

8.	$I = \int \frac{\sec^2 x}{(1 - \tan x)^2} dx$ <p>Put $1 - \tan x = t \Rightarrow \sec^2 x dx = -dt$</p> $I = -\int \frac{dt}{t^2} = \frac{1}{t} + C = \frac{1}{1 - \tan x} + C$ <p style="text-align: center;">OR</p> $I = \int_0^1 x(1-x)^n dx$ $= \int_0^1 (1-x) \cdot x^n dx = \int_0^1 (x^n - x^{n+1}) dx$ $= \left[\frac{x^{n+1}}{n+1} - \frac{x^{n+2}}{n+2} \right]_0^1$ $= \frac{1}{n+1} - \frac{1}{n+2} \text{ or } \frac{1}{(n+1)(n+2)}$	$\frac{1}{2}$ $1\frac{1}{2}$ $\frac{1}{2} + \frac{1}{2}$ $\frac{1}{2}$
9.	$y = b \cos(x + a)$ $\Rightarrow \frac{dy}{dx} = -b \sin(x + a)$ $\frac{d^2y}{dx^2} = -b \cos(x + a)$ $\Rightarrow \frac{d^2y}{dx^2} = -y$ <p>or $\frac{d^2y}{dx^2} + y = 0$</p>	$\frac{1}{2}$ 1 $\frac{1}{2}$
10.	$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 4 & -1 & 8 \\ 0 & -1 & 1 \end{vmatrix} = 7\hat{i} - 4\hat{j} - 4\hat{k}$ <p>Required unit vector = $\frac{(\vec{a} \times \vec{b})}{ \vec{a} \times \vec{b} }$</p>	1



	$= \frac{1}{9}(7\hat{i} - 4\hat{j} - 4\hat{k})$ <p style="text-align: center;">OR</p> $(\vec{a} + \lambda\vec{b}) \perp \vec{c} \Rightarrow (\vec{a} + \lambda\vec{b}) \cdot \vec{c} = 0$ $\Rightarrow [(2 - \lambda)\hat{i} + (2 + 2\lambda)\hat{j} + (3 + \lambda)\hat{k}] \cdot (3\hat{i} + \hat{j}) = 0$ $\Rightarrow 3(2 - \lambda) + 1 \cdot (2 + 2\lambda) = 0 \Rightarrow \lambda = 8$	<p style="text-align: center;">1</p> <p style="text-align: center;">$\frac{1}{2}$</p> <p style="text-align: center;">$\frac{1}{2}$</p> <p style="text-align: center;">1</p>
11.	$P(A/B) = \frac{P(A \cap B)}{P(B)} = \frac{P(A) P(B)}{P(B)}$ $= 0.3$ <p style="text-align: center;">OR</p> $\text{Required probability} = \frac{3}{5} \times \frac{3}{7} + \frac{2}{5} \times \frac{4}{7} = \frac{17}{35}$	<p style="text-align: center;">1</p> <p style="text-align: center;">1</p> <p style="text-align: center;">1+1</p>
12.	$\text{Required probability} = 1 - P(\text{problem is not solved})$ $= 1 - P(A' \cap B' \cap C')$ $= 1 - P(A') \cdot P(B') \cdot P(C')$ $= 1 - \frac{1}{2} \times \frac{2}{3} \times \frac{3}{4} = \frac{3}{4}$	<p style="text-align: center;">1</p> <p style="text-align: center;">$\frac{1}{2}$</p> <p style="text-align: center;">$\frac{1}{2}$</p>
13.	<p style="text-align: center;">SECTION C</p> <p>For reflexive: As $ab = ba$ $\Rightarrow (a, b) R(a, b) \quad \therefore R$ is reflexive</p> <p>For symmetric: Let $(a, b) R (c, d)$ $\Rightarrow ad = bc$ $\Rightarrow cb = da$ $\Rightarrow (c, d) R(a, b) \quad \therefore R$ is symmetric</p>	<p style="text-align: center;">}</p> <p style="text-align: center;">1</p> <p style="text-align: center;">}</p> <p style="text-align: center;">1</p>



