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# INDIAN COAST GAURD Exam

**Previous Paper** 

## Simplifying **Government Exams**



#### **ME1315**

#### ELECTRICAL ENGINEERING Paper - 2 Series

SLNo.: 413229

SATING BUILDS



Max. Marks: 300

Duration: 150 Minutes

INSTRUCTIONS TO CANDIDATES

- Please check the Test Booklet immediately on opening and ensure that it contains all the 150 multiple choice questions printed on it.
- Separate Optical Mark Reader (OMR) Answer Sheet is supplied to you along with the Question Paper Booklet. The OMR Answer sheet consists of two copies i.e., the Original Copy (Top Sheet) and Duplicate Copy (Bottom Sheet). The OMR sheet contains Registered Number/Hall Ticket Number, Subject/ Subject Code, Booklet Series, Name of the Examination Centre, Signature of the Candidate and Invigilator etc.,
- 3. If there is any defect in the Question Paper Booklet or OMR answer sheet, please ask the invigilator for replacement.
- 4. Since the answer sheets are to be scanned (valued) with Optical Mark Scanner system, the candidates have to USE BALL POINT PEN (BLUE/BLACK) ONLY for filling the relevant blocks in the OMR Sheet including bubbling the answers. Bubbling with Pencil / Ink Pen Gel Pen is not permitted in the examination.
- 5. The Test Booklet is printed in four (4) Series, viz. A or B or C or D. The Series A or B or C or D is printed on the right-hand corner of the cover page of the Test Booklet. Mark your Test Booklet Series in Part C on side 1 of the Answer Sheet by darkening the appropriate circle with Blue/Black Ball point pen.

Example to fill up the Booklet series

If your test Booklet Series is A, please fill as shown below:









[P.T.O.

- The algebraic sum of voltages in any closed path of network is equal to (2) Zero (1) One (4) Infinity (3) Two The minimum number of wattmeters required to measure 3-phase power is (4) 0 In a maximum power transfer theorem the internal resistance must be 3) (1) Equal to internal resistance (2) Equal to zero (3) Equal to load resistance (4) Greater than internal resistance Specific resistance of material is measured in  $(2) \cdot \Omega/m$ (1)  $\Omega$ -m (4)  $m^2/\Omega$  $\Omega$ -m<sup>2</sup> (3) At  $t = 0^+$  an inductor with zero initial conditions acts as (2) Short circuit (1) Open circuit (4) Discharging (3) Charging The Laplace transform of t.eat is  $(2) 1/(s^2 + a)$ (1) s/(s + a)(4)  $1/(s^2 - a)$ (3)  $1/(s-a)^2$ In two wattmeter method of power measurement when power factor is unity, the readings of two wattmeters W<sub>1</sub> and W<sub>2</sub> are (1)  $W_1 > W_2$
- 8) Let 'b' is a branch, 'n' is the node in the graph of network theory then the number of chords is equal to
  - (1) b-n-1

(2)  $W_1 < W_2$ (3)  $W_1 = W_2$ 

(4)  $W_1$  or  $W_2 = 0$ 

(2) b-n+1

(3) b + n + 1

(4) b \* n - 1

9)	The	reciprocity theorem is applicable for		
	(1)	Only multisource network		and and
	(2)	Multisource with time varying elemen	its	
	(3)	Only single source network		
	(4)	Single source with time varying eleme	ents	Independent must be
10)		frequency at which a series RLC cir-	cuit r	esonates is dependent on the
	(1)	R, L and C	(2)	L and C
	(3)	R and L	(4)	C and R
11)	The	phase angle between the inductor curr	rent a	nd the applied voltage is
)		90°	(2)	0°
	(3)	180°	(4)	45°.
	(0)			
10)	D	72 XV I (0 is the newson expressi	on fo	r 2 phase system then phase
12)		$\sqrt{3}$ V <sub>L</sub> I <sub>L</sub> cos $\varphi$ is the power expressi	011 10	1 3-phase system, then phase
		e φ is the angle between		
		Line voltage and line current		A minductor
	(2)	Phase voltage and phase current		imalia (E)
	(3)	Line voltage and phase current		
	(4)	Phase voltage and line current		*
12)	TC 1	is delivering maninum payo	m to 1	and then the afficiency is
13)		e source is delivering maximum powe		0%
	(1)	100%	(2) (4)	50%
	(3)	75%	(4)	3070
				11-1 manisters of 20 and 20
14)		amp source is connected across two	para	ilel resistors of 312 and 212
		current flow in $2\Omega$ resistor is	(2)	1
	(1)	6 amps	(2)	4 amps
	(3)	5 amps	(4)	2 amps
15)	For	a RL circuit, $R = 3.14\Omega$ and $L = 1$	lH co	onnected across 220v, 50Hz
	supp	bly, the quality factor is		on algorithms and the second
	(1)	314.16	(2)	
	(3)	50.001	(4)	1

