | | |
| Unit -2 | motion of med | chanical, e | lectrical, p | neumatic and h | ydraulic s | ystems, | 8 | | | | | | | | | |
| | Transforming physical model to mathematical model, Linearization, | | | | | | | | | | | | | | | |
| | Frequency respon | nse. Modell | ing of differ | ent motors and gen | nerators. | ~ | | | | | | | | | | |
| | Control Systems | s: Laplace t | ransformatio | ons, Block diagran | n reduction, | Signal | | | | | | | | | | |
| Unit -3 | flow graph, Pe | erformance | specificatio | ons, Transfer fu | nctions, St | ability, | 8 | | | | | | | | | |
| cint c | Sensitivity of the | e open-loop | o and closed | l-loop systems, T | ypes of cor | troller, | Ũ | | | | | | | | | |
| | Controller design using frequency domain and Laplace domain methods. | | | | | | | | | | | | | | | |
| | Sensors: Displa | cement, Po | osition and | Proximity senso | rs, Flow s | ensors, | | | | | | | | | | |
| | Pressure and force | e sensors, N | Aotion sense | ors, Optical, Mecha | nical and T | hermal | | | | | | | | | | |
| Unit -4 | sensors, selection | n of sensors | | | | | 8 | | | | | | | | | |
| | Actuators in Mechatronics System: Electric actuators, Stepper motors, DC | | | | | | | | | | | | | | | |
| | motors, and AC motors. | | | | | | | | | | | | | | | |
| | Electronic Elem | ligital to | | | | | | | | | | | | | | |
| Unit -5 | analog converter | s, Operatio | nal amplifie | ers, Introduction t | o Microcoi | ntrollers | 6 | | | | | | | | | |
| | and Microproces | sors. | * | | | | | | | | | | | | | |
| | Total Hours | | | | | and Microprocessors. 36 | | | | | | | | | | |

Text Books/ References:

Alciatore, D. G., Histand, M. B., & Alciatore, D. G. Introduction to mechatronics and measurement systems. Tata McGraw-Hill Education.

Bolton, W., Mechatronics: A Multidisciplinary Approach, Pearson Education, New Delhi.

Bishop, R. H. (Ed.). Mechatronics: an introduction. CRC Press.