	<p>For transitive:</p> <p>Let $a, b, c, d, e, f \in \mathbb{N}$</p> <p>Let $(a, b) R(c, d)$ and $(c, d) R(e, f)$</p> <p>$\Rightarrow ad = bc$ and $cf = de$</p> <p>$\Rightarrow d = \frac{cf}{e}$</p> <p>$\therefore a\left(\frac{cf}{e}\right) = bc$</p> <p>$\Rightarrow acf = bce \Rightarrow af = be$</p> <p>$\Rightarrow (a, b) R(e, f) \quad \therefore R$ is transitive</p> <p>Since R is reflexive, symmetric and transitive $\therefore R$ is an equivalence relation.</p> <p style="text-align: center;">OR</p> <p>Let $x_1, x_2 \in \mathbb{R} - \{2\}$</p> <p>Let $f(x_1) = f(x_2)$</p> <p>$\Rightarrow \frac{x_1}{x_1 - 2} = \frac{x_2}{x_2 - 2} \Rightarrow x_1(x_2 - 2) = x_2(x_1 - 2)$</p> <p>$\Rightarrow x_1 = x_2$</p> <p>$\Rightarrow f$ is one-one.</p> <p>Now, $g \circ f(x) = g(f(x)), \quad x \in \mathbb{R} - \{2\}$</p> $= g\left(\frac{x}{x-2}\right)$ $= \frac{2\left(\frac{x}{x-2}\right)}{\frac{x}{x-2} - 1} = x$	<p>$1\frac{1}{2}$</p> <p>$\frac{1}{2}$</p> <p>2</p> <p>2</p>
14.	<p>Put $x = \cos 2\theta \Rightarrow \theta = \frac{1}{2} \cos^{-1} x$</p> <p>LHS = $\tan^{-1}\left(\frac{\sqrt{1+\cos 2\theta} + \sqrt{1-\cos 2\theta}}{\sqrt{1+\cos 2\theta} - \sqrt{1-\cos 2\theta}}\right)$</p>	<p>1</p> <p>$\frac{1}{2}$</p>



	$= \tan^{-1} \left(\frac{\cos \theta + \sin \theta}{\cos \theta - \sin \theta} \right)$ $= \tan^{-1} \left(\frac{1 + \tan \theta}{1 - \tan \theta} \right) = \tan^{-1} \left(\tan \left(\frac{\pi}{4} + \theta \right) \right)$ $= \frac{\pi}{4} + \theta = \frac{\pi}{4} + \frac{1}{2} \cos^{-1} x = \text{RHS}$	1 $\frac{1}{2}$ 1
15.	<p>LHS: $R_1 \rightarrow R_1 - R_2, R_2 \rightarrow R_2 - R_3$</p> $= \begin{vmatrix} 0 & x-y & x^2-y^2 \\ 0 & y-z & y^2-z^2 \\ 1 & z & z^2 \end{vmatrix}$ $= (x-y)(y-z) \begin{vmatrix} 0 & 1 & x+y \\ 0 & 1 & y+z \\ 1 & z & z^2 \end{vmatrix}$ <p>Expanding along C_1</p> $= (x-y)(y-z)(z-x) = \text{RHS}$	2 1 1
16.	$x^y \cdot y^x = x^x$ $\Rightarrow y \log x + x \log y = x \log x$ <p>differentiate both sides w.r.t. x,</p> $\left(y \cdot \frac{1}{x} + \log x \cdot \frac{dy}{dx} \right) + \left(x \cdot \frac{1}{y} \cdot \frac{dy}{dx} + \log y \cdot 1 \right) = x \cdot \frac{1}{x} + \log x \cdot 1$ $\Rightarrow \frac{y}{x} + \log \left(\frac{y}{x} \right) - 1 = - \left(\log x + \frac{x}{y} \right) \cdot \frac{dy}{dx}$ $\Rightarrow \frac{dy}{dx} = \frac{1 - \frac{y}{x} - \log \left(\frac{y}{x} \right)}{\log x + \frac{x}{y}} \text{ or } \frac{y}{x} \left[\frac{x + x \log x - y - x \log y}{y \log x + x} \right]$ <p style="text-align: center;">OR</p> $\frac{dx}{d\theta} = 3a \sec^2 \theta \cdot \sec \theta \tan \theta$	1 2 1 1



	$\frac{dy}{d\theta} = 3a \tan^2 \theta \cdot \sec^2 \theta$ $\frac{dy}{dx} = \frac{\left(\frac{dy}{d\theta}\right)}{\left(\frac{dx}{d\theta}\right)} = \sin \theta$ <p>Also,</p> $\frac{d^2y}{dx^2} = \cos \theta \cdot \frac{d\theta}{dx}$ $= \frac{\cos \theta}{3a \tan \theta \sec^3 \theta} \text{ or } \frac{\cos^5 \theta}{3a \sin \theta}$	1 1 1
17.	$y = a \cos (\log x) + b \sin (\log x)$ $\frac{dy}{dx} = \frac{-a \sin (\log x)}{x} + \frac{b \cos (\log x)}{x}$ $\Rightarrow x \cdot \frac{dy}{dx} = -a \sin (\log x) + b \cos (\log x)$ <p>differentiate both sides again w.r.t x,</p> $x \cdot \frac{d^2y}{dx^2} + \frac{dy}{dx} \cdot 1 = \frac{-a \cos (\log x)}{x} - \frac{b \sin (\log x)}{x}$ $\Rightarrow x \frac{d^2y}{dx^2} + \frac{dy}{dx} = -\frac{y}{x}$ $\Rightarrow x^2 \frac{d^2y}{dx^2} + x \frac{dy}{dx} + y = 0$	1 $\frac{1}{2}$ $1 \frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$
18.	<p>Given $ay^2 = x^3$</p> <p>differentiate both sides wrt x</p> $a \cdot 2y \frac{dy}{dx} = 3x^2 \Rightarrow \frac{dy}{dx} = \frac{3x^2}{2ay}$ $\therefore \text{ Slope of tangent at } (am^2, am^3) = \frac{3(am^2)^2}{2a(am^3)} = \frac{3}{2}m$	1 1