<ul> <li>16) A dielectric medium is said to be linear if <ul> <li>(1) The permitivity is not a function of the electric force</li> <li>(2) The relative permitivity is same in all the directions</li> <li>(3) The permitivity is a linear function of the electric force</li> <li>(4) The permitivity is same everywhere</li> </ul> </li> <li>17) By saying that the electrostatic field is conservative, we donot mea <ul> <li>(1) It is the gradient of a scalar potential</li> <li>(2) Its circulation is identically zero</li> <li>(3) The potential difference between any two points is zero</li> <li>(4) Its curl is identically zero</li> </ul> </li> </ul>	
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<ol> <li>It is the gradient of a scalar potential</li> <li>Its circulation is identically zero</li> <li>The potential difference between any two points is zero</li> </ol>	
(3) The potential difference between any two points is zero	
(4) Its curl is identically zero	
18) —— is the unit of magnetic charge	
(1) Ampere-meter squared (2) Coulomb	4)
(3) Ampere meter squared (4) Ampere - meter	et e
Closed Imos	(4)
19) As per the concept of analogy between electric and magnetic circu	its, —
is the analogy pair	
(1) Conductivity - Permeability	
(2) Field Density - Field intensity H	
(3) Current - charge	
(4) Conductivity - permitivity	
20) Lightning may be regarded as	
(1) Transient, high current electric discharge	
(2) Transient, low current electric discharge	
(3) Transient, high current magnetic discharge	
(4) None of the above	Ð
21) ——— is the unit of electric dipole moment	
(1) Coulomb/m (2) Coulomb-m	
22) If the electrical susceptibility of a particular material is 'Y', then its	
(1) Relative permitivity is Y – 1	
(1) Indicate Designation and T	

				. 303/A
23)	Dev	vice employing the Hall	effect is used to me	asure ——
- 1	(1)	Electric flux density		
	(2)	Magnetic flux density		(1) the permitty in (2). The relative perm
	(3)			HE PER THE PER
	(4)	Magnetic flux		
24)	it as	relates the surfac	e integral of the Cur	rl of vector 'A' over the open
	surf	ace enclosed by a give	n closed path	the frist the gradient
	(1)	Divergence theorem	(2) cally xoro	Gradient theorem
	(3)	Stokes theorem	(4) ce between any	
25)	The	electric field lines are	O LOSA YELL	(4) Its curl is identicated
	(1)	Straight lines		
	(2)	Smooth curved lines		(1) Ampere-meter su
	(3)	Either straight lines or	smooth curved lines	s windamy (x)
	(4)	Closed lines		
26)	The	power factor of an Inc	luction motor at no l	oad is around
	(1)	0.2 lead	(2)	0.2 lag pubnico
	(3)	0.5 lag	Registron (4)	0.8 lag (GB/6/G (C)
27)				watts and copper loss of 1600
				im efficiency at a load of
	(1)	133%		125% manufacture (0)
	(3)	75%	subelli sintesta n (4)	66.6%
28)	ΑД	C generator will be flat	compounded if	
20)	(1)		emains constant irre	espective of the load current
	(2)	Generated voltage is i		current
	(3)			ner voltage at light load
	(4)	Terminal voltage incre		
29)	A D	C series motor develop	s a torque of 20 N-n	at 3 amps of load current. If
	the	current is increased to 6		
	(1)	10 N-m	(2)	20 N-m
	(3)	40 N-m	(4)	80 N-m

- 30) A transformer possesses a percentage resistance and a percentage reactance of 1% and 4% respectively. Its voltage regulation at power factor 0.8 lagging and 0.8 leading would be
  - (1) 2.4 % and -0.8%

(2) 3.2% and -1.6%

(3) 3.2% and -3.2%

- (4) 4.8% and -1.6%
- 31) An induction motor has a starting torque of 320 N-m when started by direct switching. If starting through an auto transformer with 50% tapping, the starting torque will be
  - (1) 0.05 N-m

(2) 80N-m

(3) 160 N-m

- (4) 640 N-m
- 32) Under short circuit conditions, the power factor of an alternator is
  - (1) Almost zero lagging
  - (2) Unity
  - (3) Almost 0.6 lagging
  - (4) Almost zero leading
- 33) I and T are the line current and torque respectively when DOL starter is used, these quantities when  $\frac{Y}{\Lambda}$  starter is used, are:
  - (1)  $\frac{1}{3}, \frac{T}{\sqrt{3}}$