Nagrath, I. J. and Gopal, M., Control System Engineering, New AgeInternational.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|---|------------|--|---------------------|----------------|---------------------------------|----------------|-------------|--------------|--|--|--|
| Course | :- Bachelo | or of Techn | ology (Electr | ical Enginee | ring) | | | | | | |
| Sem | iester | Eight | Subje | ct Title | Expert System Logic | & Fuzzy | Code | TOE 801 | | | |
| Cou | rse Comp | onents | Cre | edits | Contact Hours | L | T | P | | | |
| Oper | n Elective | Course | 04 | | Contact Hours | 03 | 00 | 00 | | | |
| Exan | ination D | Duration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course | e Objectiv | es | | | | | | | | | |
| CO 1 Understand expert systems and their tools with methodology for building expert system. | | | | | | | | | | | |
| CO^2 | Understa | nd fuzzy log | gic basics and | d operations, | Fuzzy arithmetic an | d representa | tions and | classical | | | |
| 002 | logic. | | | | | | | | | | |
| CO3 | To equip | students wi | th the knowl | edge and skil | ls in logic programr | ning | | | | | |
| CO4 | To under | stand the w | orking of cor | ntroller based | on classical as well | as fuzzy log | gic | | | | |
| CO5 | To under | stand contir | ngency analy | sis, and appli | cations like control | of inverted p | endulum | and aircraft | | | |
| | control | | | | | | | | | | |
| | | | | | | | | | | | |
| Unit | Conten | nt i i i i i i i i i i i i i i i i i i i | | | | | | Hours | | | |
| <i>INO</i> . | Ermont | Crustoma | Ten Arno al en otte | m e Taolas | Introduction Chang | atomiation A | | | | | |
| | Experi | - Systems - | - Introductio | ing Noture of | introduction, Chara | clefistics, A | cquiring, | | | | |
| Unit -1 | tools | FMVCIN | EXPERT O | PSS POSIE | Block board arch | itecture Ru | le based | 06 | | | |
| | System | is Associati | ive nets and s | symbolic cor | nuting | inecture, Ru | le Daseu | | | | |
| | Buildi | ng an Exne | rt System: B | uilding an Ex | peting. opert System Diffici | ulties in deve | elopment | | | | |
| Unit -2 | of ES. | Common pi | tfalls, pitfalls | during devel | lopment. Expert sys | tems in mark | tet place. | 08 | | | |
| | comme | ercial implic | cations. | 8 | r y r y | | · · · · · , | | | | |
| | Introd | uction of I | Fuzzy Sets a | nd Relation | s: Crisp set-vaguer | ness, uncerta | inty and | | | | |
| Linit 2 | imprec | ision, fuzz | zy set-fuzzy | operators, | properties, crisp | versus fuz | zy sets, | 10 | | | |
| Unit -5 | represe | ntation of f | uzzy sets, fu | zzy complem | ents, union, intersec | ction, combin | nation of | 10 | | | |
| | operato | ors, crisp an | d fuzzy relati | ions, composi | itions of fuzzy relati | ons. | | | | | |
| | Fuzzy | Logic and | Controllers | : Fuzzy logi | c-classical logic-fuz | zzy proposit | ions and | | | | |
| | quantif | iers, linguis | stic hedges, | fuzzification | and its types de-fu | zzification | methods, | | | | |
| Unit -1 | data ba | se, rule bas | e, inference e | engine structu | re of FLC. | | | 12 | | | |
| Omt -4 | Applic | ations of E | xpert Syster | ns and Fuzz | y Logic: Application | ons of expert | systems | 12 | | | |
| | and fu | zzy logic in | n ac and dc | drives. VAF | R control, continger | ncy analysis | , control | | | | |
| | system | -inverted pe | endulum and | aircraft contr | ol application. | | | | | | |
| | Total I | Hours | | | | | | 36 | | | |

Text Books:

- 1. Timothy J. Ross, Fuzzy Logic with Engineering Applications, International edition, McGraw Hill, 2000.
- 2. Donald A. Waterman, A guide to Expert System, Addison Wiley, 1999.

References:

- 1. Dan W. Patterson, Introduction to AI and expert systems, Pearson education.
- 2. John yen and rezalansari, Fuzzy logic. Fuzzy logic intelligence, control and information-Pearson's education.

| Course:- | Bachelor | of Techno | ology (Electr | ical Enginee | ring) | | | | |
|----------|---|--------------|----------------|---------------|--|--------------|-----------|---------|--|
| Seme | rster | Eight | Subject Title | | Intelligent Sensors and Instrumentation | | Code | TOE 802 | |
| Cours | se Compo | nents | Cre | dits | Contract House | L | Т | Р | |
| Open | Elective C | Course | 0 | 3 | Contact Hours | 03 | 00 | 00 | |
| Exami | nation Du | ıration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | |
| | (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | |
| Course | Objective | S | | | | | | | |
| CO 1 | Acquire | basic know | vledge about | sensors and | actuators. | | | | |
| CO2 | Understand the fundamental principles of various types of sensors and their general characteristics, terminologies, sensing and transduction principles | | | | | | | | |
| CO3 | Acquire | knowledge | e about the fa | brication tec | hniques of sensors | | | | |
| CO4 | Understa | and the tec | hniques used | to interface | computers with vari | ous sensors | | | |
| CO5 | design intelligent sensors as per IEEE standard | | | | | | | | |
| | | | | | | | | | |
| Unit | Content | | | | | | | Hours | |
| No. | | | | | | | | | |
| Unit -1 | Basic co | ncept, sem | niconductor s | ensors, MEM | I sensors, actuators | | | 06 | |
| Unit -2 | Network | k sensor, sr | nart sensor & | z sensor netw | orking, neuro senso | rs, Bio-sens | ors. | 06 | |
| | Sensor | material, | fabrication | of sensors: | thin /relatively th | nick film d | lepositon | | |
| Unit -3 | techniqu | ies, wet / d | lry etching te | echniques, hi | gh aspect ratio tech | niques of fa | brication | 08 | |
| | of senso | r. | | | | | | | |
| Unit -4 | Intellige | nt instrum | entation syst | em, soft com | puting techniques, | coding techr | niques of | 08 | |
| | binary si | ignals. | | | | | | 00 | |
| Unit -5 | IEEE 14 | 51 Standa | rds, STIM, T | EDS Calibra | tion, NAC Network | technologie | s. | 08 | |
| | Total H | ours | | | | | | 36 | |