	<p>Equation of tangent is</p> $y - am^3 = \frac{3}{2}m(x - am^2)$ $\Rightarrow 3mx - 2y = am^3$	}	2
19.	<p>Put $\sin x = t \Rightarrow \cos x \, dx = dt$</p> $I = \int \frac{dt}{(t+1)(t+2)}$ $= \int \left(\frac{1}{t+1} - \frac{1}{t+2} \right) dt$ $= \log t+1 - \log t+2 + C$ $= \log \sin x + 1 - \log \sin x + 2 + C \quad \text{or} \quad \log \left \frac{\sin x + 1}{\sin x + 2} \right + C$		1 1 $1\frac{1}{2}$ $\frac{1}{2}$
20.	$I = \int_0^{\pi} \frac{x \sin x}{1 + \cos^2 x} dx \quad \dots(1)$ $I = \int_0^{\pi} \frac{(\pi - x) \cdot \sin x}{1 + \cos^2 x} dx \quad \dots(2)$ <p>Adding (1) and (2)</p> $2I = \int_0^{\pi} \frac{\pi \sin x}{1 + \cos^2 x} dx$ $I = \frac{\pi}{2} \int_0^{\pi} \frac{\sin x}{1 + \cos^2 x} dx$ <p>Put $\cos x = t \Rightarrow -\sin x \, dx = dt$</p> $\therefore I = \frac{\pi}{2} \int_{-1}^1 \frac{dt}{1+t^2}$ $= \frac{\pi}{2} [\tan^{-1} t]_{-1}^1 = \frac{\pi^2}{4}$		1 $\frac{1}{2}$ $\frac{1}{2}$ 1 $\frac{1}{2} + \frac{1}{2}$



21.	<p>Given equation can be written as</p> $x dx = ye^y \sqrt{1+x^2} dy$ $\Rightarrow \int \frac{x}{\sqrt{1+x^2}} dx = \int y \cdot e^y dy$ $\Rightarrow \sqrt{1+x^2} = e^y (y - 1) + C$ <p>when $y = 1, x = 0 \Rightarrow C = 1$</p> <p>$\therefore$ Required solution is $\sqrt{1+x^2} = e^y (y - 1) + 1$</p> <p style="text-align: center;">OR</p> <p>Given differential equation can be written as</p> $\frac{dy}{dx} = \frac{y}{x} + \frac{1}{\cos\left(\frac{y}{x}\right)}$ <p>Put $\frac{y}{x} = v$ i.e. $y = vx$</p> $\Rightarrow \frac{dy}{dx} = v + x \cdot \frac{dv}{dx}$ <p>Given equation becomes</p> $v + x \frac{dv}{dx} = v + \frac{1}{\cos v}$ $\Rightarrow \int \cos v dv = \int \frac{dx}{x}$ $\Rightarrow \sin v = \log x + c$ $\Rightarrow \sin\left(\frac{y}{x}\right) = \log x + c$	<p>1</p> <p>1+1</p> <p>$\frac{1}{2}$</p> <p>$\frac{1}{2}$</p> <p>$\frac{1}{2}$</p> <p>1</p> <p>$\frac{1}{2}$</p>
22.	<p>A(1, 2, -1), B(3, -1, 0), C(2, 3, 2), D(4, 0, 3)</p> $\overline{AB} = 2\hat{i} - 3\hat{j} + \hat{k}, \overline{AC} = \hat{i} + \hat{j} + 3\hat{k}, \overline{AD} = 3\hat{i} - 2\hat{j} + 4\hat{k}$	<p>$1\frac{1}{2}$</p>



	$\text{Consider} = [\overrightarrow{AB} \ \overrightarrow{AC} \ \overrightarrow{AD}] = \begin{vmatrix} 2 & -3 & 1 \\ 1 & 1 & 3 \\ 3 & -2 & 4 \end{vmatrix} = 2(10) + 3(-5) + 1(-5) = 0$ <p>\Rightarrow A, B, C and D are coplanar</p>	<p>1+1</p> <p>$\frac{1}{2}$</p>
23.	<p>Let equation of line is $\vec{r} = (2\hat{i} + 3\hat{j} - \hat{k}) + \lambda(a\hat{i} + b\hat{j} + c\hat{k})$</p> <p>here, $3a + 4b + 2c = 0$... (1)</p> <p>$3a - 2b - 2c = 0$... (2)</p> <p>Solving (1) and (2)</p> $\frac{a}{-8+4} = \frac{-b}{-6-6} = \frac{c}{-6-12} = \mu$ <p>$\Rightarrow \frac{a}{2} = \frac{b}{-6} = \frac{c}{9} = -2\mu$</p> <p>$\therefore$ Required equation of line is</p> $\vec{r} = (2\hat{i} + 3\hat{j} - \hat{k}) + \lambda(2\hat{i} - 6\hat{j} + 9\hat{k})$	<p>1</p> <p>1</p> <p>1</p> <p>1</p>
24.	<p style="text-align: center;">SECTION D</p> <p>$A = -2 \neq 0 \Rightarrow A^{-1}$ exists</p> <p>Now, $A_{11} = -1, A_{12} = 8, A_{13} = -5$</p> <p>$A_{21} = 1, A_{22} = -6, A_{23} = 3$</p> <p>$A_{31} = -1, A_{32} = 2, A_{33} = -1$</p> $\text{adj } A = \begin{bmatrix} -1 & 1 & -1 \\ 8 & -6 & 2 \\ -5 & 3 & -1 \end{bmatrix}$ $A^{-1} = \frac{1}{ A } \cdot \text{adj } A = \frac{-1}{2} \begin{bmatrix} -1 & 1 & -1 \\ 8 & -6 & 2 \\ -5 & 3 & -1 \end{bmatrix}$ <p>Given system of equations can be written as $AX = B$,</p>	<p>$\frac{1}{2}$</p> <p>$2\frac{1}{2}$</p> <p>1</p>