(2)  $\frac{T}{3}, \frac{1}{\sqrt{3}}$ 

 $(3) \quad \sqrt[I]{\sqrt{2}}, \sqrt[T]{\sqrt{2}}$ 

- (4)  $\frac{1}{2}, \frac{T}{4}$
- 34) To reverse the phase sequence of voltage generated in the alternator, we should
  - (1) Reverse the connection of its field winding
  - (2) Interchange any two of its phase terminals
  - (3) Interchange all three of its phase terminals
  - (4) Not possible to change the phase sequence
- 35) In an alternator, the following method gives the voltage regulation more than the actual value
  - (1) Zero power factor method to other hands drive to long good and the 11 (2)
  - (2) Synchronous impedance method
  - (3) mmf method
  - (4) No load method

					JUJIA
36)	Th	e direction of rotation of a DC sh	nunt motor	is reversed by	
	(1)	Reversing armature connection	IS		
	(2)	Interchanging the armature and	field conn	ections	
	(3)	Adding resistance to the field c		. so nmow surpest	
	(4)				
	. [-1	Magnetic flux			
37)	The	e internal characteristic of the DC	generator	is the curve between	1
	(1)	Armature current and the gener	ated e.m.f.	Training to the same of the same	PROBLEM STATE
	(2)	Load current and terminal volta	ige		
	(3)	Field current and no load volta	ge		
	(4)	Armature current and IR drop			
38)	The	e damping winding in a synchron	ous motor	is generally used	
	(1)	To provide starting torque only	out sun fame	store onemialis	
	(2)	To reduce noise level			
	(3)	To reduce eddy currents			
	(4)	To prevent hunting and provide	the startin	ig torque	
39)	A 1	00v/10v, 50vA transformer is co	nverted to	100v/110v auto trai	nsformer,
		rating of the auto transformer is			bus I (El
		550 vA	(2)	500 vA	sasnir . Is
		110 vA	(4)	100vA	
40)	If th	ne excitation of the synchronous g	generator f	ails, it acts as a	
,	(1)	Synchronous motor	C MILLIAM TO	X27/2	
	(2)	Synchronous generator			
. b.	(3)	Induction motor		nounce sende admen	
751	(4)	Induction generator			
41)	A C	imulative compound dc motor ru	ns at 1500	rpm on full load. If	ite ceries
11)		l is short circuited, its speed		ipin on fun load. If	its series
		Becomes zero	(2)	Remains unchanged	1
	(3)	Increases	CARRY HISTORY	Decreases	•
	(3)	Increases	(4)	Decreases	me all
12)		induction motor with certain rati			the 1/7 <sup>th</sup>
		ne normal rated speed, the motor			
	(1)	Hunting		Crawling	
	(3)	Cogging	(4)	Jogging	
901					

	503/A
13)	n case of an Alternator, for a full pitch stator winding, the generated voltages
73)	n both coil sides are
	1) Exactly in phase
	2) In quadrature
	3) Exactly 180 degrees out of phase
	4) Approximately 180 degrees out of phase
	Approximately 100 degrees out of phase
44)	Synchronous reactance of an alternator represents
,	Armature reactance and leakage reactance
	2) Reactance operating at synchronous speed
	3) Field winding reactance
	4) A reactance connected in series with a synchronous generator
	The particular and the control of the particular particular and the pa
45)	A transformer takes a current of 0.6 A and absorbs 64 W when the primary is connected to its normal supply of 200v, 50Hz, the secondary being on open circuit. The iron loss component of current is  1) 0.2 A  (2) 0.43 A  (3) 1 A  (4) 0.32 A
46)	A 250 v DC shunt motor takes a total current of 20A. Resistance of shunt ield winding is 200 ohms and that of the armature is 0.3 ohm. Then the rmature current is
	1) 9.65 A (2) 11.25 A
	3) 18.75 A (4) 16.62 A
47)	he voltage regulation of an alternator depends on
	1) Load current only
	2) Power factor only 100 100 100 100 100 100 100 100 100 10
	Both load current and power factor
	4) No load current only
48)	The distribution of load between two alternators operating in parallel can be hanged by changing

[P.T.O.

(1) Phase sequence

(2) Field excitation of alternators
(3) Driving torques of prime movers
(4) Load currents of alternators

- 503/A 49) In case of power transformer, the no load current in terms of full load primary current is (2) 15 to 30% (1) 3 to 5% (4) 40 to 50% (3) 30 to 40% 50) The starting torque of an induction motor is maximum when (1) Rotor resistance equals rotor reactance (2) Rotor resistance is twice the rotor reactance (3) Rotor resistance is half the rotar reactance (4) Rotor resistance is 1.414 times rotor reactance 51) In an alternator for zero leading power factor, the effect of armature reaction (1) Magnetizing only (2) Demagnetizing only (3) Cross magnetizing only (4) Zero effect 52) The 'v' curve of a synchronous motor shows the relation between the following quantities
  - (1) Armature current and field current
  - (2) Power factor and field current
  - (3) Armature current and power factor
  - (4) Armature voltage and power factor
- 53) Which of the following motors is suitable for high starting torque
  - (1) Shunt motor
  - (2) Cumulative compound motor
  - (3) Series motor
  - (4) Compound motor
- 54) In a DC generator with lap connected winding, the number of brushes required is equal to
  - (1) Number of poles
  - (2) Number of pairs of poles
  - (3) Half the number of poles
  - (4) Always equal to zero