References:

- 1. Science and engineering of microelectronics fabrication by Stephen A, Campbell,
- 2. Intelligent instrumentation by Bhuyan
- 3. Modern inertial sensors and system by Amitava Bose, Somnath Puri, Paritosh Banerjee.

| | ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-------------|--|--|---|---|--|--|--------------------------------------|---------|--|--|--|--|
| Course:- | Bachelor | of Techno | ology (Elec | trical Engine | eering) | | | | | | | |
| Seme | ster | Eighth | Subje | ct Title | Engineering Eco | nomics | Code | TOE 803 | | | | |
| Cours | se Compo | nents | Cr | edits | Contact Hours | | T | Р | | | | |
| Open | Elective C | Course | | 03 | Contact Hours | 03 | 00 | 00 | | | | |
| Exami | nation Du | ration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | | |
| | (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | | |
| Course (| Objective, | S | | | | | | | | | | |
| CO 1 | Apply kn problems | nowledge s | of mathema | atics, econom | ics, and engineering pri | nciples to sol | lve engine | ering | | | | |
| CO2 | Underst capital in | and the m | ajor capabi | lities and lim | itations of cash flow and | alysis for eva | luating pro | oposed | | | | |
| CO3 | Recognize, formulate, analyze and solve cash flow models in practical situations. | | | | | | | | | | | |
| CO4 | Develop the ability to account for time value of money using engineering economy factors and formulas | | | | | | | | | | | |
| CO5 | Communicate the results of the modeling process to management and other non-specialist users in a lucid, informative manner (graphs, tables and/or text). | | | | | | | | | | | |
| Unit No. | Content | | | | | | | | | | | |
| Unit -1 | Introduction to Economics: Definitions, Nature, Scope, Difference between Microeconomics & Macroeconomics | | | | | | | | | | | |
| Unit -2 | Theory equilibri Elasticit Theory & charac | of Deman um betwee ty: elastic: of produc cteristics o | nd & Supp en demand ity of dem etion: prod f Land, Lal | ly: meaning, & supply. and, price e action function our, capital o | determinants, law of de lasticity, income elasti on, meaning, factors of & entrepreneur). | emand, law o city, cross e production, (| f supply, elasticity, (meaning | 10 | | | | |
| Unit -3 | Law of long run cost. Break e Markets Monopo | variable j cost, fixed ven analy s: meanin ly, Monop | proportion l cost, varia sis: meanin g, types of polistic Con | s & law of r ble cost, total g, explanatio f markets & pletion, Olig | returns to scale Cost: cost, average cost, marg n their characteristics (copoly) | meaning, sho ginal cost, op Perfect Con | ort run & portunity | 10 | | | | |
| Unit -4 | Nationa price, Gl Basic ed measure Inflation | I Income: NP, GDP, conomic s to reduce n: meaning | meaning, s NNP,NDP problems e Unemploy g, types, ca | stock and flow Personal inc Poverty-mea ment: meani uses, measure | w concept, NI at current ome, disposal income. ning, absolute & relating, types, causes, remedies to control | t price, NI at tive poverty lies | constant , causes, | 10 | | | | |
| | ι υιάι Π | iour s | | | | | | 30 | | | | |