$$\text{where } X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ and } B = \begin{bmatrix} 5 \\ 10 \\ 9 \end{bmatrix}$$

$$\text{Now } AX = B \Rightarrow X = A^{-1}B$$

$$= \frac{-1}{2} \begin{bmatrix} -1 & 1 & -1 \\ 8 & -6 & 2 \\ -5 & 3 & -1 \end{bmatrix} \begin{bmatrix} 5 \\ 10 \\ 9 \end{bmatrix}$$

$$= \frac{-1}{2} \begin{bmatrix} -4 \\ -2 \\ -4 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$$

$$\therefore x = 2, y = 1, z = 2$$

OR

$$A = IA$$

$$\Rightarrow \begin{bmatrix} 3 & -1 & 1 \\ -15 & 6 & -5 \\ 5 & -2 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot A$$

$$R_1 \rightarrow \frac{R_1}{3}$$

$$\Rightarrow \begin{bmatrix} 1 & -\frac{1}{3} & \frac{1}{3} \\ -15 & 6 & -5 \\ 5 & -2 & 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot A$$

$$R_2 \rightarrow R_2 + 15R_1, R_3 \rightarrow R_3 - 5R_1$$

$$\Rightarrow \begin{bmatrix} 1 & -\frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 0 \\ 0 & -\frac{1}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & 0 & 0 \\ 5 & 1 & 0 \\ -\frac{5}{3} & 0 & 1 \end{bmatrix} \cdot A$$