55)	The (1) (3)	field winding of an alternator DC supply Both DC and AC	(2)	AC supply Universal supply
56)	the		on the low vo	is connected in star/delta and ltage side has a ratio of 400/5.
	(1)	80:5	(2)	80: $5\sqrt{3}$
	(3)	80:5/√3	(4)	160 : 5√3
57)	For (1) (2) (3) (4)	Three phase and three-earth Three phase and two-earth far Two phase and two-earth far Two phase and one-earth far	fault relays are ault relays are alt relays are r	required equired
58)	Jaco (1)	a 20 bus power system with obian matrix is 16 x 16 19 x 19		ontrolled bus, the size of the 32 x 32 38 x 38
59)	unlo p.u, indu (1)	paded synchronous generator	is to be same, 0.05 p.u. for the rounding is (2)	faults at the terminals of an If the terminal voltage is 1.0 e alternator, then the required 0.05 p.u. 0.15 p.u
60)	Two	wes not depend on the los	apacitance val ad line insulati ing efficiency (2)	ue 'C' make up a string for a on system. If the pin to earth
61)	For is (1) (3)	Newton-Raphson method Decoupled method	(2)	Gauss-siedal method FDLF method
	(-)			

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- 62) A short circuit occurs in a transmission line (neglect line capacitance) when the voltage wave is going through zero, the maximum possible momentary short circuit current corresponds to
  - (1) Twice the maximum of symmetrical short circuit current
  - (2) The maximum of symmetrical short circuit current
  - (3) Thrice the maximum of symmetrical short circuit current
  - (4) Four times the maximum of symmetrical short circuit current
- 63) For a Power Transformer
  - (1) Positive sequence impedance is more than negative sequence and zero sequence impedances
  - (2) Positive, negative and zero sequence impedances are equal
  - (3) Positive and negative sequence impedances sum is equal to zero sequence impedance
  - (4) Positive sequence impedance is less than negative sequence and zero sequence impedances
- 64) The rate of rise of restriking voltage depends upon
  - (1) The type of circuit breaker
  - (2) The inductance of the system only
  - (3) The capacitance of the system only
  - (4) The inductance and capacitance of the system
- 65) For protection of parallel feeders fed from one end the relays required are:
  - (1) Non-directional relays at the source end and directional relays at the load end
  - (2) Non-directional relays at both the ends
  - (3) Directional relays at the source end and non-directional relays at the load end
  - (4) Directional relays at both the ends

- 66) A generator is connected to a synchronous motor. From stability point of view it is preferable to have
  - (1) Generator neutral reactance grounded and motor neutral resistance grounded
  - (2) Generator and motor neutrals resistance grounded
  - (3) Generator and motor neutrals reactance grounded
  - (4) Generator neutral resistance and motor neutral reactance grounded
- 67) In EHV Transmission lines, efficiency of Transmission can be increased by decreasing the corona loss. This is achieved by
  - (1) Increasing the distance between the line conductors
  - (2) Using bundled conductors
  - (3) Using thick conductors
  - (4) Using thin conductors
- 68) If the penality factor of a Power plant is unity, its incremental transmission loss is
  - (1) 1.0

(2) -1.0

(3) zero

- (4) 0.5
- 69) If the loading of the transmission line corresponds to the surge impedance loading then the voltage at the receiving end is
  - (1) Greater than sending end voltage
  - (2) Less than sending end voltage
  - (3) Equal to the sending end voltage
  - (4) Does not depend on the loading
- 70) A three phase transmission line conductors were arranged in horizontal spacing, with 'd' as the distance between the adjacent conductors. If these conductors are rearranged to form an equilateral triangle with sides equal to 'd', then the
  - (1) Capacitance and the inductance will decrease
  - (2) Capacitance will increase and the inductance will decrease
  - (3) Capacitance and the inductance will remain the same
  - (4) Capacitance will decrease and the inductance will increase