Text Books/ References

- 1. Engineering Economics, R.Paneerselvam, PHI publication
- 2. Principles and Practices of Management by L.M.Prasad.
- **3.** Fundamentals of Management: Essential Concepts and Applications, Pearson Education, Robbins S.P. and Decenzo David A.
- 4. Economics: Principles of Economics, N Gregory Mankiw, Cengage Learning
- 5. Principles of Management by Tripathy and Reddy
- 6. Modern Economic Theory, By Dr. K. K. Dewett& M. H. Navalur, S. Chand Publications

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | |
|-----------------------------------|---|--|--|---|---|---|--|---------------|--|--|--|
| Seme | ester | Eight | Subject Title | | Advanced W Technolo | elding | Code | TOE 804 | | | |
| Cour | se Comp | onents | Cre | edits | Contract Hours | L | Т | Р | | | |
| Open | Elective | Course | 0 |)3 | Contact Hours | 03 | 00 | 00 | | | |
| Exami | nation D | ouration | Theory | Practical | WEIGHTAGE: | CWA | MSE | ESE | | | |
| | (Hrs) | | 03 | 00 | EVALUATION | 25 | 25 | 50 | | | |
| Course | Objectiv | es | | | | | | | | | |
| CO 1 | Course of the | e Outcome process. | 1: Understa | and the weld | ing, its process cla | assification | and other | · limitations | | | |
| CO2 | Course weldin | e Outcome g techniqu | 2: Understates. | and and revie | ew brief technolog | gies aspect o | of conven | tional | | | |
| CO3 | Course Outcome 3: Understand and analyze different advance welding techniques and their applications | | | | | | | | | | |
| CO4 | Course Outcome 4: Analyze and understand welding design and metallurgical aspects | | | | | | | | | | |
| CO5 | Course Outcome 5: Understand principle and application of arc fusion welding | | | | | | | | | | |
| 000 | Course Outcome 6: Describe different testing and inspection methods of welding joints | | | | | | | | | | |
| 000 | and the | eir applicat | tions. | | | | | | | | |
| TT T | | | | | | | | ** | | | |
| Unit No | Content | | | | | | | | | | |
| 110. | Introd | uction: De | finition. Clas | ssification. A | pplication. Advanta | iges & limit | ations of | | | | |
| Unit -1 | Welding, Selection guidelines for relevant welding process, Comparison of welding with other joining methods Brief technological review of conventional welding techniques: Oxy-acetylene gas welding, Introduction to welding torch & filler rod, Principle of arc welding, Inert Gas Welding (MIG and TIG),Submerged arc welding (SAW), Atomic hydrogen arc welding, Various types of Resistance Welding, Soldering, Brazing techniques and their applications, Types of welding electrodes, Classification and coding of mild steel and low alloy steel electrodes, American system and Indian system, types of fluxes | | | | | | | | | | |
| Unit -2 | Used for fusion welding, soldering and brazing.Advanced welding Techniques I:Principle, techniques, problems (limitations), working and applications of advanced welding techniques such as Plasma Arc Welding (Key-hole and non-keyhole techniques), Electro-slag welding, Laser beam welding, Electron beam welding, Ultrasonic welding, Friction stir welding, Explosive welding, Underwater welding, Welding of Plastics and Dissimilar metals , Need and Technology of Cladding, Hard-facing , Surfacing, Oxy-acetylene gas cutting, Electric | | | | | | | | | | |
| Unit -3 Unit -4 | Weldin heat flo Angula Weldab or Hyd propert equival Princip functio space a defects effects | ng Design a bow, relative r distortion, bility, Welda drogen-inducties of steel lent based s ble of Arc n and ioniz and anode s , detection on weld pr | nd Metallur plate thickne , control of d ability tests si ced cracking l, Carbon-eq statistical eva fusion weld ation potent spot, Various c roperties, Hy | gical Factors ss factor, tran listortion, We uch as Hot-cra g test, Effect uivalent and <u>aluation of ho</u> ing: Electron ial, Cathode s Modes of N auses & ren drogen embr | : Heat input, net he hisverse shrinkage, lo ldability, Effects of acking test, the Murr of carbon conten its relation with c <u>ot-cracking tendence</u> s thermionic emissis spot, cathode space Metal Transfer in a nedy, Heat-affected ittlement, Phenome | at utilized in ongitudinal sl alloying eler ex test, Cold- t on struct ooling rate, y. ion, thermion e, arc colum rc welding, l-zone (HAZ non of Arc | melting, hrinkage, ments on cracking ture and Carbon- nic work n, anode Welding C) and its blow, its | 8 | | | |