$$R_1 \rightarrow R_1 + \frac{1}{3}R_2, R_3 \rightarrow R_3 + \frac{1}{3}R_2$$

1

 $\frac{1}{2}$ $\frac{1}{2}$

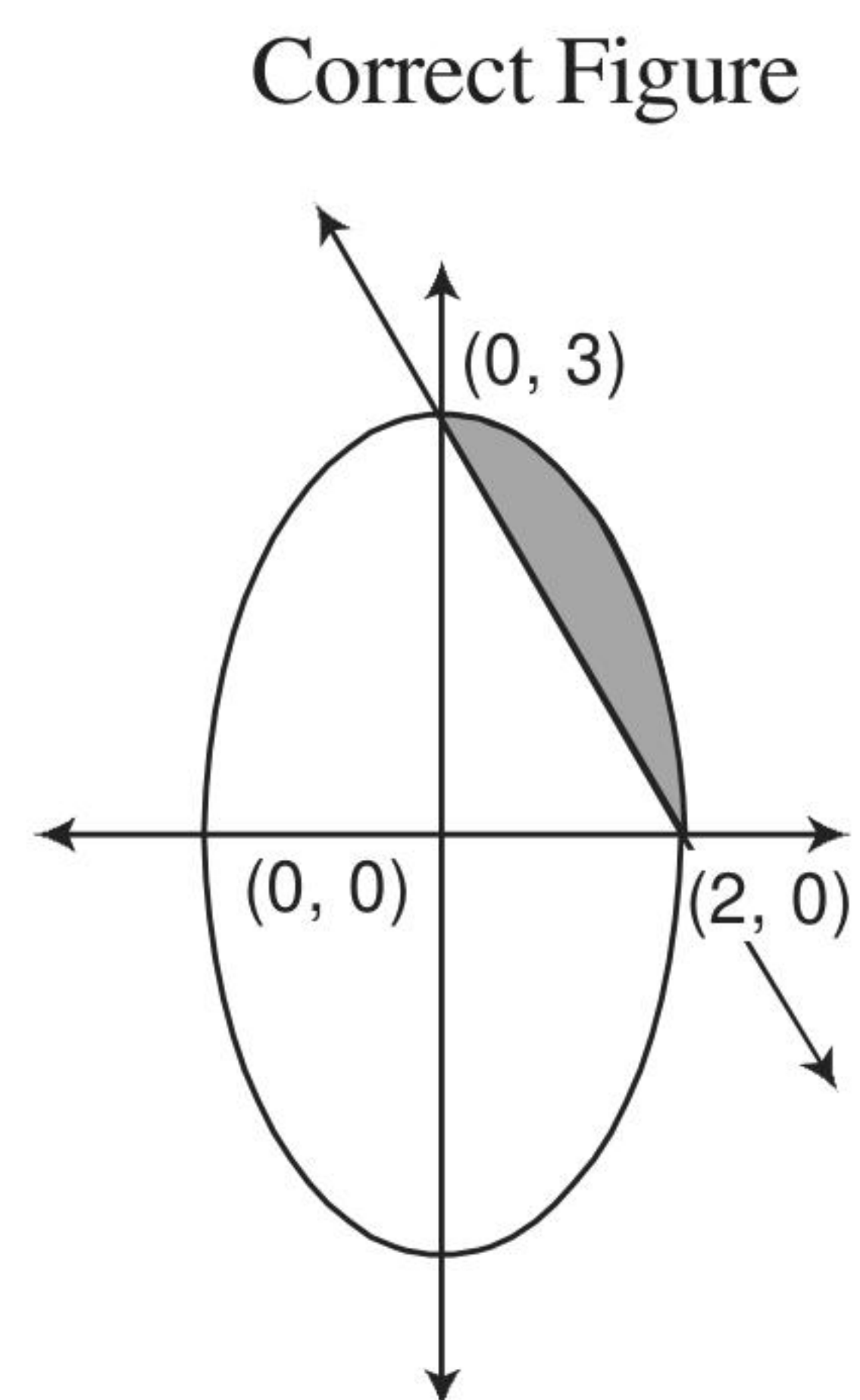
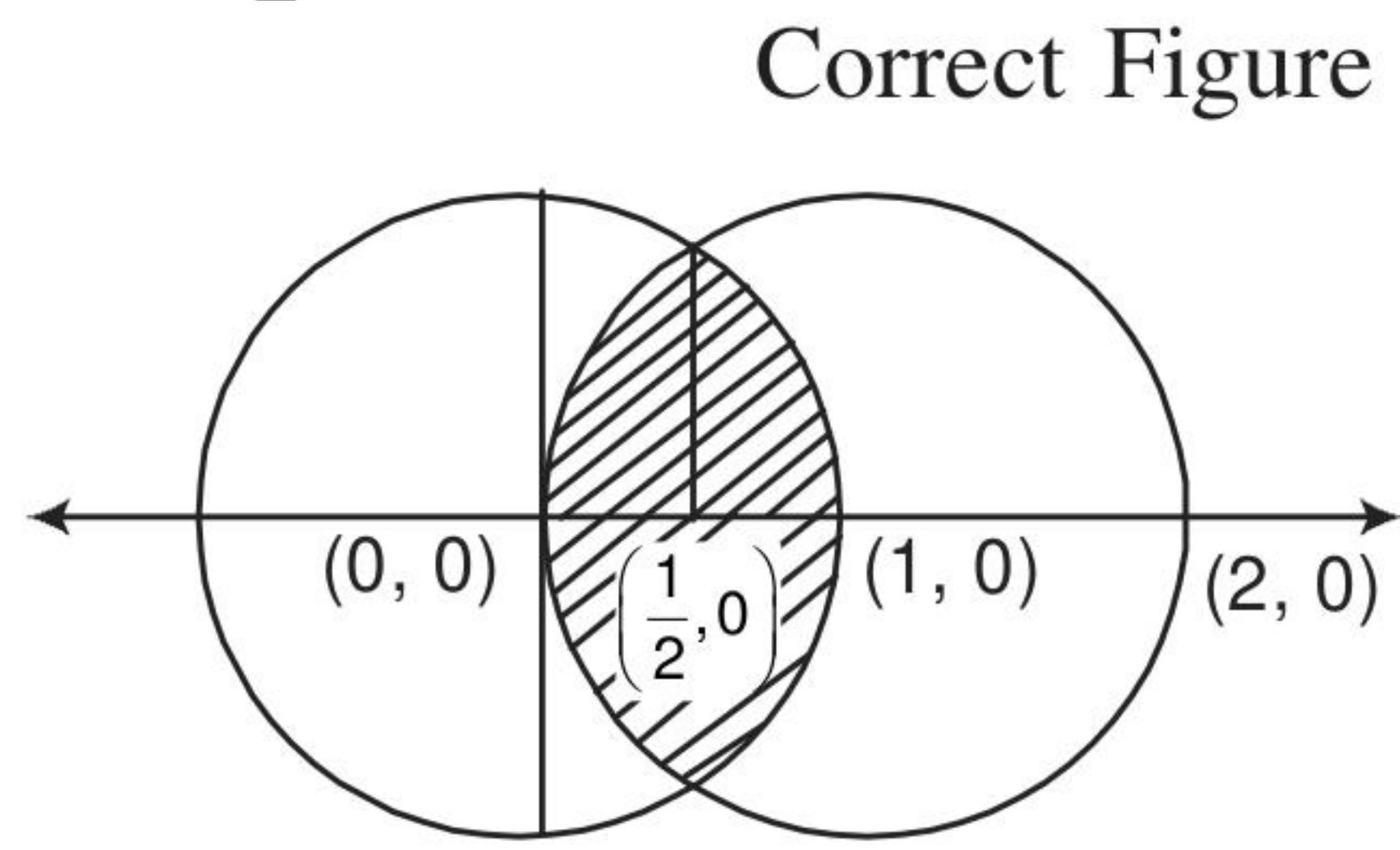
1