71)	The	e advantage of corona in a power Power loss is less	er system is	t beroduced in total	
	(2)	Increase the flow of charging of	currents		
	(3)				
	(4)	Power loss is more		nerator and motor unerator and motor u	(2). Ge
72)	Loa	d flow study is carried out for			
	(1)	Fault calculations	(2)	Stability studies	
	(3)	System planning	(4)	Load Frequency	control
73)	The	presence of earth in case of ov	erhead lines	and snows our end	
	(1)	Increases the capacitance			
	(2)	Increases the inductance			
	(3)	Decreases the capacitance and	increases t	he inductance	
	(4)	Does not affect any of the line	constants		To.
74)	Stea	ady state stability of a power sys	stem is imp	roved by	
110	(1)	Reducing fault clearing time			
	(2)	Using double circuit line instead	d of single	circuit line	
	(3)	Single pole switching			
	(4)	Decreasing generator inertia			
75)	Div	ersity factor is always			
	(1)	Equal to one	(2)	Less than one	
	(3)	Greater than one	(4)	Zero	
		The capacitation of the system			
76)	The	open loop transfer function of	a control s	system is G(s)H(s)	$=\frac{10(s+1)}{s(s-1)}$
,				A 100 DESCRIPTION OF PARTY	s(s-1)
		ch of the following is the gain m			
	(1)	+ 20 dB	(2)	-20 dB	the load
	alvu,				
		tiv, b at imperable this signs			
77)		racteristic equation of a contro			
	(1)	til remain the same		±j√2	
	(3)	±j2	(4)	±j3	
	(-)				

- 78) The system  $x(t) = A \dot{x}(t) + Bu(t)$  with  $A = \begin{bmatrix} -1 & 2 \\ 0 & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  is
  - (1) Stable and controllable
  - (2) Stable but uncontrollable
  - (3) Unstable but controllable
  - (4) Unstable and uncontrollable
- 79) A unity feedback system has a open loop transfer function  $G(s) = \frac{s+2}{(s+1)(s-1)}$ , number of encirclements of the point (-1, j, 0) in Nyquist plot and its closed loop system is
  - (1) One counter clock encirclement, stable
  - (2) One clockwise encirclement, unstable
  - (3) Two counter clockwise encirclements, unstable
  - (4) No encirclements, unstable
- 80) The open loop transfer function of a unity feedback system is given by G(s)=k/s(1+sT). By what factor the gain 'k' should be multiplied so that the damping ratio is increased from 0.3 to 0.6
  - (1) 0.5

(2) 2.0

(3) 4.0

- (4) 0.25
- 81) The phase angle at w = infinity for the transfer function,

$$G(jw) = \frac{90(1+j0.5w)}{jw(1+jw)(1+j2w)}$$
 is

(1) 90°

 $(2) -180^{\circ}$ 

(3) · 270°

- (4) -90°
- 82) The number of roots of the characteristic equation  $s^4 + 4s^3 + s^2 + 8s + 1 = 0$  lie on the right side of the s-plane
  - (1) 1

(2) 2

(3) 0

(4) 3

- 83) The system  $\dot{x}(t) = Ax(t) + Bu(t)$  with  $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ , its state transition matrix is

ALEGR

- (3)  $\begin{bmatrix} e^t & 0 \\ e^t & e^t \end{bmatrix}$  (4)  $\begin{bmatrix} e^t & e^t \\ 0 & e^t \end{bmatrix}$
- 84) The effect of phase lead compensator on rise time and band width
  - (1) Both increase
  - (2) Both decrease
  - (3) Rise time increases and band width decreases
  - (4) Rise time decreases and band width increases
- 85) The first two rows of routh tabulation of a third order system are as

$$s^3$$
 1 1

$$s^2$$
 2 2

This means there are

- (1) Two roots at  $s=\pm j$  and one root in right half s-plane
- (2) Two roots at  $s=\pm i2$  and one root in right half s-plane
- (3) Two roots at  $s=\pm j$  and one root in left half s-plane
- (4) Two roots at  $s=\pm j2$  and one root in left half s-plane
- 86) Which one of the following variables cannot be taken as a state variable
  - (1) Current passing through an inductor
  - (2) Voltage across a capacitor
  - (3) Current passing through a resistor
  - (4) Output of the integrator

87)	Which of the following comp	pensators is	used	to increase	the spee	ed of the
	response (1) Lead compensator (3) Lead lag compensator		-	Lag compe None of the		
88)	Which of the following is not (1) State model of the system (2) In transfer function mode (3) Transfer function is appli (4) In state model, initial con	n is unique el, initial con icable only fo	or line	ear time invar	riant sys	tems
89)	The Initial slope of the bode p (1) Type of the system (3) Nature of system time re		(2)	Stability of		em
90)	A rough measure of band wid (1) Phase crossover frequen (3) Resonant frequency		m is (2) (4)	Gain crosso Undamped r	The second secon	A
91)	A meter has a full scale angle of square law response. Assumin angle 45° will be (1) 0.5 A (2) 0.5	ng spring co	ntrol,			eflection
92)	Two ammeters, one will full so $100 \Omega$ , and the other with a full of $25 \Omega$ , are connected in paracan carry without any meter re(1) 1 mA (2) 10	l scale currer llel. What is	nt of the to scale	10mA and intotal current to	ternal re hese two	sistance
93)	The resistance of a circuit is power fed into the circuit. If the and current are ±1.5% and measurement of resistance will	te limiting er ±1% respec	rors i	n the measur	ement in	n power
	(1) 1% (2) 1.5	19	(3)	2.5%	(4) 3.5	[P.T.O.