| Unit -5 | Inspection Methods - Testing and inspection of welding joints, Methods used for Inspection of welding, Hardness test, Visual, Magnetic particle, Fluorescent particle, Ultrasonic, Radiography, methods of Inspection. Basic welding symbols and location of weld, Measurement of heat input in arc welding, Heat flow. | 5 |
|---------|---|----|
| | Total Hours | 36 |

Reference Books:

- O.P. Khanna, A Text Book of Welding Technology, Dhanpat Rai Publications , New Delhi
- Dr. Parmar R.S. ,Welding Engineering and technology; Khanna Publisher.
- P. N. Rao, Manufacturing Technology (Foundary, Forming and Welding), Tata McGraw-Hill Publications, New Delhi.
- Amithab Ghosh, Manufacturing Science, Tata McGraw-Hill Publications, New Delhi.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|-----------------------------------|--|---|--|--|--|-----------------------------------|-------------------------|------------|--|--|--|--|
| Course: | - Ba | chelor of T | echnolog | y (Electrica | l Engineering) | | | | | | | |
| Seme | ster | Eight | Subje | ect Title | Robotics | | Code | TOE 805 | | | | |
| Course | Con | nponents | Cr | redits | Contact Hours | L | Т | Р | | | | |
| Open E | lectiv | ve Course | 3 | | Contact Hours | 3 | 0 | 0 | | | | |
| Exa Dura | umin ation | ation (Hrs) | Theory | Practical | WEIGHTAGE:EVALUATION | CWA | MSE | ESE | | | | |
| | | | 3 | 0 | | 25 | 25 | 50 | | | | |
| Course | Obj | iectives | | | | | | | | | | |
| CO 1 | CO 1 Understand different aspects in the field of robotics and its interdisciplinary approach. | | | | | | | | | | | |
| CO2 | De | velop the o | direct and | l inverse ki | inematic models of different rob | otic con | ıfigurati | ons. | | | | |
| CO3 | An | alyze diffe | erential m | notion and | singularities in robotic manipula | tors. | | | | | | |
| CO4 | De | velop dyna | amic moo | lel of robot | tic manipulators. | | | | | | | |
| CO5 | CO5 Develop trajectory planning and control schemes for robotic manipulators. | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Unit No |). | Content | | | | | | Hours | | | | |
| Unit -1 | | INTROD evolution, manipulat | UCTIO , characte cors, actu | N: Definiti eristics of re ators, sense | on, classification of robots, histo obots, industrial robot anatomy, ors, end-effectors, robot configu | orical rations. | | 6 | | | | |
| Unit -2 | | MANIPU transform inverse ki | LATOR ation, De | R KINEM enavit—Ha | ATICS: Coordinate frames, map rtenberg notation, direct kinema | ping an tic mod | id eling, | 8 | | | | |
| Unit -3 | | MANIPU and rotatic Jacobian, | ULATOR on, Deriv inverse J | COLIFFERE vatives of h facobian, si | ENTIAL MOTION: Differentia omogeneous transformations, m ingularities, static force and mor | al transla anipula nent ana | ation tor alysis. | 8 | | | | |
| Unit -4 | -4 MANIPULATOR DYNAMICS: Acceleration of a rigid body, mass distribution, Newton's and Euler's equations, iterative Newton-Euler formulation, Lagrange-Euler formulation of manipulator dynamics. | | | | | | | | | | | |
| Unit -5 | | TRAJEC MANIPU space sche force and | TORY I ULATOR eme, intru torque co | PLANNIN RS: Introdu oduction to ontrol. | G AND CONTROL OF ction to trajectory planning tech control schemes, control law pa | niques, artitioni | joint- ng, | 7 | | | | |
| | | Total Hou | rs | | | | | 36 | | | | |