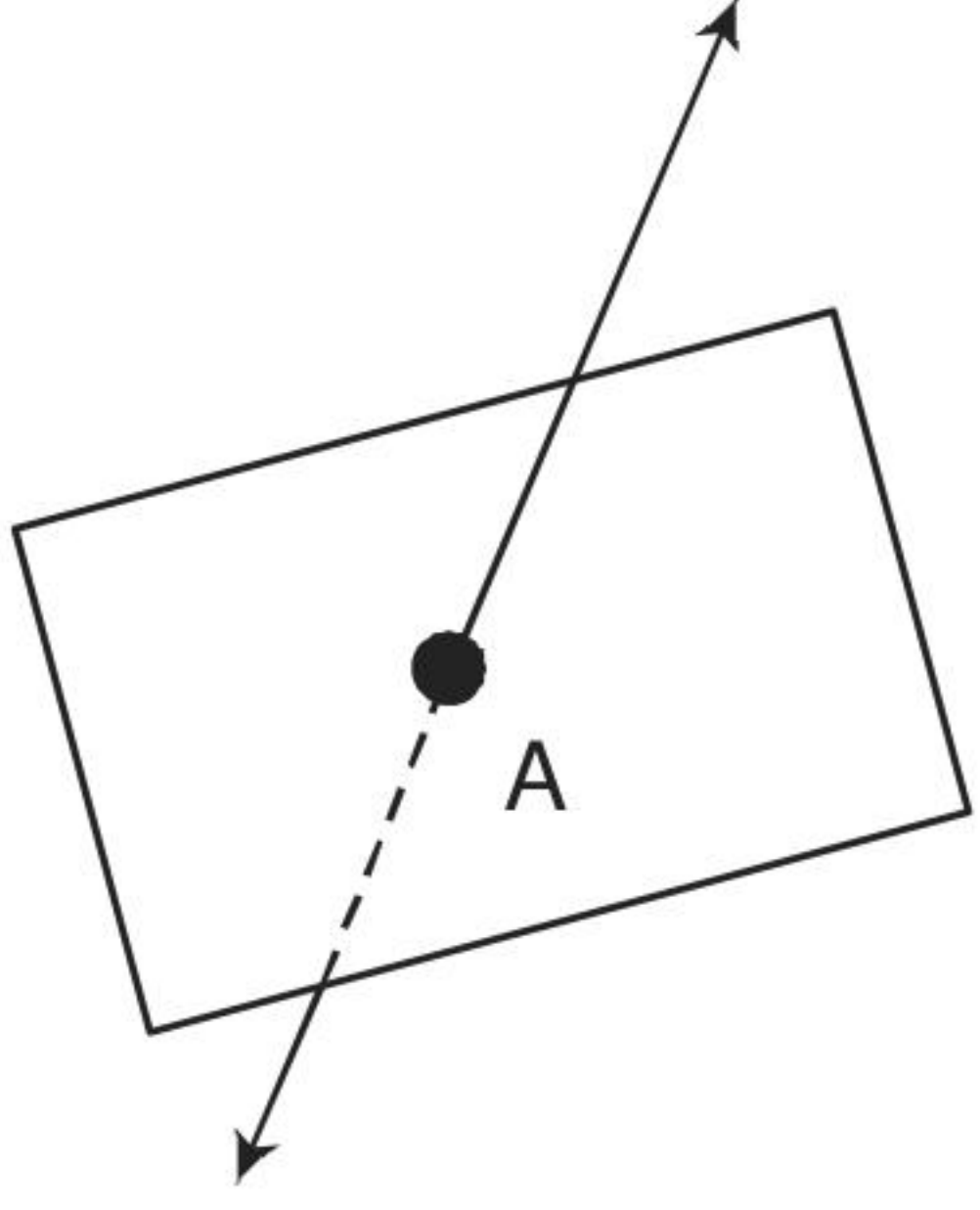
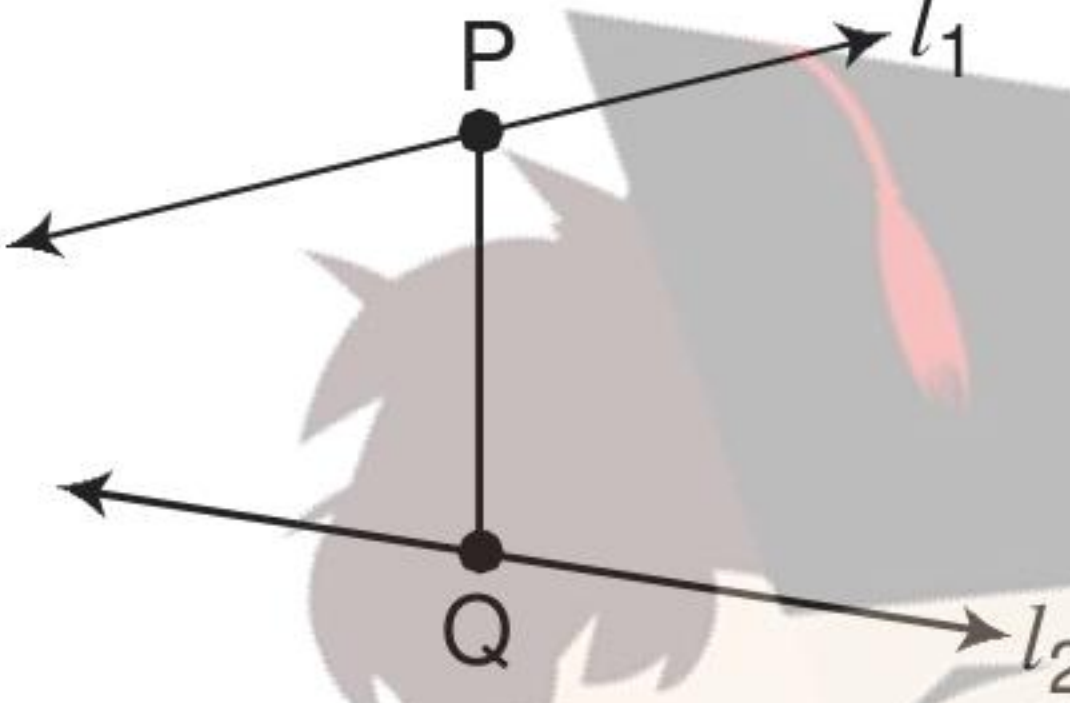