	503/A
94)	Error due to change in frequency in moving iron instrument is reduced by connecting a capacitor 'c' across the series resistance 'r'. If 'L' is the inductance of the coil, the readings of the instrument will be independent of frequency only when
	(1) $c = \frac{1}{r^2}$ (2) $c = L^2 r$ (3) $c = \sqrt{L} r^2$ (4) $c = \frac{1}{r}$
95)	If two 300v full scale voltmeters $v_1$ and $v_2$ having sensitivities of $100k\Omega/v$ and $150k\Omega/v$ are connected in series to measure 500 v, then  (1) $v_1$ and $v_2$ will read 250v each  (2) $v_1$ will read 200v and $v_2$ will read 300v
84)	(3) v <sub>1</sub> will read 300v and v <sub>2</sub> will read 200v (4) v <sub>1</sub> and v <sub>2</sub> will read 0v each.
96)	In current transformers turns compensation is provided mainly to reduce the  (1) Power losses  (2) Phase angle error  (3) Ratio error  (4) Both ratio and phase angle errors
97)	PMMC type instrument normally use (1) Air-friction damping (2) Fluid-friction damping (3) Eddy current damping (4) No damping is required
98)	The inductance of a high quality factor inductor can be measured by a  (1) Schering bridge  (2) Wien's bridge  (3) Maxwell's bridge  (4) Hay's bridge
56) S	What will happen if a voltmeter is connected like an ammeter in series to the load  (1) The meter will burn out (2) The measurement will be too high (3) An inadmissably high current will flow (4) There will be almost no current in the circuit
(6)	The best material use for standard resistor is (1) Manganin (2) Aluminium (3) Nichrome (4) Platinum

									303/1	1
101) The	e functioning of	comp	ensating	bindir	ng in t	he dy	namomet	er typ	e wattmet	er
	neutralize the				1100					
(1)	Power loss in			il circi	nit		able devic			
(2)	Power loss in									
(3)	The current in						zibajno o	as two		
(4)	Voltage in the						molding (4)			
(4)	voltage in the	press	suic con c	mount						
102) As	tandard cell of	1.02 v	used wit	h a sin	nple p	oten	tiometer b	alance	es at 50 cr	n.
	en the emf of th									
	2.04 v	(2)					8 v	(4)	3.06 v	
(-)					1			100		
103) The	y - input of a C	CRO is	s 10 sin 1	00t an	d the	x-inp	out is 10 co	s 100	t. The ga	in
	both $x$ - change									
	ern on screen s								196 (6)	
	Sinusoidal sig					(2)	A straigh	nt line		
(3)	an eclipse	and -				(4)	A circle			
(3)	an conpsc					(1)				
104) Sch	ering bridge is	used	to				in circula e			
(1)	Determine dis			ofac	anaci	tor				
	Determine inc	_		orac	apaci					
	Measure low					LIP			dA (1)	
(4)	Measure mutu									
(4)	Wieasure mutt	iai iiiu	uctance						) Address	
105) Ma	vina iran instru	monto	can be u	sad or	2					
	ving iron instru A.C. only	ments	can be u	sed of	.1	(2)	D.C. onl	.,	ne 12-Pe	
		100						10000	v cupply	
(3)	Both A.C. and	ID.C				(4)	High free	quene	y supply	
100 4	ideal on ann al	DO:1	(A)							
	ideal op-amp sl			(2)	T4		(1)	T. C.	italy fort	
(1)	Very slow	(2)	Slow	(3)	rast		(4)	пппп	illery fast	
I OFFIT O	110 (t) 110 (t)		H. (A)	0.0	,000	11100	101	1101	01,(1)	_1
	's complement	repres	entation t	ne nur	nber 1	11100	o 101 repre	sents	me decima	41
num	iber	(2)	MOTOR -	(2)	200		(4)	vbs or		
(1)	+ 37	(2)	-31	(3)	+ 27	CORV	(4)	-27	the com	
100 00	sepundes care	PAIL.	figur iron	n the	2.1	ZEID	nplex circ	מופ פסו	DC (1)	
	number of con	_						W IW ZI	IDC 1S	
(1)	2	(2)	3	(3)	1		(4)	8		
OI Della	pri et a nutormy	a gude	acrest-late	ada be	Major		aniel to one		The pra	
	number of unu							STORE	toph ogn	
(1)	2 190000 0000	(2)	4	(3)	8		(4)	12		1
				21					IP.T.C	)