Text/ Reference Books

- 1. Craig, J. J. (2005). Introduction to robotics: mechanics and control. Pearson Prentice Hall
- 2. Niku, S. B. (2001). Introduction to robotics: analysis, systems, applications. Prentice Hall.
- 3. Mittal, R. K., & Nagrath, I. J. (2003). Robotics and control. New Delhi: Tata McGraw-Hill.

| ELECTRICAL ENGINEERING DEPARTMENT | | | | | | | | | | | | |
|--|---|--|---|---|--|---|--------------------------|------------|--|--|--|--|
| Course: | - Bachel | or of Tec | hnology (| Electrical E | Engineering) | | | | | | | |
| Sem | ester | Eight | Subject Title | | Mobile Computing | | Code | TOE 806 | | | | |
| Cours | e Compo | nents | Cr | edits | Contract Hours | L | Т | Р | | | | |
| Open l | Elective C | Course | | 3 | Contact Hours | 3 | 0 | 0 | | | | |
| Examir | nation Di | ıration | Theory | Practical | WEIGHTAGE·EVALUATION | CWA | MSE | ESE | | | | |
| | (Hrs) | | 3 | 0 | | 25 | 25 | 50 | | | | |
| Course | Objecti | ves | | | | | | | | | | |
| CO 1 Exemplify the concepts, techniques, protocols and architecture employed in wireless local area networks, cellular networks, and Adhoc Networks based on the standards | | | | | | | | | | | | |
| CO2 | CO2 Describe and analyze the network infrastructure requirements to support mobile devices and users. | | | | | | | | | | | |
| CO3 Design and implement mobile applications to realize location-aware computing | | | | | | | | | | | | |
| CO4 Asses the important issues and concerns on security and Data management | | | | | | | | | | | | |
| CO5 Development of various scenarios for mobile computing system. | | | | | | | | | | | | |
| CO6 Evaluate the concepts of mobile agents and mobile Adhoc algorithms with the help of NS2. | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Unit No | . Co | ntent | | | | | | Hours | | | | |
| Unit -1 | Intr cor hie | roduction ncept, GS rarchical | n, issues in SM: air-int , handoffs | n mobile con terface, char , channel al | mputing, overview of wireless telep nnel structure, location managemer location in cellular systems, CDM | phony: co nt: HLR- A, GPRS | cellular -VLR, 6 S | | | | | |
| Unit -2 | Wi To app app | reless No oth, Wire plications plication | etworking eless multi s, data bro environm | , Wireless L ple access p adcasting, N ent, applicat | AN Overview: MAC issues, IEEE protocols, TCP over wireless, Wire Mobile IP, WAP: Architecture, prot tions | 802.11, less tocol stac | Blue ck, | 8 | | | | |
| Unit -3 | Da clu | ta manag stering fo | ement iss or mobile | ues, data rep wireless net | plication for mobile computers, ada tworks, File system, Disconnected | aptive operatio | ns | 8 | | | | |
| Unit -4 | Mo mo | bile Age bile com | ents computing en | uting, securi vironment. | ity and fault tolerance, transaction J | processir | ng in | 6 | | | | |
| Unit -5 | Ad rou sou Ter app | Hoc net ting (GS tree routi mporary plications | works, loc R), Destir ng (DSR) ordered ro | calization, M nation seque , Ad Hoc or puting algor | AC issues, Routing protocols, glo enced distance vector routing (DSD a demand distance vector routing (A ithm (TORA), QoS in Ad Hoc Net | bal state DV), Dyn AODV), works, | amic | 8 | | | | |
| | Total Hours | | | | | | | | | | | |

Text/ Reference Books:

J. Schiller," Mobile Communications", Addison Wesley.
 A. Mehrotra, "GSM System Engineering".
 M. V. D. Heijden, M. Taylor, "Understanding WAP", Artech House