	$\Rightarrow \begin{bmatrix} 1 & 0 & \frac{1}{3} \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 2 & \frac{1}{3} & 0 \\ 5 & 1 & 0 \\ 0 & \frac{1}{3} & 1 \end{bmatrix} \cdot A$ <p>$R_3 \rightarrow 3R_3$</p> $\Rightarrow \begin{bmatrix} 1 & 0 & \frac{1}{3} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & \frac{1}{3} & 0 \\ 5 & 1 & 0 \\ 0 & 1 & 3 \end{bmatrix} \cdot A$ <p>$R_1 \rightarrow R_1 - \frac{1}{3}R_3$</p> $\Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & -1 \\ 5 & 1 & 0 \\ 0 & 1 & 3 \end{bmatrix} \cdot A$ <p>$\Rightarrow A^{-1} = \begin{bmatrix} 2 & 0 & -1 \\ 5 & 1 & 0 \\ 0 & 1 & 3 \end{bmatrix}$</p>	4
25.	<p>Let Q(x, y) be the nearest point to P(1, 2)</p> <p>Minimize $s = \sqrt{(x-1)^2 + (y-2)^2}$</p> <p>Let $l = s^2 = (x-1)^2 + (y-2)^2$</p> <p>$\Rightarrow l = x^2 + y^2 - 2x - 4y + 5 \quad \dots(1)$</p> <p>Also, $x^2 + y^2 = 80 \quad \dots(2)$</p> <p>from (1) and (2), $l = 85 - 2x - 4\sqrt{80 - x^2}$</p> <p>$\frac{dl}{dx} = -2 - 4 \cdot \frac{1}{2\sqrt{80 - x^2}}(-2x) = -2 + \frac{4x}{\sqrt{80 - x^2}}$</p> <p>$\frac{dl}{dx} = 0 \Rightarrow x = 4, -4$ (rejected)</p>	1 1 1



	$\frac{d^2l}{dx^2} = \frac{4\sqrt{80-x^2} + \frac{4x^2}{\sqrt{80-x^2}}}{80-x^2} > 0 \text{ at } x=4$ <p>$\therefore (4, 8)$ is the nearest point.</p>	1 1
26.	<p>x-coordinate of the point of intersection of given circles is $\frac{1}{2}$.</p> <p>Required Area = $4 \cdot \int_0^{1/2} \sqrt{1-(x-1)^2} dx$</p> $= 4 \left[\frac{x-1}{2} \cdot \sqrt{1-(x-1)^2} + \frac{1}{2} \sin^{-1}(x-1) \right]_0^{1/2}$ $= 4 \left[\frac{-1}{4} \times \frac{\sqrt{3}}{2} + \frac{1}{2} \sin^{-1}\left(\frac{-1}{2}\right) - \frac{1}{2} \sin^{-1}(-1) \right]$ $= \frac{2\pi}{3} - \frac{\sqrt{3}}{2}$ <p>OR</p> <p>Given equation of ellipse $\frac{x^2}{4} + \frac{y^2}{9} = 1$</p> <p>and equation of line $\frac{x}{2} + \frac{y}{3} = 1$</p> <p>Point of intersection (2, 0) and (0, 3)</p> <p>Required Area = $\int_0^2 \frac{3}{2} \sqrt{4-x^2} dx - \int_0^2 \frac{3}{2} (2-x) dx$</p> $= \frac{3}{2} \left[\frac{x}{2} \sqrt{4-x^2} + 2 \sin^{-1}\left(\frac{x}{2}\right) \right]_0^2 + \frac{3}{2} \cdot \left[\frac{(2-x)^2}{2} \right]_0^2$ $= \frac{3}{2} (2 \sin^{-1} 1) + \frac{3}{4} (-4)$ $= \frac{3\pi}{2} - 3$	1 1 1 2 1 1 1 1 2 1