1000	Thich of the following is not a	characteristi	c of a	a flip-flop?
(1)		. Dusamolkane		madent at he many of St.
(2)	,	ittoria il quan		clade nitrael roles (C)
(3)		re compleme	ent of	each other
(4)	) It has one input terminal			(4) Voltage in the press
111) Ad	ddressing capacity of 8085 m	icroprocesso	or is	
(1)	) 8 kB (2) 64 kB	(3) 128	kB	(4) 16 kB
	192. E. v(4) year 250v 89da (8			(C) 3 04 50 C (D)
112) In	a flash $\frac{A}{D}$ converter, the pr	iority encode	er is u	ised to
(1)	AND THE RESERVE OF THE PARTY OF			
(3)	) Select the lowest value input	ut (4)	Sel	ect the last input lod 161
113) Or	n the drain characteristic curve	of a JFET fo	r VG	GS = 0, the pinch-off voltage
is				अध्याविक सार्व (स्ट्री)
(1)	) Below the ohmic area			
(2)	Between the ohmic area an	d the constan	nt cur	rrent area
(3)	Between the constant curre	ent area and t	he br	reak down region
(4)	Above the breakdown region	on		
114) Ad	ldress bus length of 8086 mic	roprocessor	ie	
	8 (2) 16	_	20	(4) 40
	(2) 10	ne used on	BB3	Movement none automatic
115) A	4-bit R/2R ladder digital-to-ar	nalog convert	er us	es the D.A (t)
(1)	Two resistor values		(2)	Three resistor values
(3)	Five resistor values		(4)	Four resistor values
116) Bir	nary subtraction of a decimal 15	from 43 will	utiliz	e which two's complement?
(1)				001 (4) 011100
to domina	er 11100101 represents the de	tion the numb	Elings	This I's complement repres
117) The	e main advantage of the succ	essive - app	roxi	mation A/D converter over
the	counter - ramp A/D converte	r is its		
(1)	More complex circuitry		(2)	Less complex circuitry
(3)	Longer conversion time		(4)	Shorter conversion time
118) The	e practical use of binary-weigh	nted digital-to	o-ana	alog converters is limited to
	R/2R ladder D/A converters			4-bit D/A converters
(3)		(8)	(4)	Op-amp comparators
( )			( )	

303/A
119) A single - phase full converter with R-L load is triggered at 30°. Then each device conducts for
(1) $180^{\circ}$ (2) $150^{\circ}$ (3) $30^{\circ}$ (4) $120^{\circ}$
<ul><li>120) In which of the following both frequency and voltage can be controlled?</li><li>(1) Inverter and a.c. voltage controller</li></ul>
(2) Cyclo-converter and a.c. voltage controller
(3) Inverter and cycloconverter
(4) Inverter, cyclo converter and a.c. voltage controller
121) A circulating current mode dual converter has the following properties.
(1) size is more and efficiency is high
(2) size is more and efficiency is low
(3) size is less and efficiency is high
(4) size is less and efficiency is low
122) The firing angle of a 1-phase a.c. voltage controller is zero. Assuming resistive load, the input current wave shape is
(1) a.c. square wave
(2) constant d.c. wave
(3) d.c. sine wave
(4) a.c. sine wave that a more than the same and the same
123) The output frequency of a 1-phase cycloconverter is found to be 12 Hz then the input frequency is
(1) 50 Hz (2) 60 Hz (3) 40 Hz (4) 30 Hz
124) An IGBT gas
(1) high input impedance and low conduction losses
(2) low input impedance and low conduction losses
(3) high input impedance and high conduction losses
(4) low input impedance and high conduction losses
125) Choose a correct statement from the following:
(1) If THD increases, input p.f. increases
(2) If THD increases, input p.f. decreases
(3) If displacement factor increases, input p.f. decreases
(4) If displacement factor increases or decreases, input p.f. remain constant
(3) (C) and (D) are true

126) If the	he duty cycle of a d.	c. chopper is "	a', the	en rij	pple factor is given by		
(1)	$\sqrt{(1-\alpha)/\alpha}$ (2)	$\sqrt{\alpha/(1-\alpha)}$	(3)	α	(4) 1/α		
127) Wh	ich of the following de	evices has the le	owest '	Max	cimum switching frequency'		
		IGBT					
120) Th	seme concin, of the	day seems.	STH		parano-ology (C)		
(1)	e converters which op half-wave and full-	the state of the s	-	adra	ints are		
(2)	1711 U LI (LO 5)		18		The Inverter with		
	full wave and semi						
	dual converter and		2				
(1)	deci he lowest valu	The House are	iger en				
	ced communication i	s necessary in	Holen		cuits.mersale(1)		
	GTO Based	urve of a life		(2) MOSFET Based			
(3)	Converter grade SC	CR		(4)	Inverter grade SCR		
130) In a calle		ctions are forw	ard bi	ased	then the operating mode is		
(1)	cut-off mode			(2)	forward active mode		
(3)	saturation mode			~ .	reverse active mode		
					(3) - d.c. sine waw		
					y a voltage source inverter		
	frequency of rotor c	urrent at fifth l	narmoi				
	equal to 50 Hz				less than 250 Hz		
(3)	more than 250 Hz			(4)	exactly equal to 250 Hz		
132) At n	no-load the ratio of	energy loss	lue to	dyn	amic braking and counter		
	ent braking of a sepa						
(1)							
	ioli (osses	3:1 wol b	the Son	BLS	ich man wol (2)		
133) The	value of slip of a 3-ph	ase induction	motor a	at nth	harmonic is approximately		
	slip/n (2)				slip (4) 1		
	1 41	induction mot			is operated at above rated		
(A)	voltage decreases			(B)	torque decreases		
	power increases			(D)	slip speed increases		
	(B) and (C) are true				(A) and (C) are true		
(3)	(C) and (D) are true			(4)	(B) and (D) are true		

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135) Speed of 3-phase induction motor	r is controlle	ed by 3-p	hase a.c. v	oltage
controller. If firing angle is decrease			mean at 16	7 34 1
(1) speed increases & peak torque	*			
(2) speed decreases & peak torque				
(3) speed increases & peak torque				
(4) speed decreases & peak torque			agai (ia	
136) A chopper fed dc motor runs with dis	scontinuous a	rmature cu	irrent at par	ticular
duty ratio. The current can be made	continuous l	by .		
(1) increasing duty ratio	(2)	increasi	ng frequenc	у
(3) decreasing duty ratio	(4)	decreas	ing frequen	су
137) In constant power operation of an a	.c. drive			
(1) voltage is constant and frequen	cy is variable	Tangue in		
(2) voltage is variable and frequence	cy is constant	of specific	nno ailTic	
(3) both voltage & frequency are c	onstant			
(4) both voltage and frequency are	variable			
138) In 4 quadrant of a drive operation, q	uadrants II a	nd III are		
(1) forward monitoring & reverse n				
(2) forward braking and reverse gen	nerating			
(3) forward braking and reverse mo	onitoring	1011 TURUS		
(4) forward monitoring and reverse	generating	ionom red	Tale (E)	
139) The slip of a 3-phase induction mo	otor is 0.05.	At the in	stant of dy	namic
braking, the slip is				
(1) 0.95 (2) -0.05	(3) 1.95	5 (4)	0.05	
140) Speed of a 3-phase a.c. motor is cont				
At a very low speeds, the voltage is			Therefal	
(1) proportional to frequency	Thomas Int.		moral and	
(2) less than the value of voltage in				
(3) more than the value of voltage in	1(1)			
(4) equal to the rated voltage				
141) The unit of luminous flux is		nation (2)		
(1) Radians (2) Lumens	(3) Lux	(4)	Candela	
· · · · · · · · · · · · · · · · · · ·		(		ν.

142	(1) (2)	heating e low melt high tem	ting p							503/A
	(3) (4)		d the	required					ed	
143	(1)	softening 500°C		300°C			opper el 00°C	ectrode	e is (4)	150°C
144	(1) (2) (3) (4)	power su power su power su power su power su	ipply ipply ipply	is on to a is cut off on & tra	accelerate and train in is runr	e train is allowing at o	wed to r	speed		momentum
145	(1) (2) (3)	unit of sp Watt hou Watt hou Watt hou Watt hou	rs/tor rs/kil rs/kil	nne-kilom ometer ometer p	eter	Total Control		tric trac	etion sy	ystem
146	) Whic	ch of the	moto	is best s	uited for	traction	n			
		DC shun				(2)	DC se	ries mo	otor	
	(3)	Stepper 1	notoi	5		(4)	Shade	d pole	motor	
147	(1)	ection fac Reflected MSCP/M	llight		light	(2) (4)		nt light/ CP/MS0		ted light
148	The l	neat produ I²R	(2)	in the res Eddy cu	istance w rrents (3	velding ) VI	at the jo	oints is j	propor sterisis	tional to loss
149)	The to	otal lume mp is 100	ns rea	aching the	e working on factor	g plane	is 60 an	d total	lumens	s given out
	(1)	1.66667	(2)	160	(3	) 40	(4	0.6		
150)	lumer	ns. The lu	mens	per watt	is				total flu	ax of 4400
	(1)	+0	(2)	0.05	(3	) 4620	(4	) 20		

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