27.		<p>Given line $\frac{x-8}{4} = \frac{y-1}{1} = \frac{z-3}{8} = \lambda$</p> <p>Any point on it is $(4\lambda + 8, \lambda + 1, 8\lambda + 3)$</p> <p>Let A $(4\lambda + 8, \lambda + 1, 8\lambda + 3)$</p> <p>A lies on plane $2x + 2y + z = 3$</p> $\therefore 2(4\lambda + 8) + 2(\lambda + 1) + (8\lambda + 3) = 3$ $\Rightarrow \lambda = -1$ $\therefore A(4, 0, -5)$ <p>II part: Let angle between line and plane be θ.</p> <p>Then, $\sin \theta = \frac{4(2) + 1(2) + 8(1)}{\sqrt{16+1+64} \sqrt{4+4+1}} = \frac{2}{3}$</p> $\Rightarrow \theta = \sin^{-1}\left(\frac{2}{3}\right)$ <p>OR</p>  <p>Let $P(3\lambda + 7, 2\lambda + 5, \lambda + 3)$ and $Q(2\mu + 1, 4\mu - 1, 3\mu - 1)$</p> <p>Now, d.r.'s. of PQ = $3\lambda - 2\mu + 6, 2\lambda - 4\mu + 6, \lambda - 3\mu + 4$</p> <p>According to question,</p> $\frac{3\lambda - 2\mu + 6}{2} = \frac{2\lambda - 4\mu + 6}{2} = \frac{\lambda - 3\mu + 4}{1}$ $\Rightarrow \lambda + 2\mu = 0 \text{ and } 2\mu = 2 \Rightarrow \mu = 1$ $\Rightarrow \lambda = -2\mu$ $\therefore \mu = 1, \lambda = -2$ $\therefore P(1, 1, 1) \text{ and } Q(3, 3, 2)$ $PQ = \sqrt{(3-1)^2 + (3-1)^2 + (2-1)^2} = \sqrt{4+4+1} = 3$ <p>Equation of PQ is $\frac{x-1}{2} = \frac{y-1}{2} = \frac{z-1}{1}$</p>	1 2 1 $\frac{1}{2}$ $\frac{1}{2}$ 1 1 1 1
28.	<p>Let number of chairs be x and number of tables be y.</p> <p>Maximize $z = 40x + 60y$</p>		1



	<p>Subject to following constraints:</p> $x + y \leq 50$ $\frac{x}{2} + y \leq 40$ $x \geq 0, y \geq 0$ <table border="1" data-bbox="405 1448 1041 1739"> <thead> <tr> <th>Corner point</th> <th>$z = 40x + 60y$</th> </tr> </thead> <tbody> <tr> <td>A(50, 0)</td> <td>2000</td> </tr> <tr> <td>B(20, 30)</td> <td>2600</td> </tr> <tr> <td>C(0, 40)</td> <td>2400</td> </tr> </tbody> </table> <p>Number of chairs manufactured = 20 Number of tables manufactured = 30 Maximum profit = ₹ 2,600</p>	Corner point	$z = 40x + 60y$	A(50, 0)	2000	B(20, 30)	2600	C(0, 40)	2400	<p>2</p> <p>2</p> <p>1</p>
Corner point	$z = 40x + 60y$									
A(50, 0)	2000									
B(20, 30)	2600									
C(0, 40)	2400									
<p>29.</p>	<p>Let E_1: Transferred ball is green E_2: Transferred ball is red A: Green ball is found</p> <p>Here, $P(E_1) = \frac{2}{6}, P(E_2) = \frac{4}{6}$</p> <p>$P(A/E_1) = \frac{6}{9}, P(A/E_2) = \frac{5}{9}$</p>	<p>1</p> <p>1</p> <p>1</p>								

Using Baye's theorem.

$$P(E_1/A) = \frac{P(E_1) \cdot P(A/E_1)}{P(E_1) \cdot P(A/E_1) + P(E_2) \cdot P(A/E_2)}$$

$$= \frac{\frac{2}{6} \times \frac{6}{9}}{\frac{2}{6} \times \frac{6}{9} + \frac{4}{6} \times \frac{5}{9}}$$

$$= \frac{12}{12+20} = \frac{3}{8}$$

2

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